Pixel Synchronization: Solving Old Graphics Problems with New Data Structures

Marco Salvi

Advanced Rendering Technology Intel - San Francisco



My Background

- 7 yrs as Gfx Engineer on PC and two generations of Sony & MS consoles
 - High performance 3D engines
 - Exponential shadow maps & deferred shadowing
 - HDR rendering & MSAA with LogLuv buffers (aka nao32 ③)



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• Intel R&D – Tech Lead in Advanced Rendering Technology team (2008 - present)

- Shadow map filtering & partitioning schemes
- OIT, anti-aliasing, volumetric shadows
- Stochastic rasterization & shader caches
- New graphics architectures





Talk Outline

- Introduction and Problem Statement
- Pixel Synchronization
- Applications & Demos
- Performance Tips & Tricks
- Summary
- Q&A



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 - ...but very fast and power efficient



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 - Can only order color, z & stencil operations from a fixed menu..
 - ...but very fast and power efficient
- Add new programmable back-end?
 - Let it coexist side by side with fixed function HW to leverage respective strengths



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 - Fragments mapping to same pixel can cause data races
 - Fragments can be shaded out-of-order, can't support order-dependent algorithms





shade fragment from 1st triangle

r/m/w







Advances in Real-Time Rendering in Games course





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 - Avoid data races
 - Guarantee primitive submission order for R/M/W memory operations





Pixel Synchronization

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 - Enable ordering for R/W memory accesses (i.e. same order as alpha-blending)
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 - Little to no performance impact in most cases
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- Very good performance
 - Little to no performance impact in most cases
 - R/W memory accesses are backed by the full SoC cache hierarchy
- More powerful than reading back the frame buffer from a pixel shader
 - Build and access data structures of arbitrary size/type/dimensionality (including voxels 😊)
 - Decoupled from MSAA, can work with per-pixel and/or per-sample data structures



























10



IntelExt_BeginPixelOrdering();

```
uint rgbe = gRGBEBuffer[xy];
float3 dstRGB = RGBE_to_RGB(rgbe);
```

```
dstRGB = alpha * rgb + (1 - alpha) * dstRGB;
```

```
gRGBEBuffer[xy] = RGB_to_RGBE(dstRGB);
```



Advances in Real-Time Rendering in Games course

}

void PS_RGBE_Blend (...)
{

IntelExt_Init();

}

float3 rgb = ...
float alpha = ...

always run concurrently with other fragments

might wait for the retirement of other fragments that map to the same pixel

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A Few Programmable Blending Applications

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- Blending for deferred shaders
 - e.g. Apply decals by blending normals and other material attributes



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 - Render N-layers of the image in a single pass
- Countless applications:
 - Depth-peeling
 - Constructive solid geometry
 - Depth-of-field & motion blur
 - Volume rendering
 - •
 - <insert your idea here ☺>



Compute fragment color, z, etc..

void PSMain(...)
{
 IntelExt_Init();

Fragment frag = {...};



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IntelExt_Init();
Fragment frag = {...};
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IntelExt_BeginPixelOrdering();

Enable pixel synchronization







```
Compute fragment
                      void PSMain(...)
    color, z, etc..
                      {
                          IntelExt_Init();
                          Fragment frag = {...};
                                                                     Enable pixel synchronization
Read N fragments
                          IntelExt BeginPixelOrdering();
 from K-buffer
                          Fragment fragArray[N] = gBuffer[xy];
                          for (int i = 0; i < N; i++) {
                             if (frag.Z < fragArray[i].Z) {</pre>
                                                                           Bubble sort (1 pass)
                                   Fragment temp = frag;
                                  frag = fragArray[i];
                                  fragArray[i] = temp;
```





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 - Requires unbounded memory (per-pixel lists)
 - Not so great performance due to global atomics, fragments sorting, etc.
- Pixel Synchronization enables new methods
 - Single geometry pass and fixed memory requirements
 - Stable and predictable performance
 - Scalable: easily trade-off image quality for performance/memory





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 - Use full screen pass to resolve data and blend resulting color over opaque color buffer



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- Step 3: Use more layers to trade-off image quality for perf/memory



Deep Shadow Maps

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 - Lossy compression of the visibility data



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- Adaptive Volumetric Shadow Maps*
 - Like DSMs but designed for real-time rendering
 - Lossy compression of the visibility data
- Pixel synchronization enables first fixed memory implementation of AVSM
 - Demo 😊



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- Use pixel synchronization to build 3D data structures at voxelization time
 - Problem: fragment dependencies cannot be tracked over multiple 2D planes
- Easy fix: voxelize onto one 2D plane at time
 - 3 draw calls per mesh, one per 2D plane (i.e. reject triangles that map to other planes)
 - Number of generated voxels doesn't change & more flexible than using global atomics



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 - Store N fragment per pixel (z, $\partial z/\partial x$, $\partial z/\partial y$, color, coverage)
 - Merge fragments (lossy)
- Analytic methods
 - Render scene using conservative rasterization
 - Build per-pixel spatial subdivision structure using primitive edges (per-pixel BSP? ☺)
 - Compute fragment weights from fraction of pixel area covered by leaf cells and resolve





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bool clear = gClearMask[xy];



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bool clear = gClearMask[xy];

```
if (clear) {
    gClearMask[xy] = false;
    myLargeStruct = ...
```

Mark pixel as "used" and initialize large struct

















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- Prefer inserting the synchronization point in the second half of the shader
 - Increase likelihood of concurrently shading fragments that map to the same pixel
 - Corollary: use HW z-test when possible for better performance (Hi-Z is fast!)



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 - 3. Use the data & enjoy your results (sip tea or coffee 🙂)



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 - 2. Draw geometry to build your data in a streaming fashion
 - 3. Use the data & enjoy your results (sip tea or coffee ③)
- DX11+ extension available now (download demos), OpenGL extension in development.





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• Source code

- Programmable Blending:
- Order-Independent Transparency:
- Adaptive Volumetric Shadow Maps:

bit.ly/pixelsync_pb bit.ly/pixelsync_oit bit.ly/pixelsync_avsm

- Contacts
 - e-mail: marco.salvi@intel.com
 - twitter: @marcosalvi

