

Multi-Scale Global Illumination in Quantum Break

Ari Silvennoinen

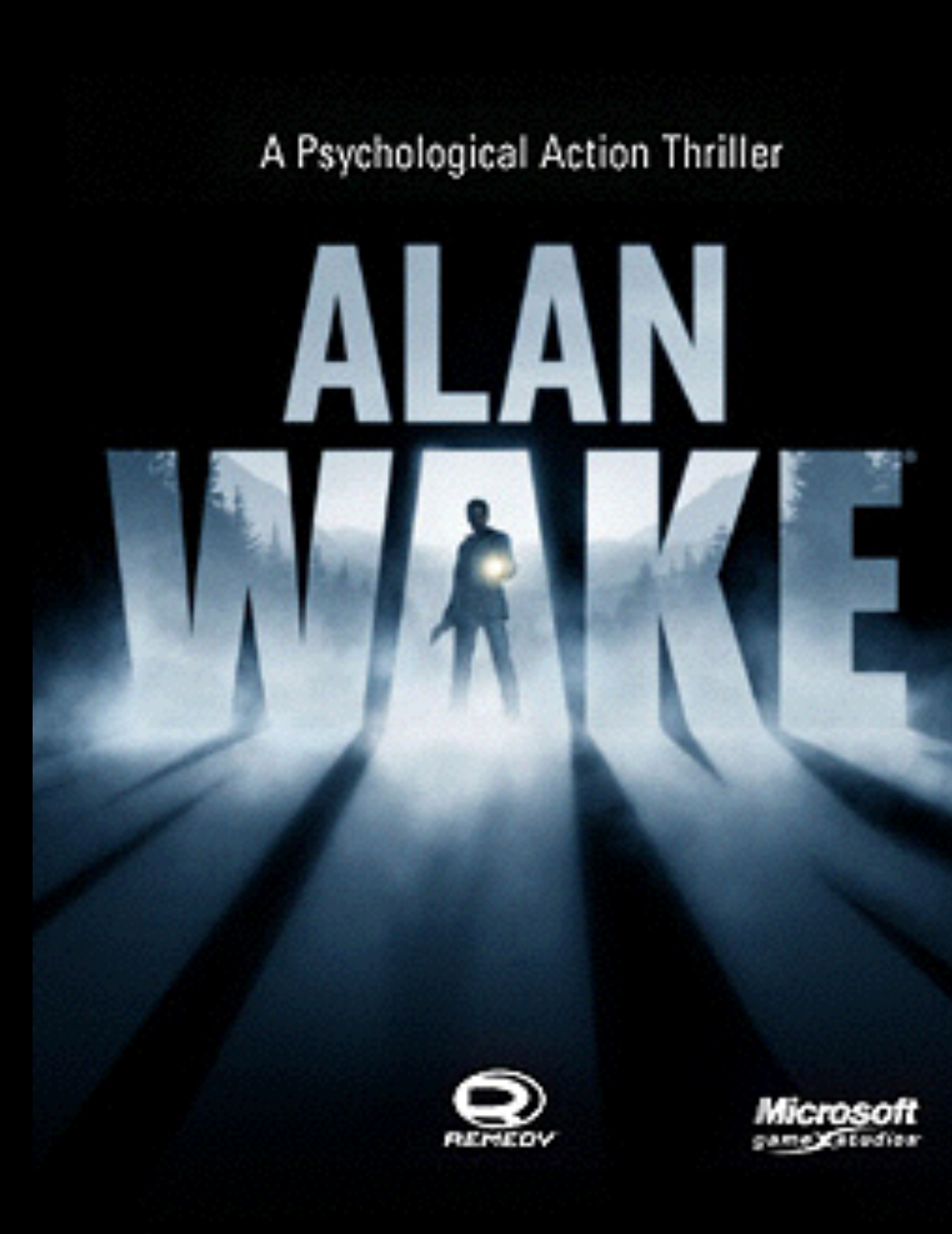
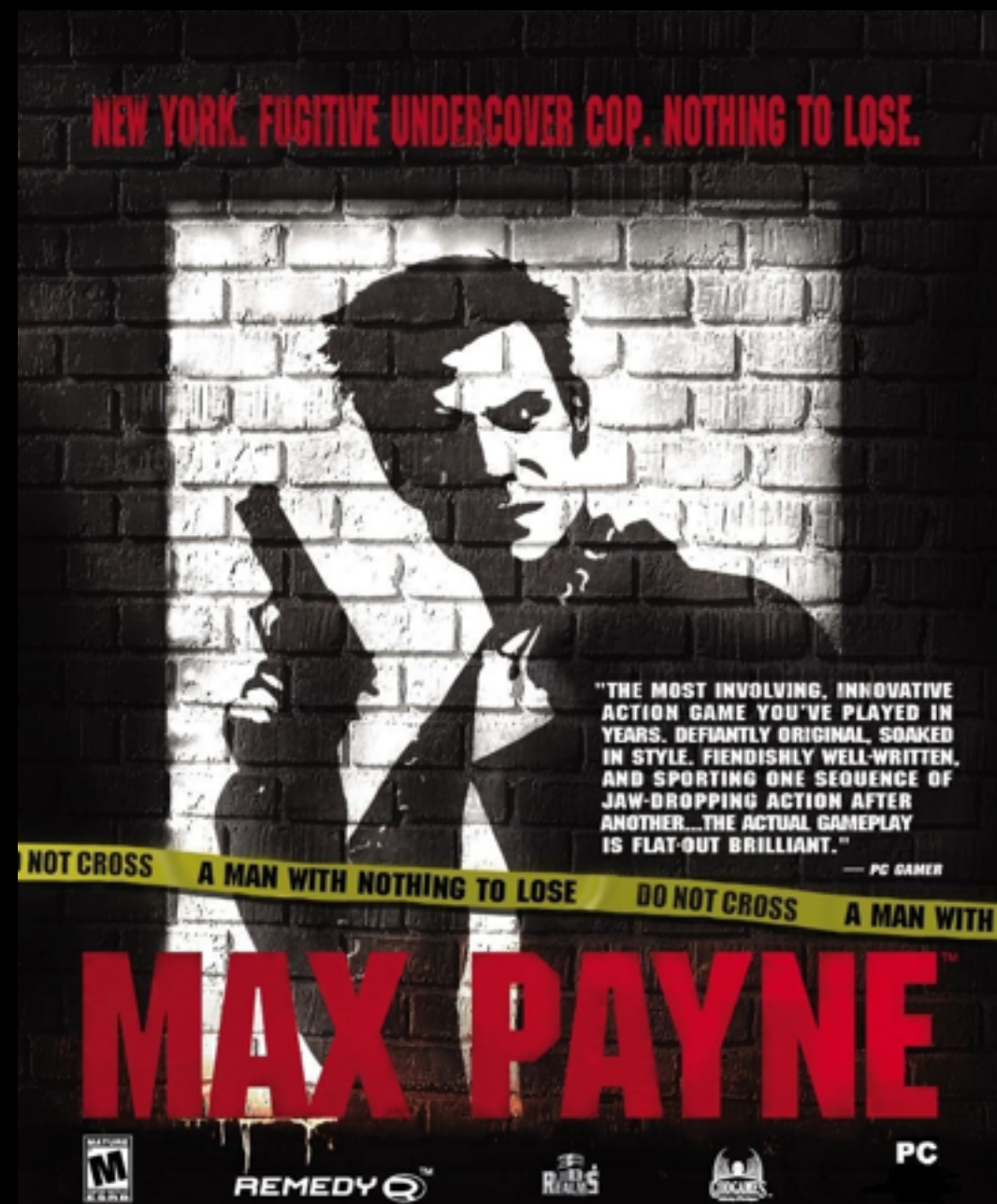
Remedy Entertainment
Aalto University

Ville Timonen

Remedy Entertainment



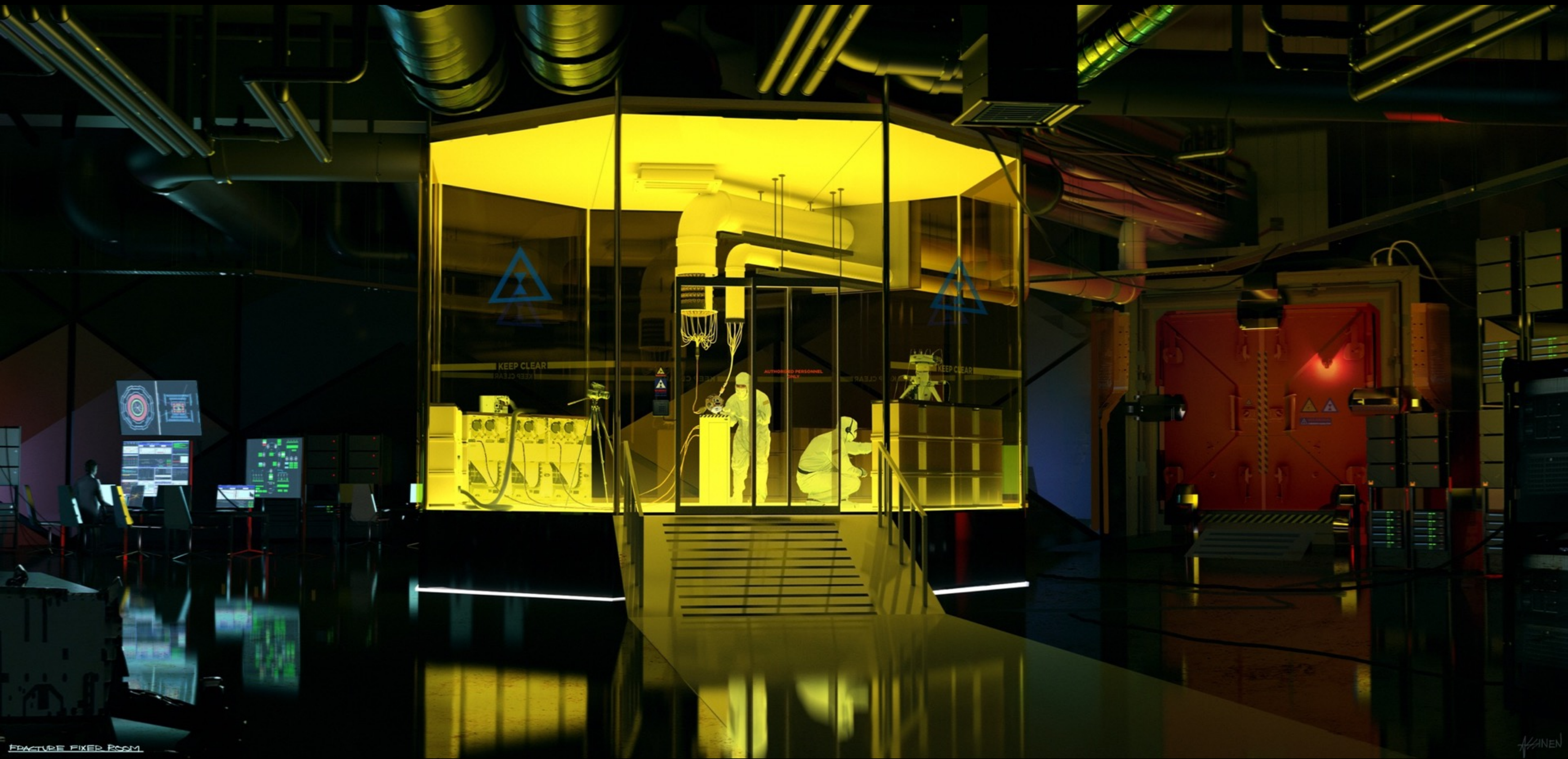
Remedy Entertainment



n^orthlight[®]

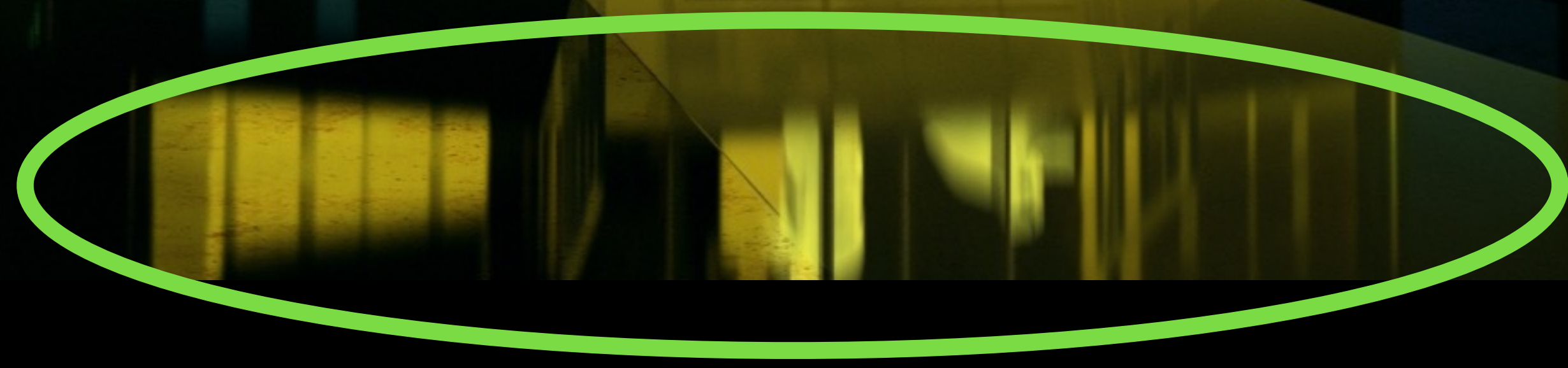
Custom in-house engine

Physically based light pre-pass renderer



FRACTURE FIXED ROOM

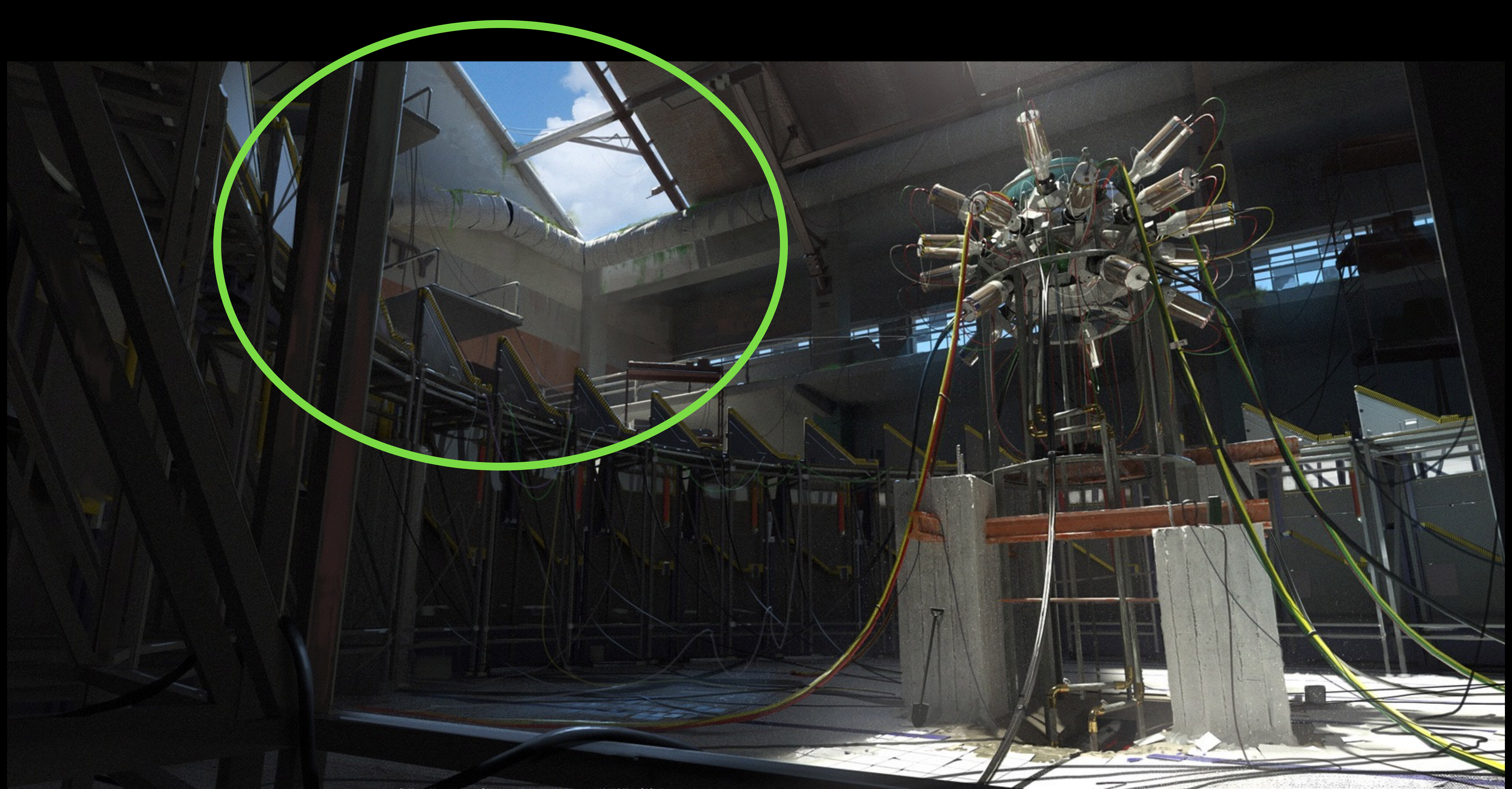
AINEN



FRACTURE FIXED ROOM

AINEN









Design Goals and Constraints

Consistency

A dark, atmospheric rendering of an industrial interior, possibly a warehouse or factory. The scene is dimly lit, with light filtering through windows and a single hanging lamp. The architecture features a complex metal structure with beams and supports. Various objects are scattered on the floor, including boxes, a pallet, and a yellow forklift in the background. The overall mood is gritty and industrial.

Design Goals and Constraints

Consistency

Semi-dynamic environments and lighting

Design Goals and Constraints

Consistency

Semi-dynamic environments and lighting

Fully automatic

Screen-Space Lighting



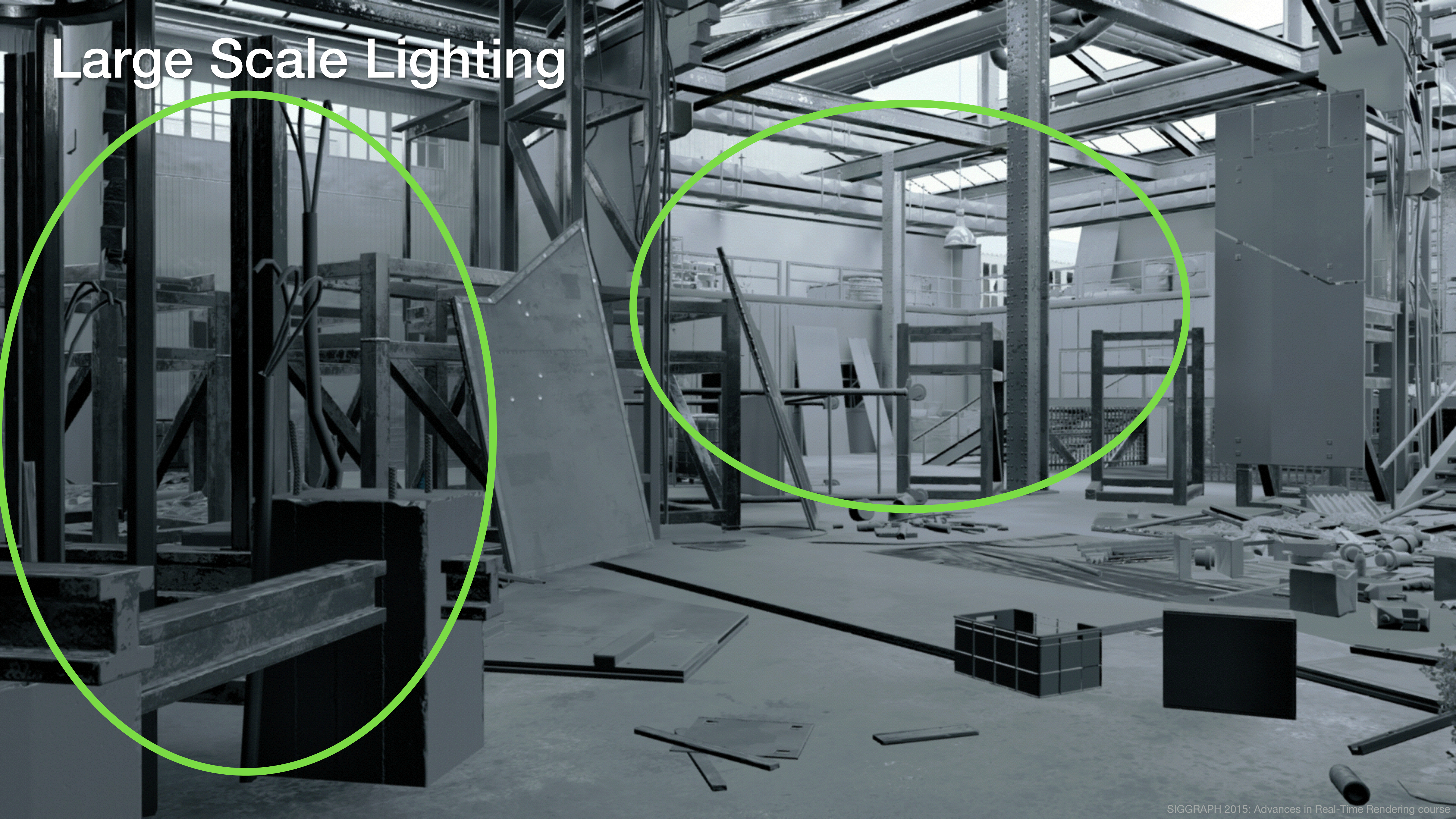
Screen-Space Lighting



Screen-Space Lighting



Large Scale Lighting



Multi-Scale Lighting



Talk Outline



Part I: Large-scale lighting

Part II: Screen-space lighting

Talk Outline



Part I: Large-scale lighting

Part II: Screen-space lighting

Possible Solutions for Global Illumination

Dynamic Approaches

- Virtual Point Lights (VPLs) [Keller97]
- Light Propagation Volumes [Kaplaynan10]
- Voxel Cone Tracing [Crassin11]
- Distance Field Tracing [Wright15]

Possible Solutions for Global Illumination

~~Dynamic Approaches~~

- ~~— Virtual Point Lights (VPLs) [Keller97]~~
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- ~~— Voxel Cone Tracing [Crassin11]~~
- ~~— Distance Field Tracing [Wright15]~~

Cost was too high for the **quality** we wanted

Possible Solutions for Global Illumination

Mesh-based Precomputation

- Precomputed Radiance Transfer (PRT) [Sloan02]
- Spherical Harmonic Light Maps

Meshless Precomputation

- Irradiance Volumes [Greger98]

Possible Solutions for Global Illumination

Mesh-based Precomputation

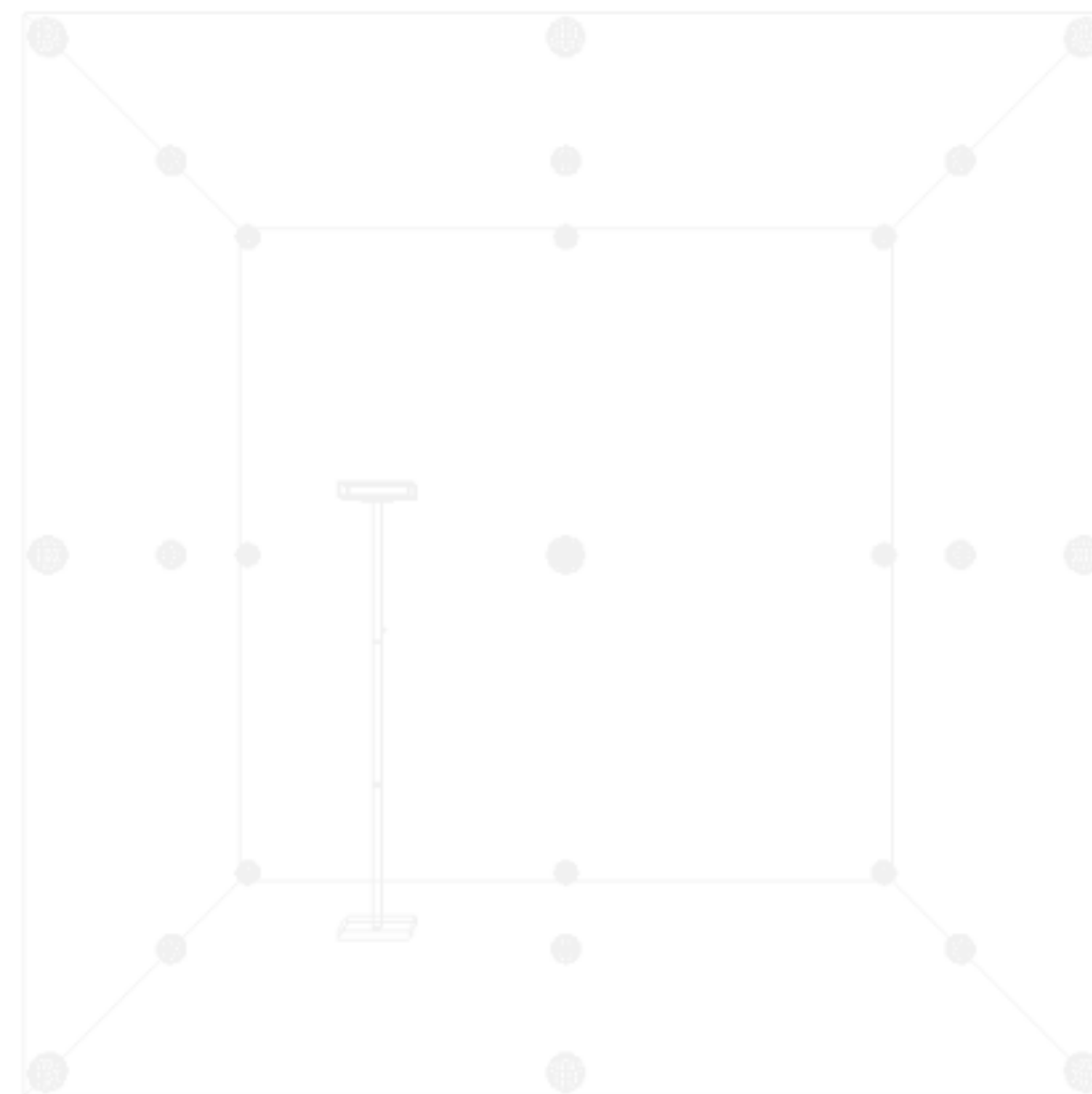
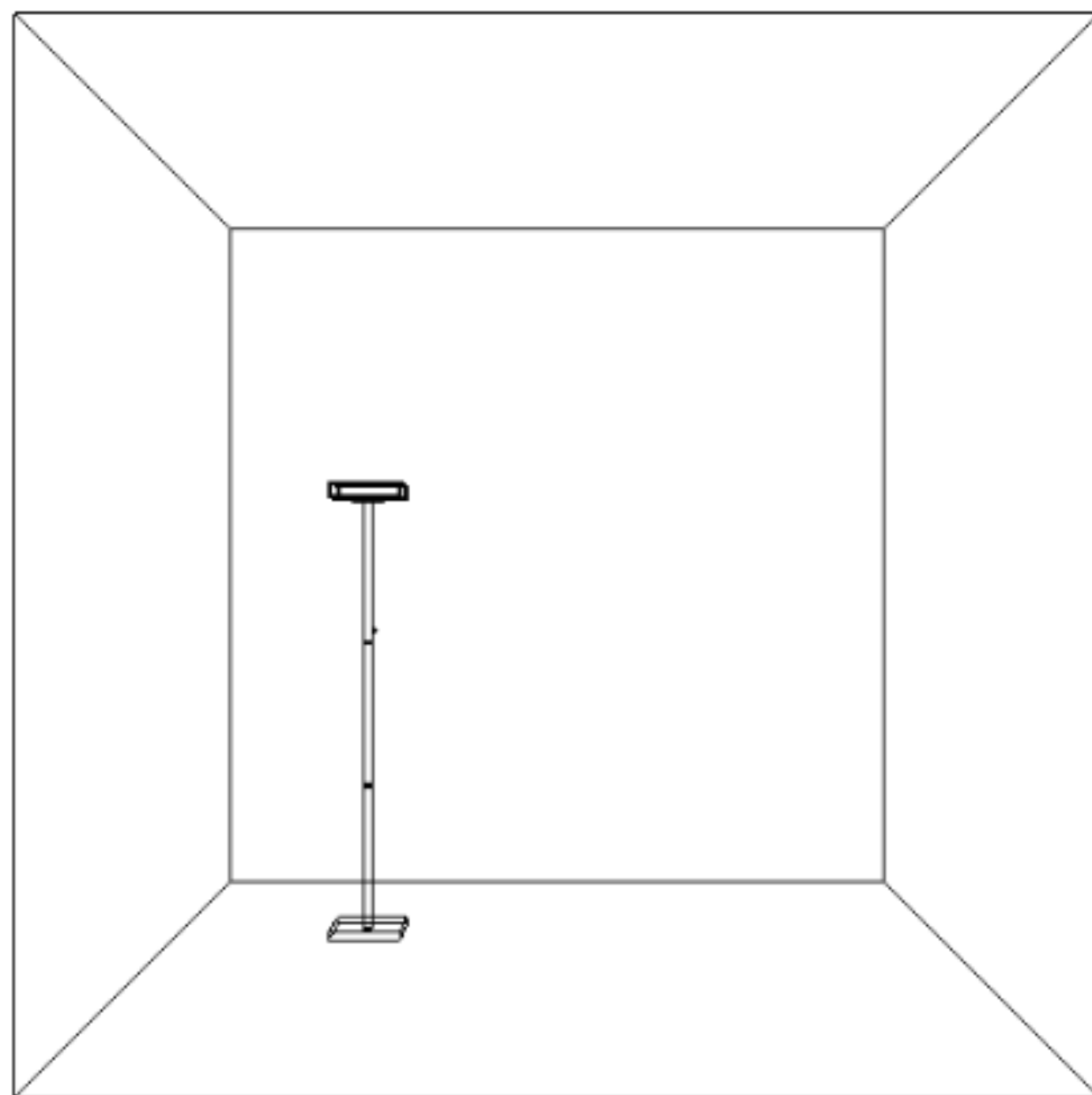
- Precomputed Radiance Transfer (PRT) [Sloan02] X
- Spherical Harmonic Light Maps X

Meshless Precomputation

- Irradiance Volumes [Greger98] ✓

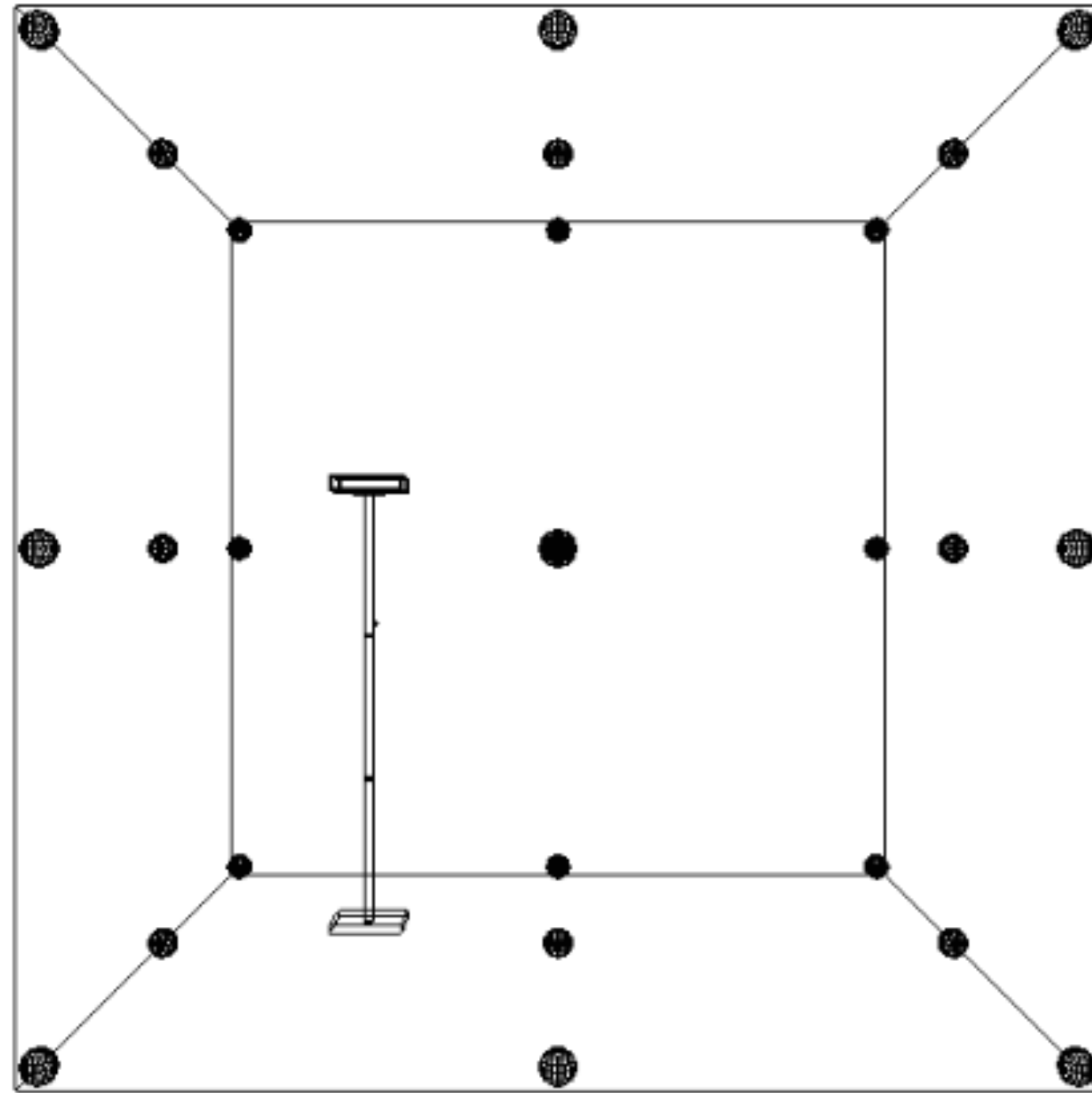
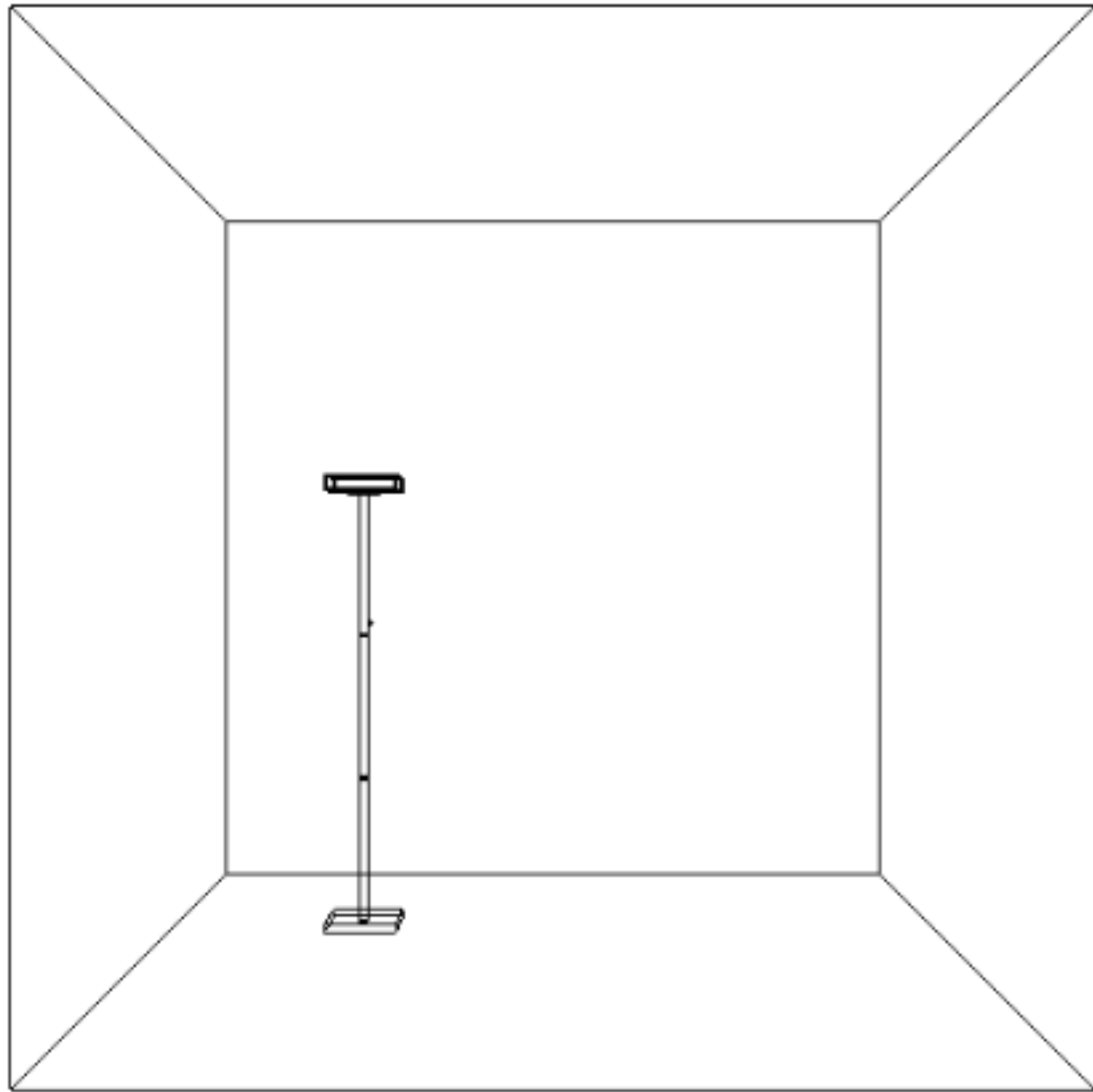


Irradiance Volumes



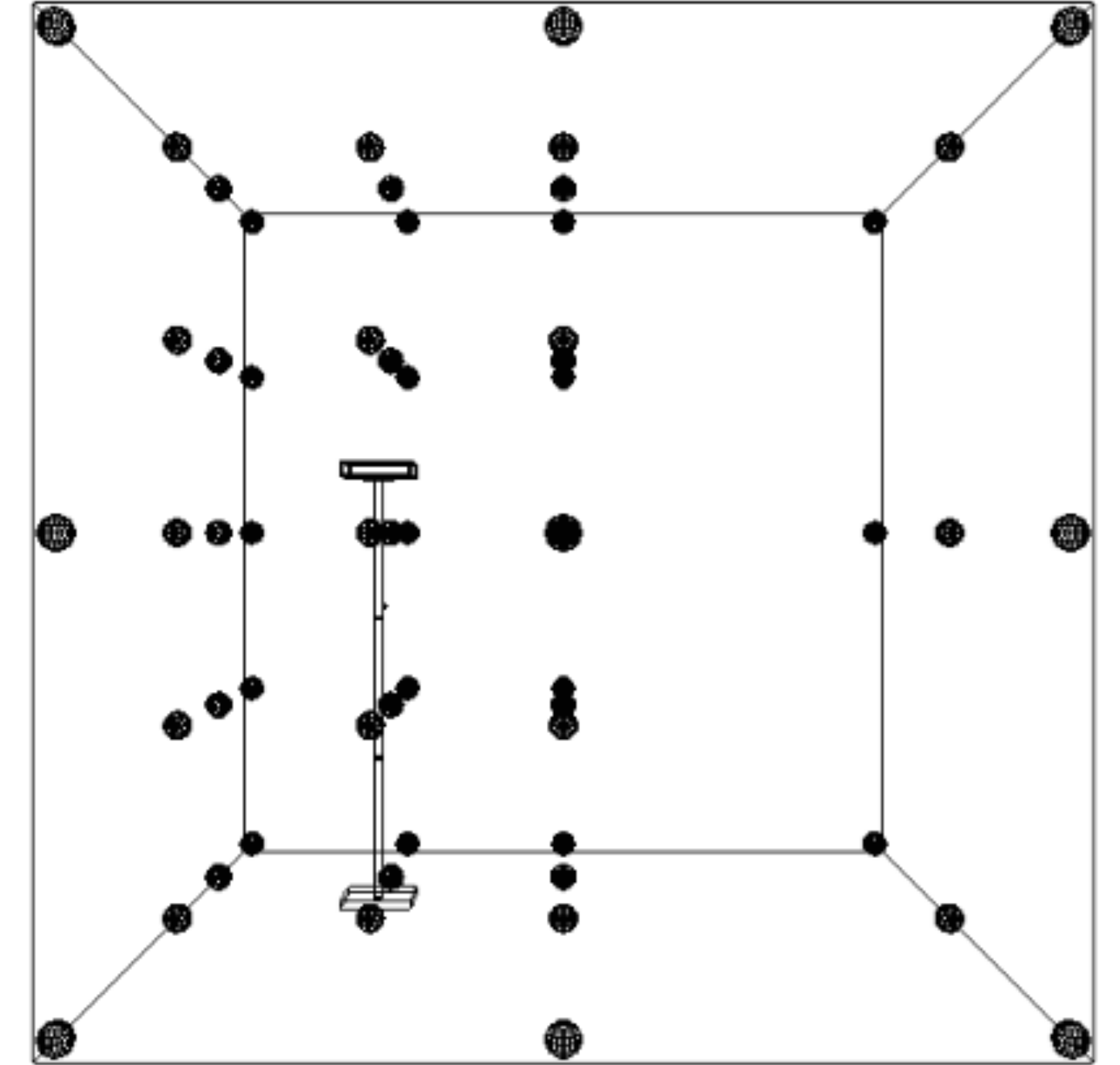
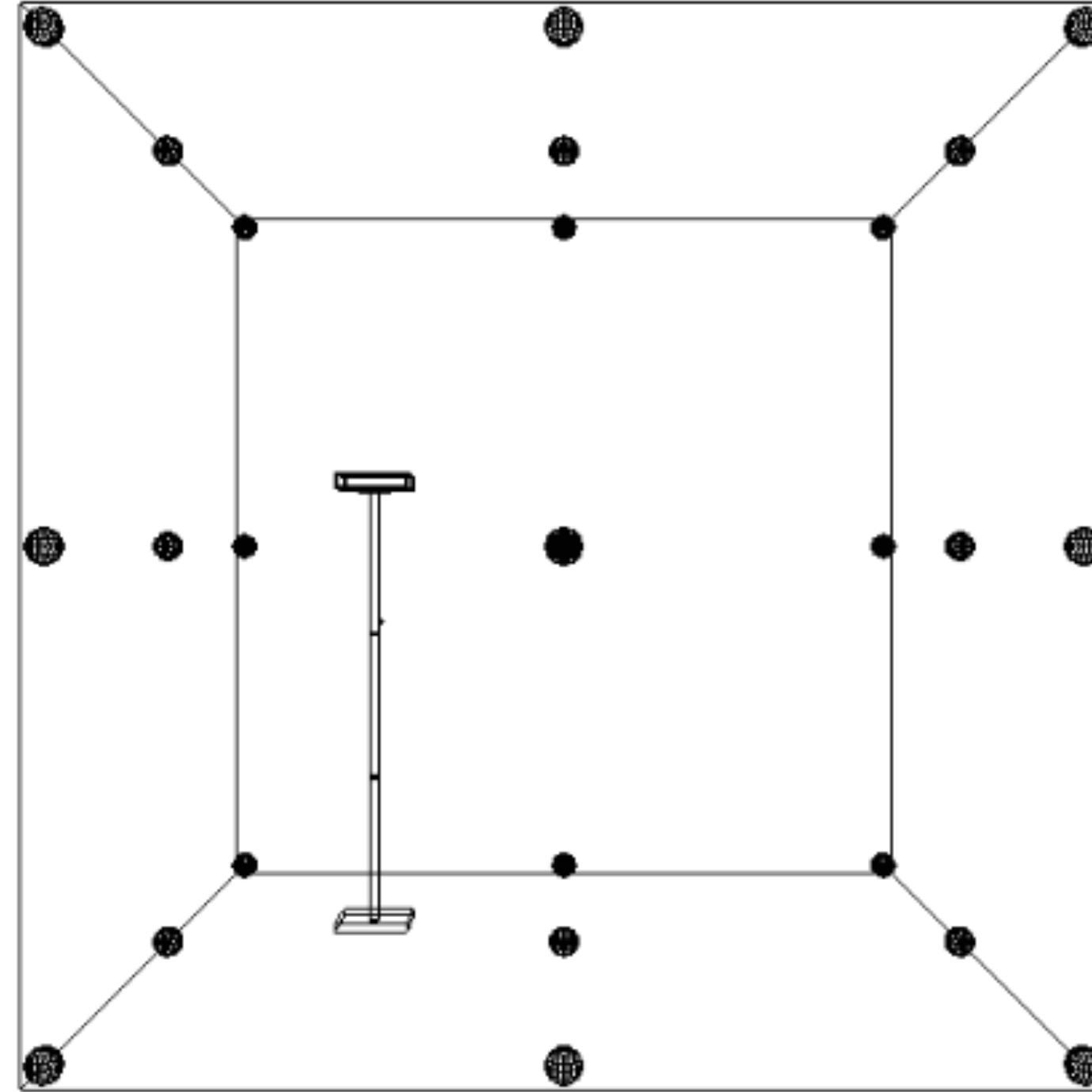
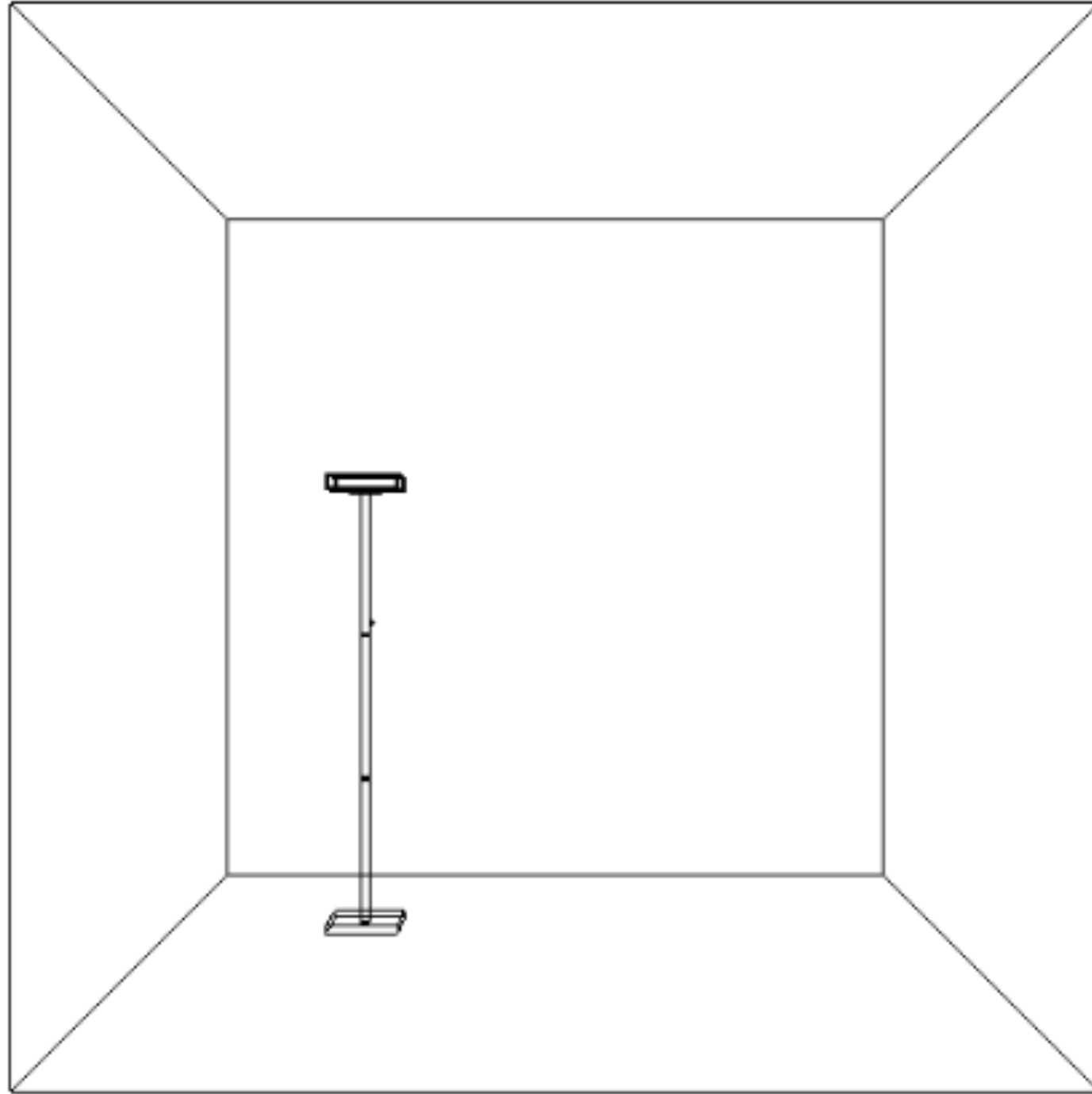
[Greger 1998]

Irradiance Volumes



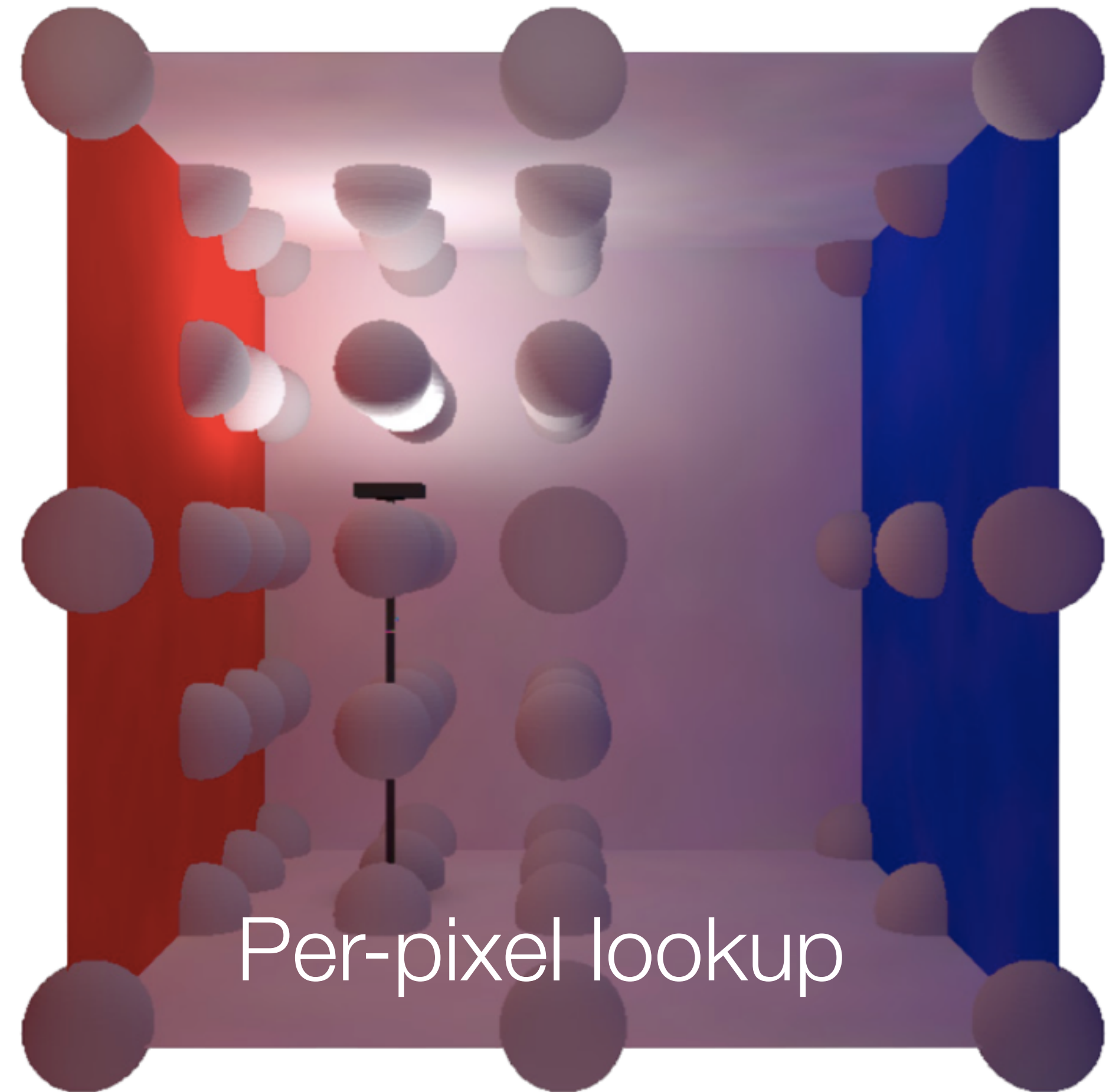
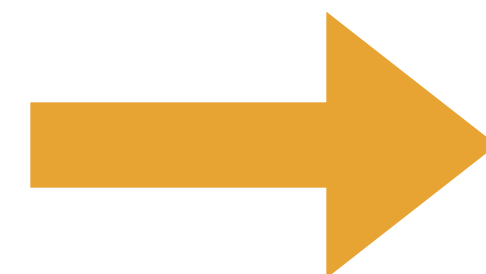
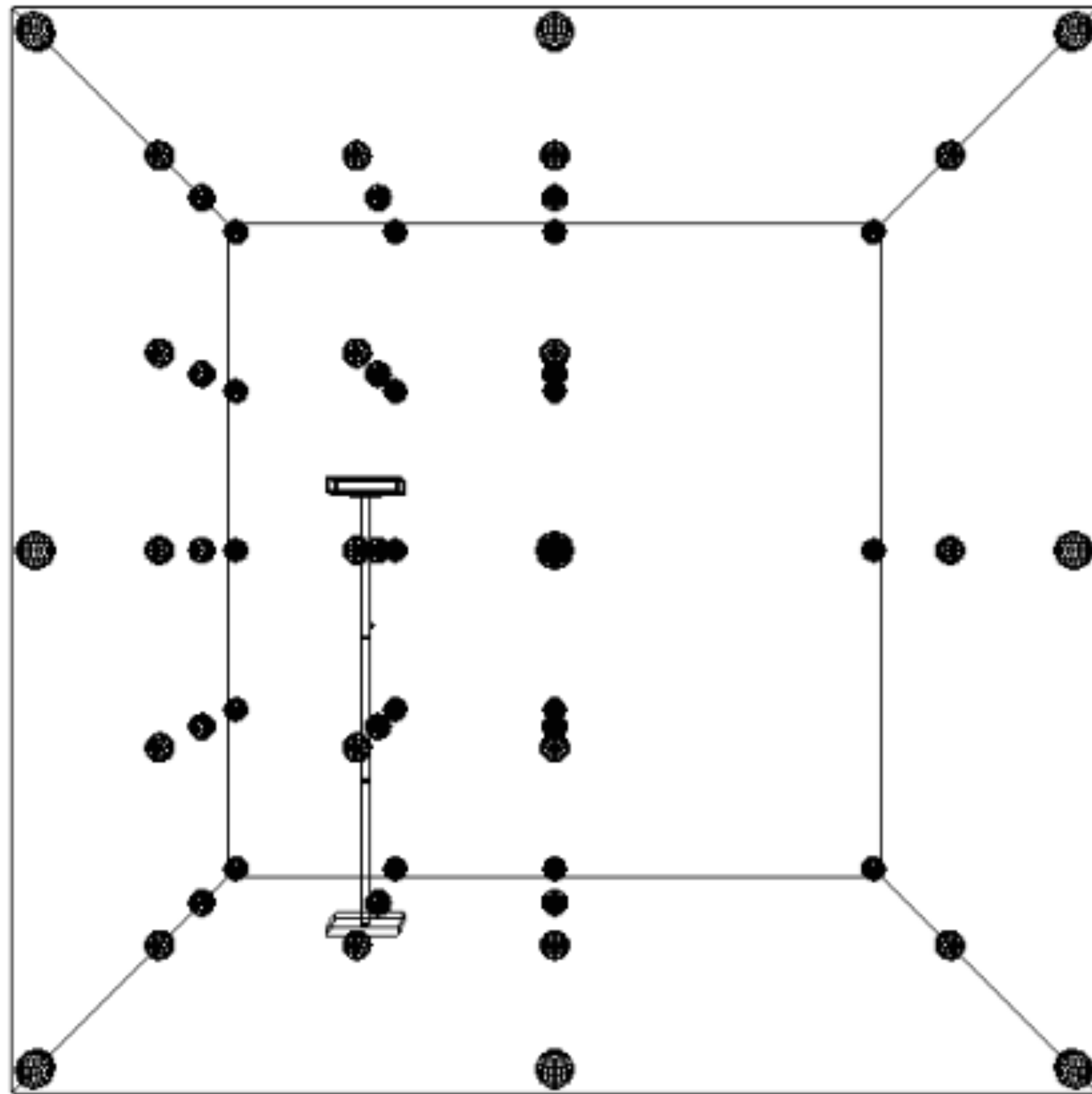
[Greger 1998]

Irradiance Volumes



[Greger 1998]

Irradiance Volumes



[Greger 1998]

Global Illumination Volumes

Augment irradiance volumes with global illumination data



Lighting Only



Local Irradiance



Indirect Sun Light Transport



Sky Light Transport



Lighting Only



Local Irradiance



Indirect Sun Light Transport



Sky Light Transport



Lighting Only



Local Irradiance



Indirect Sun Light Transport



Sky Light Transport



Lighting Only



Local Irradiance



Indirect Sun Light Transport



Sky Light Transport

Global Illumination Volumes

No UVs ✓

Works for LOD models ✓

Volumetric lighting ✓

Consistent with dynamic objects ✓



Global Illumination Volumes

No UVs ✓

Works for LOD models ✓

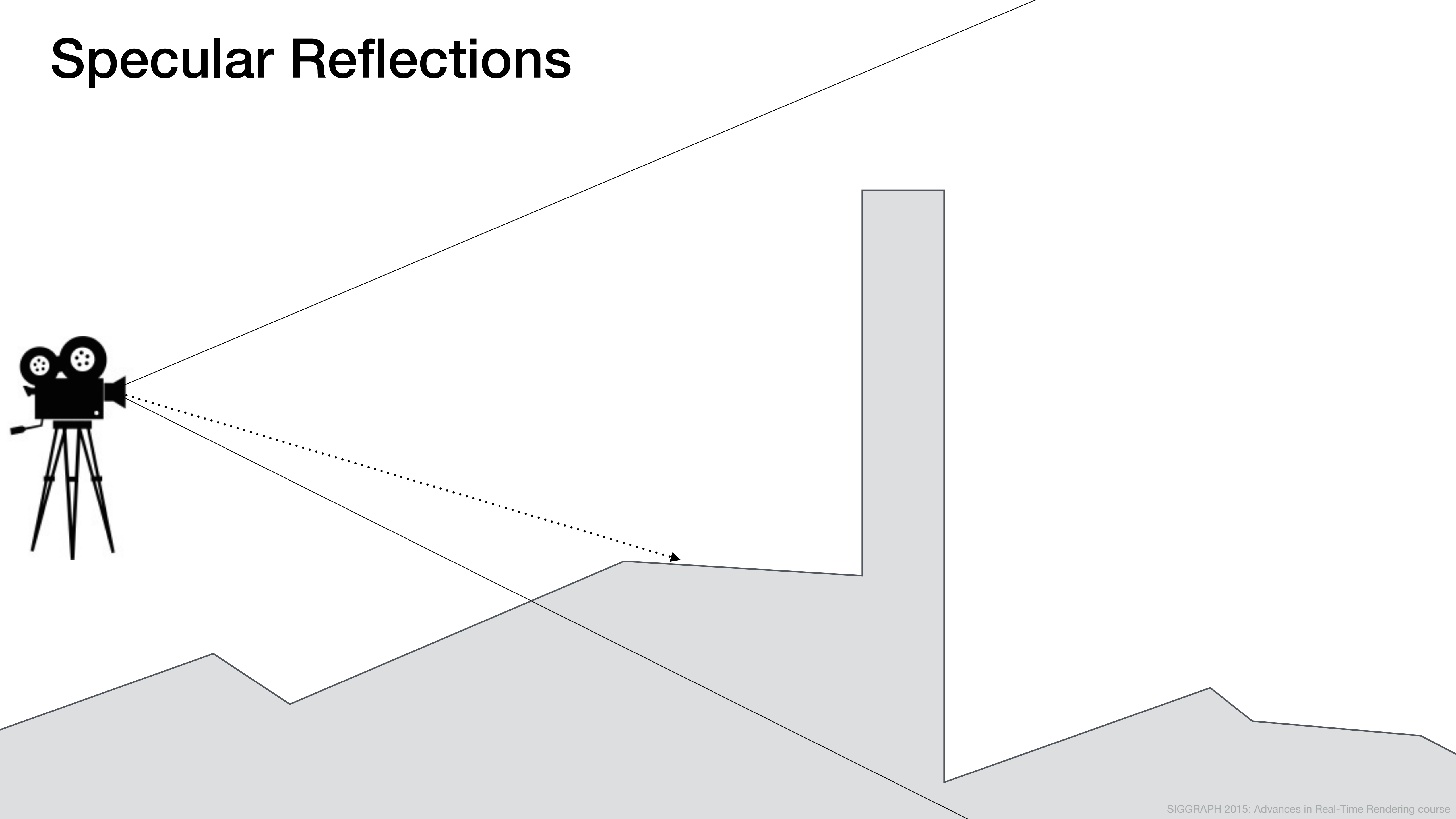
Volumetric lighting ✓

Consistent with dynamic objects ✓

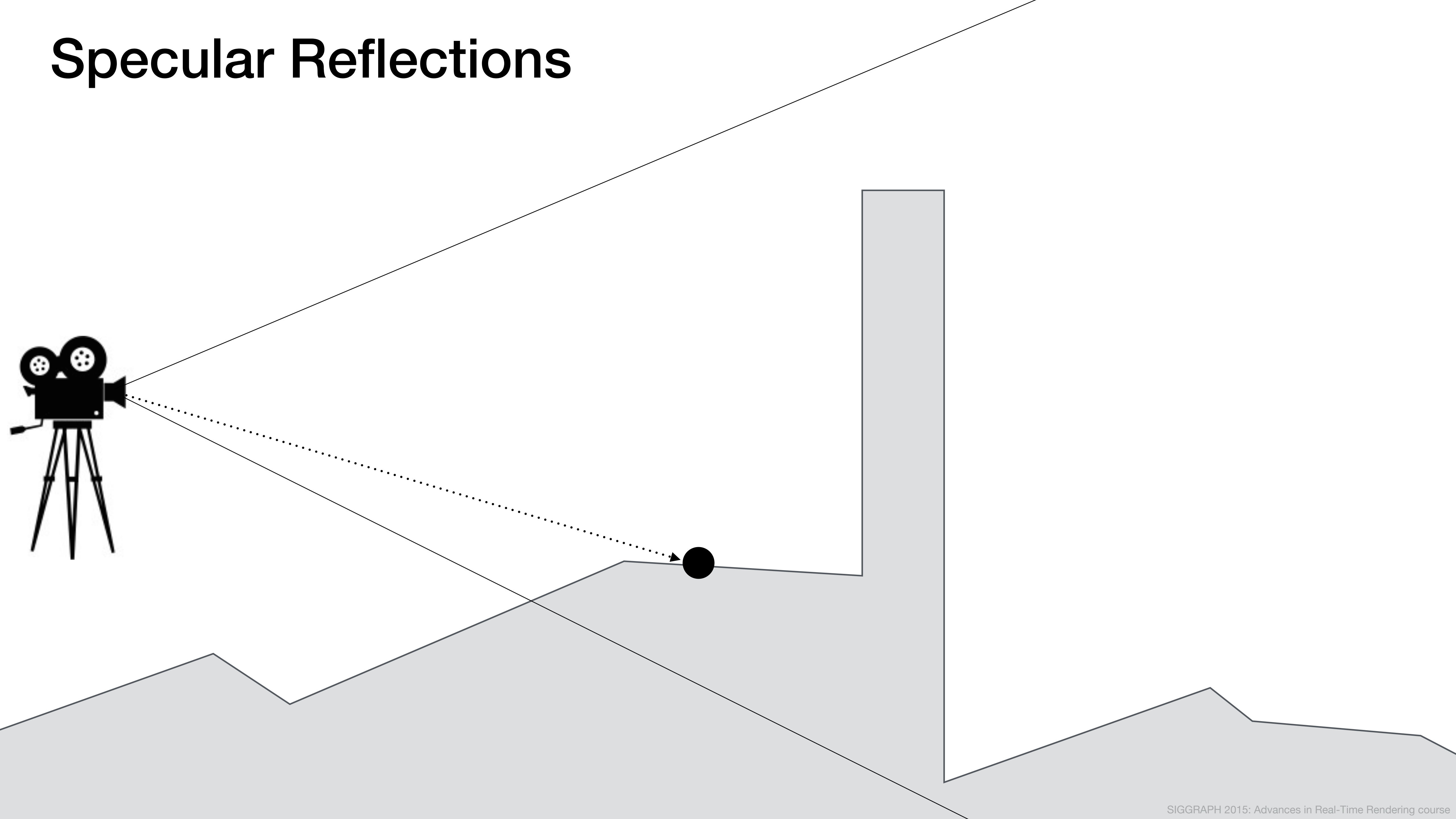
Specular **infeasible** ✗
due to data size



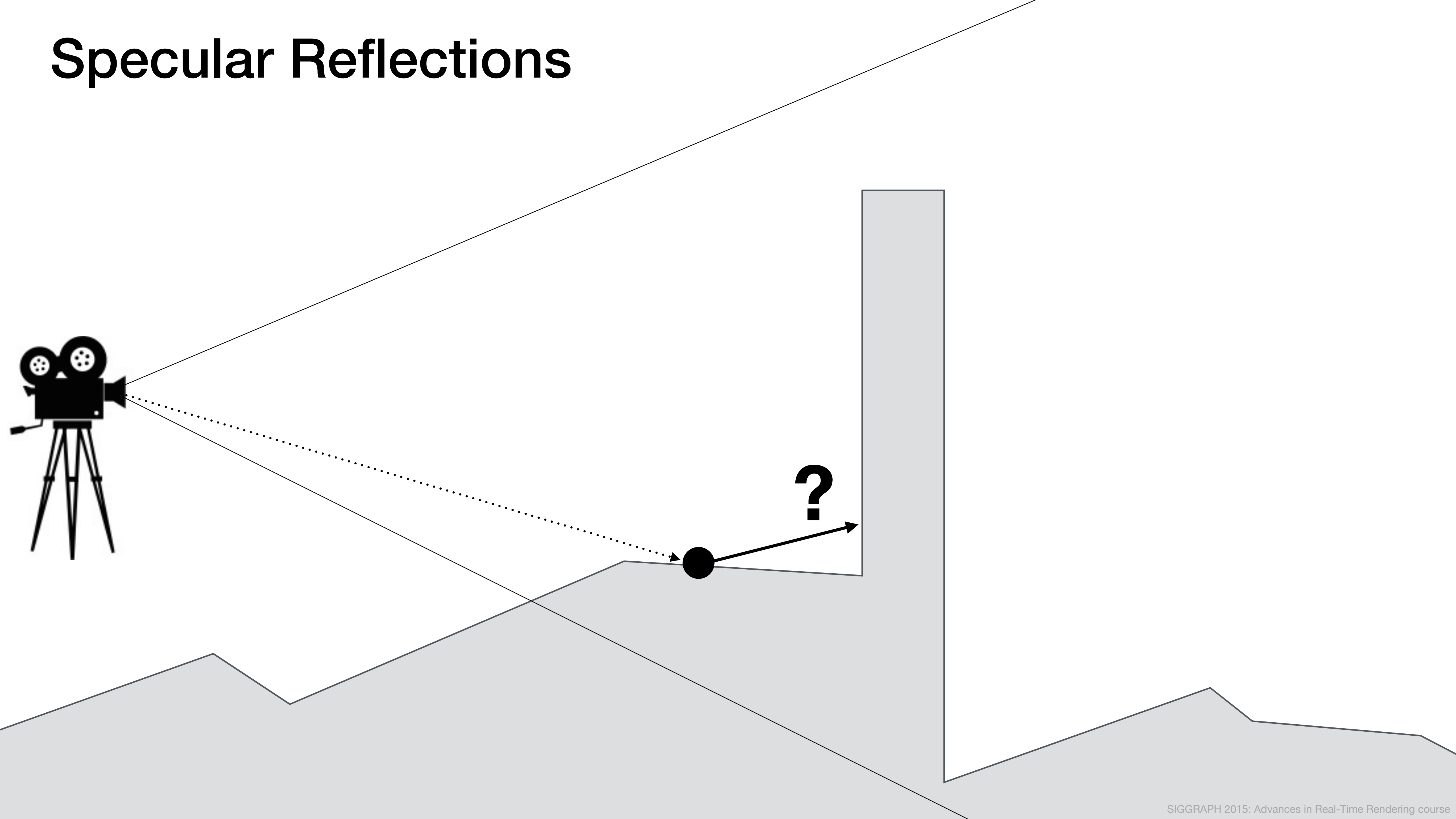
Specular Reflections



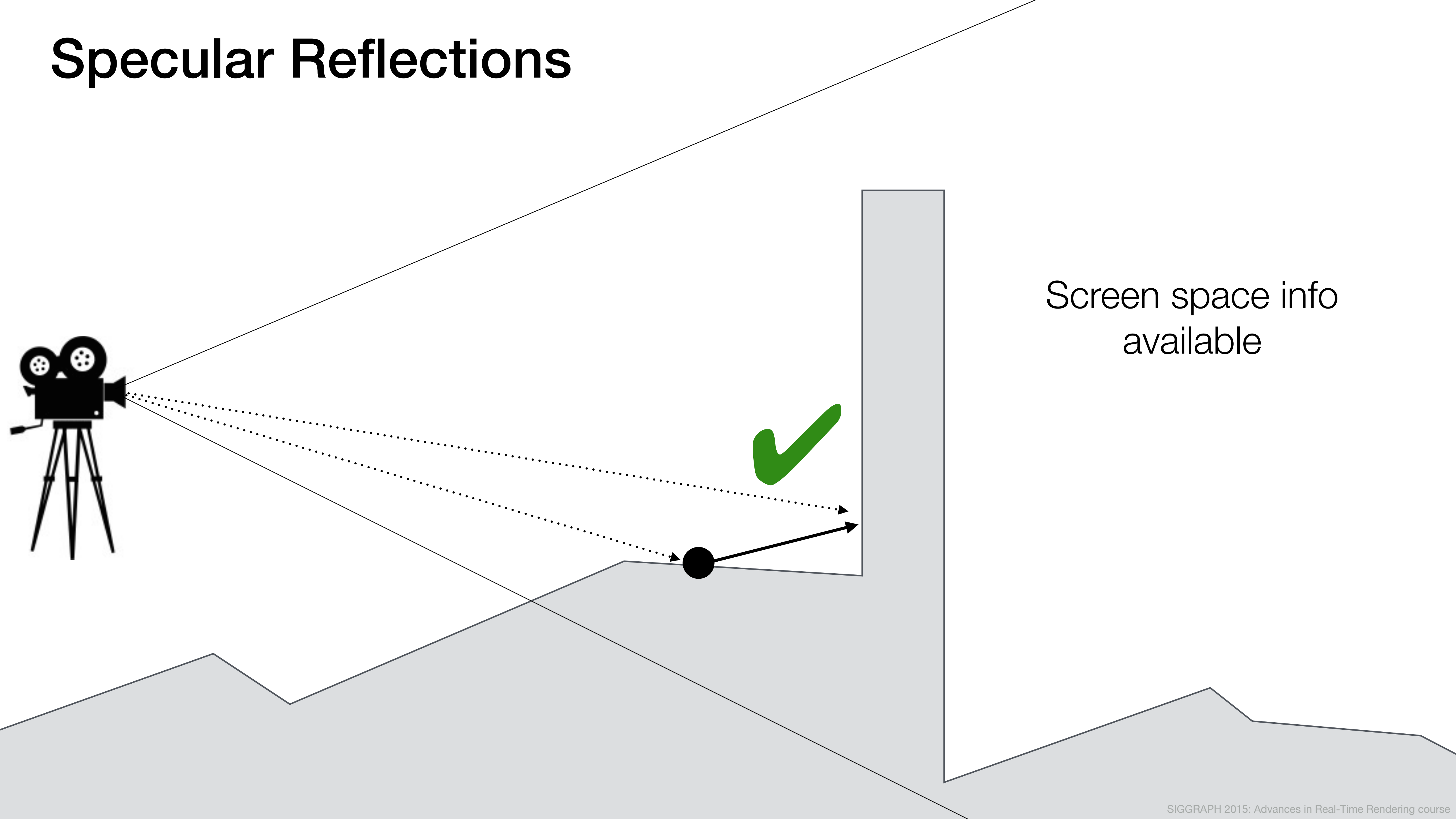
Specular Reflections



Specular Reflections

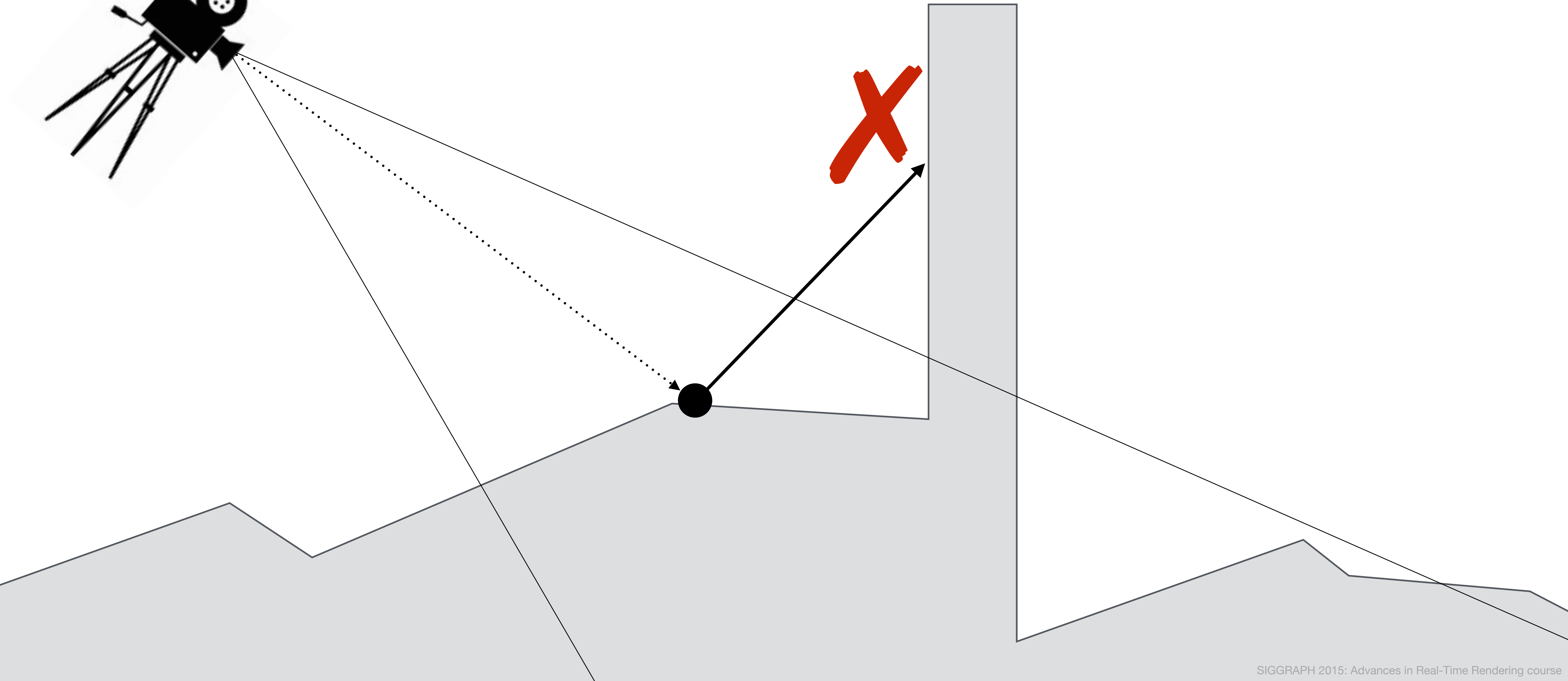


Specular Reflections



Screen space info
available

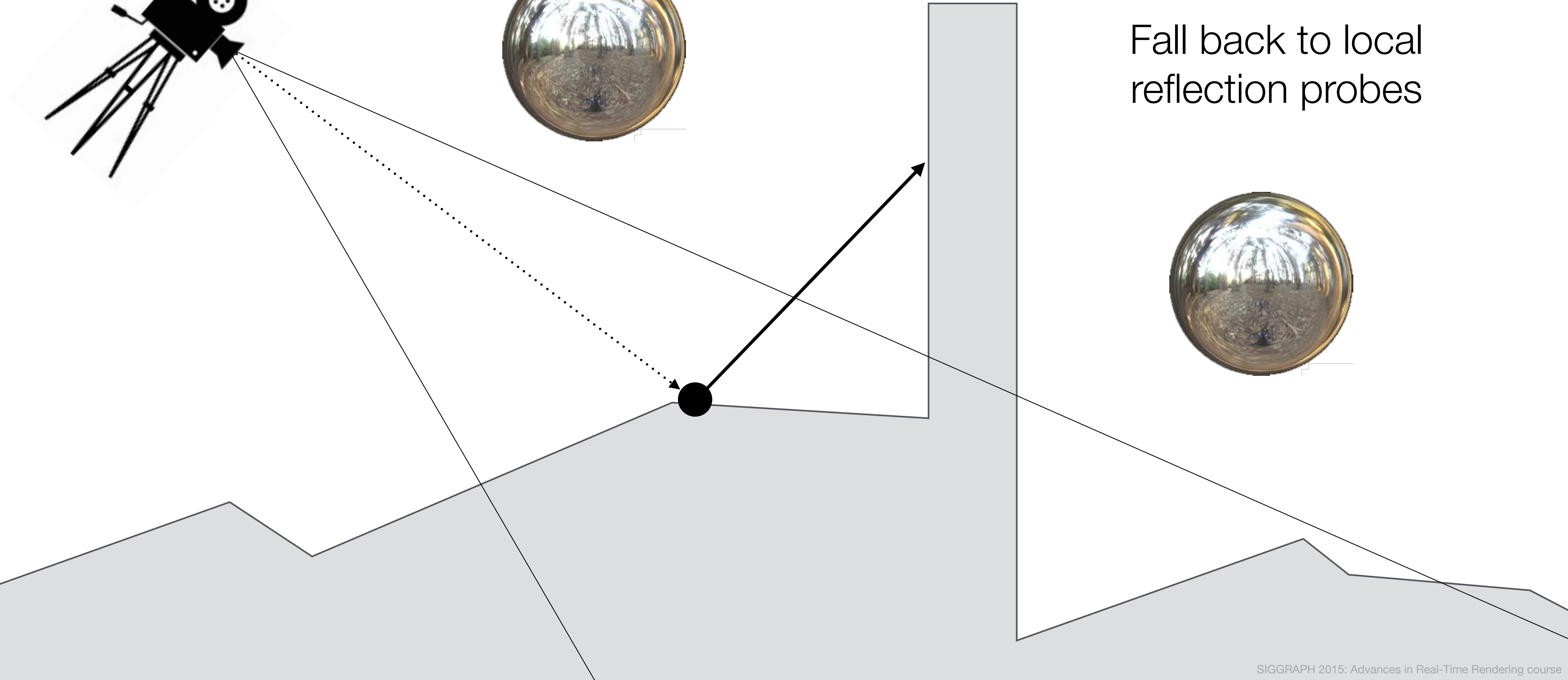
Specular Reflections



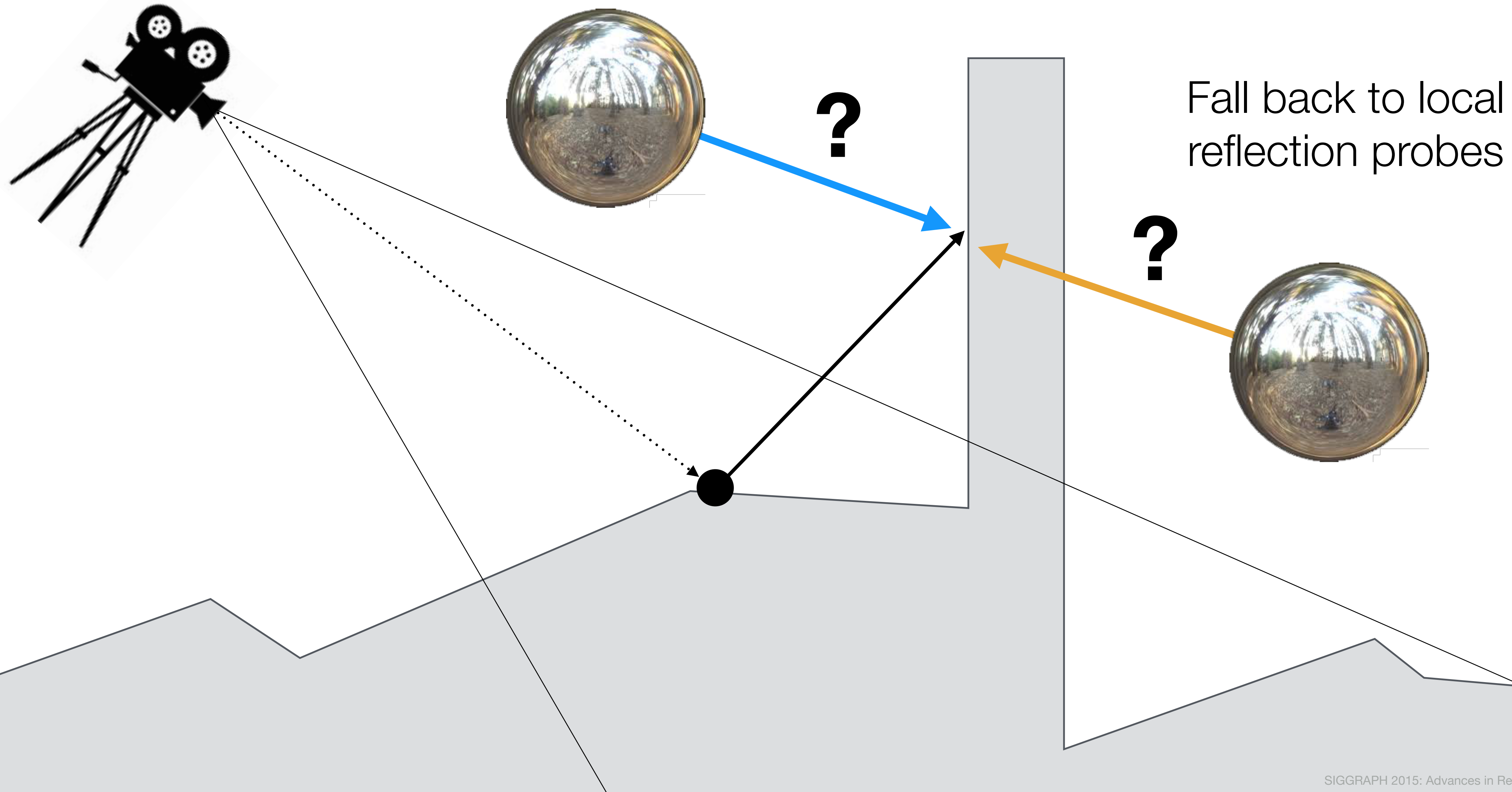
Specular Reflections



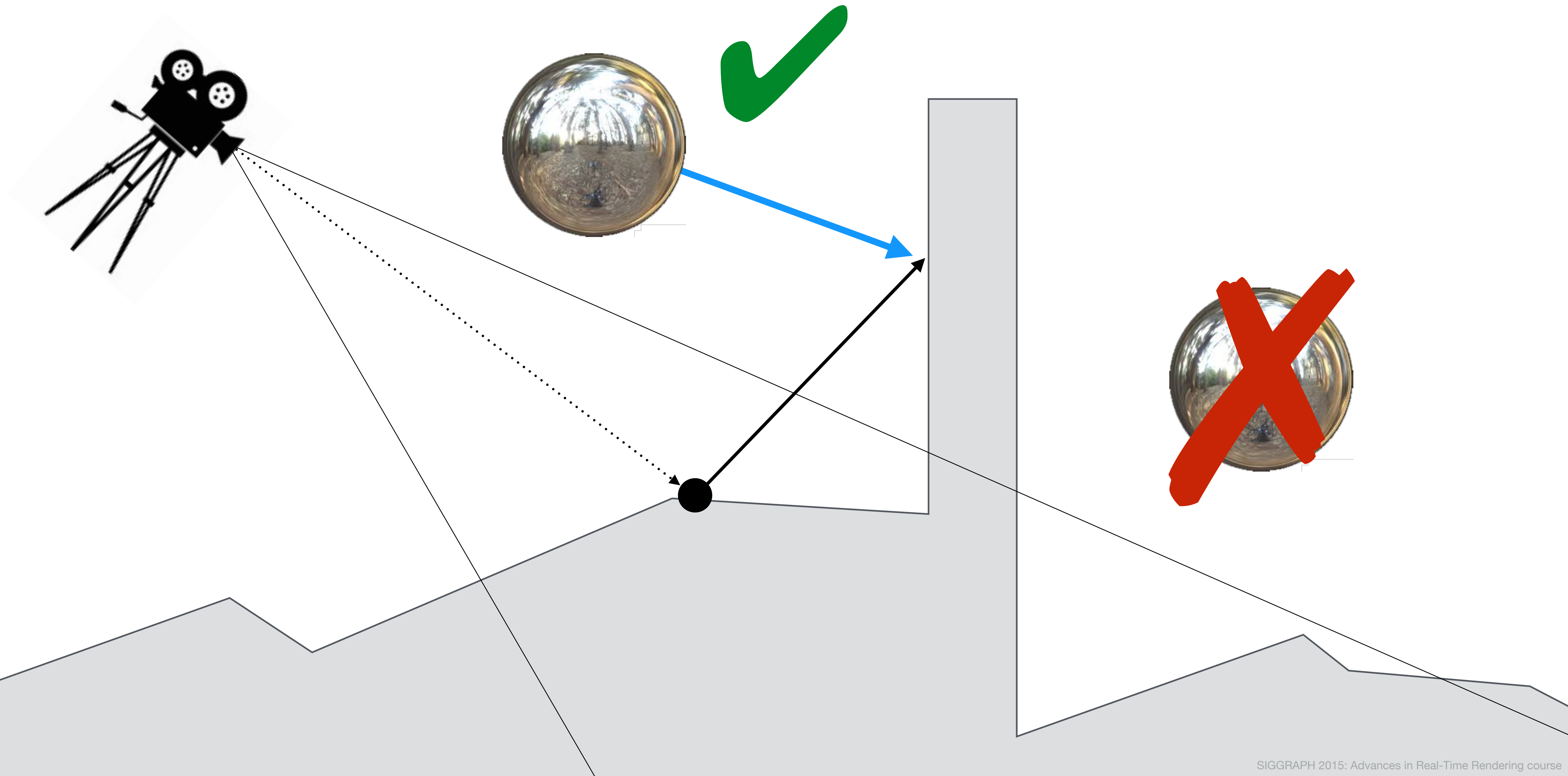
Fall back to local reflection probes



How to Blend Reflection Probes?



How to Blend Reflection Probes?



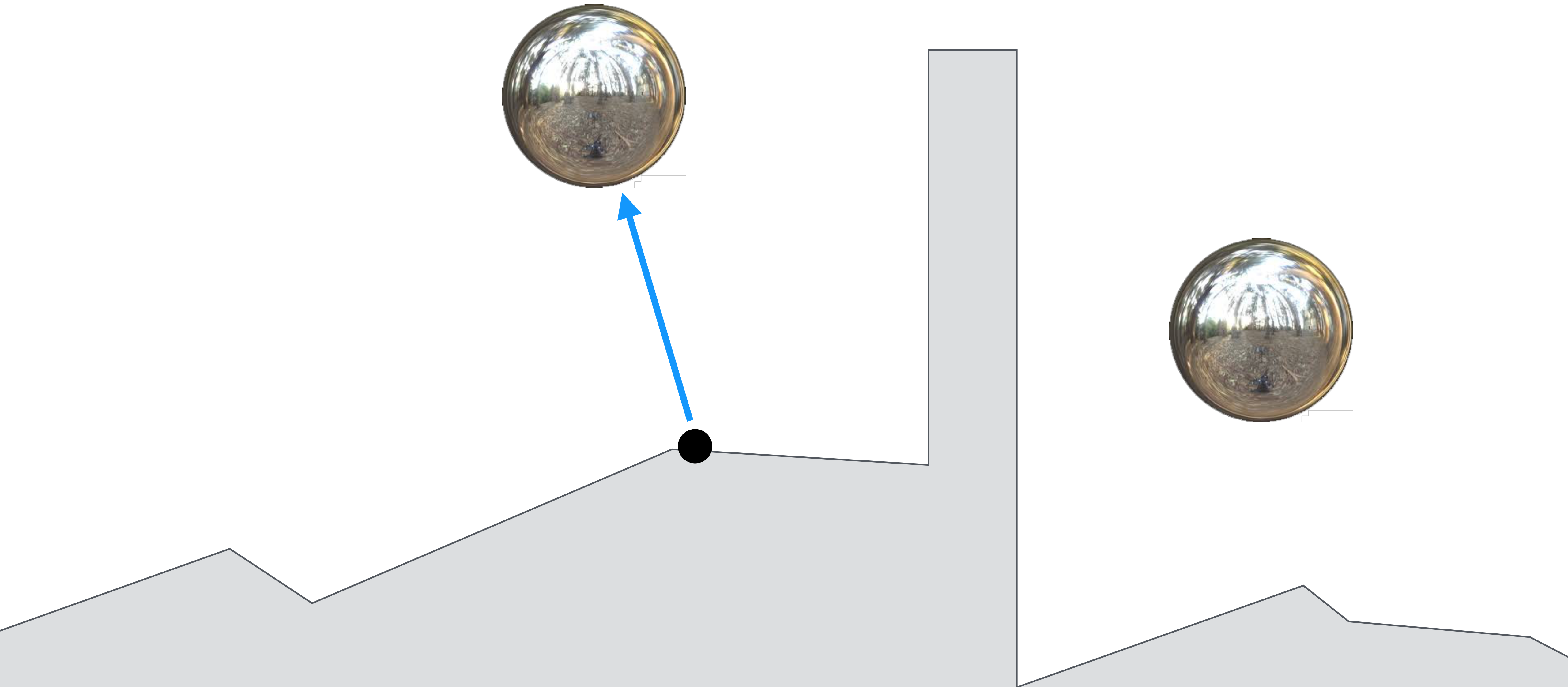
Reflection Probe Visibility



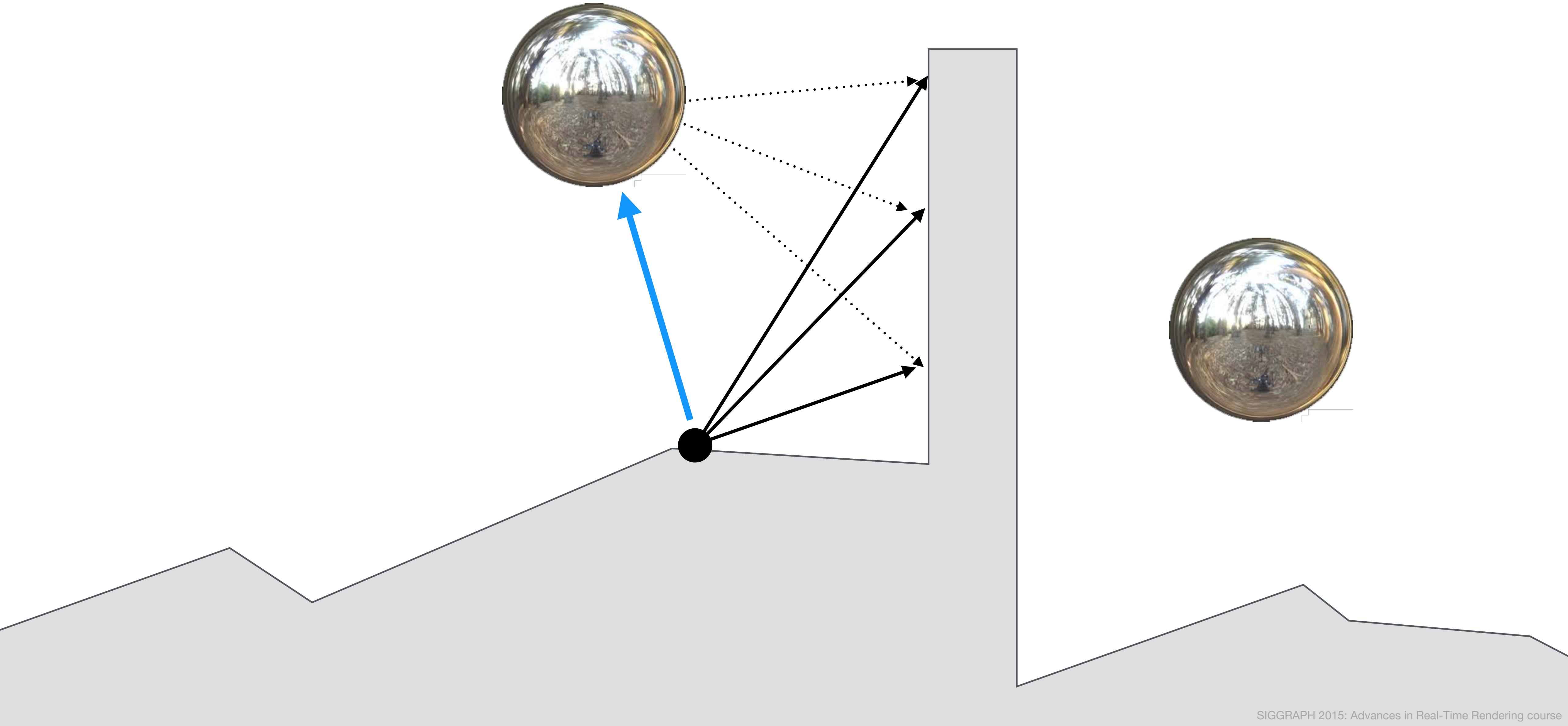
Reflection Probe Visibility



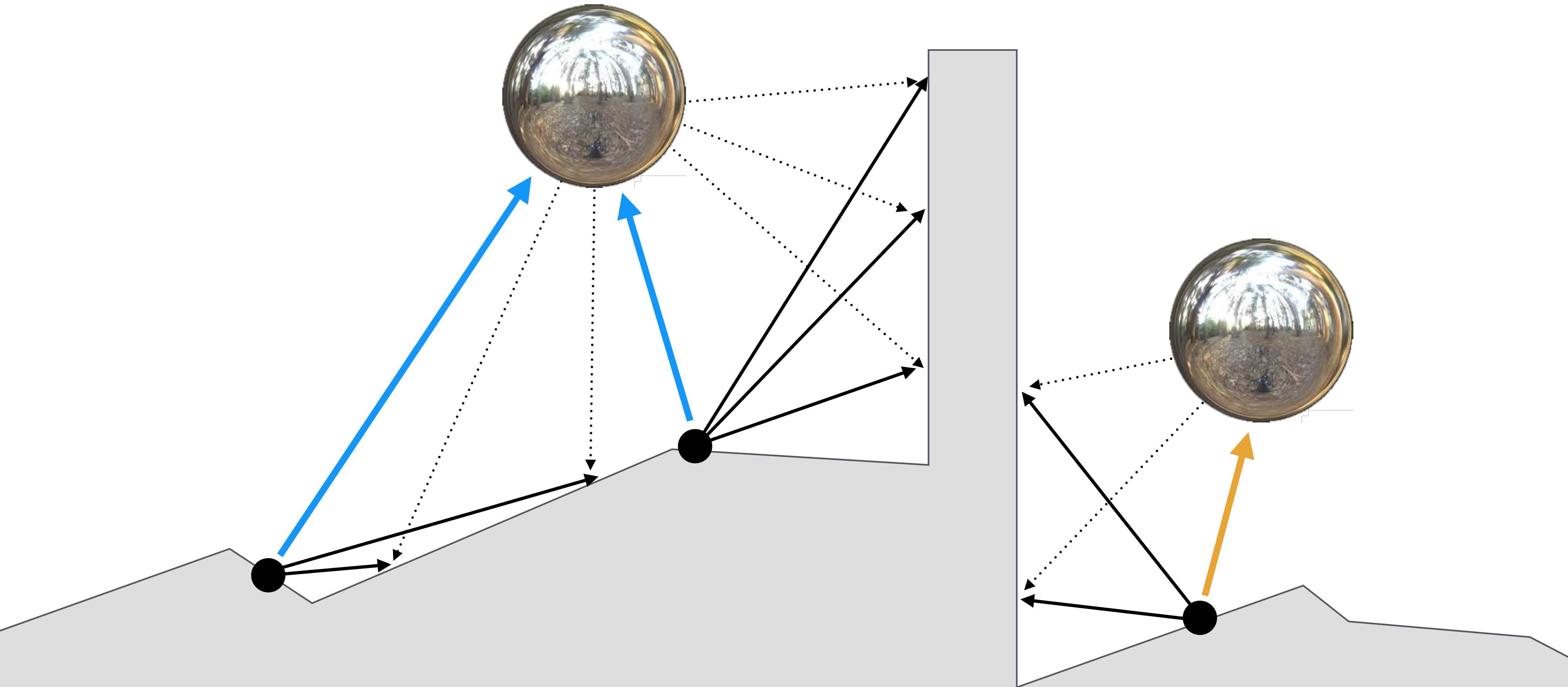
Reflection Probe Visibility



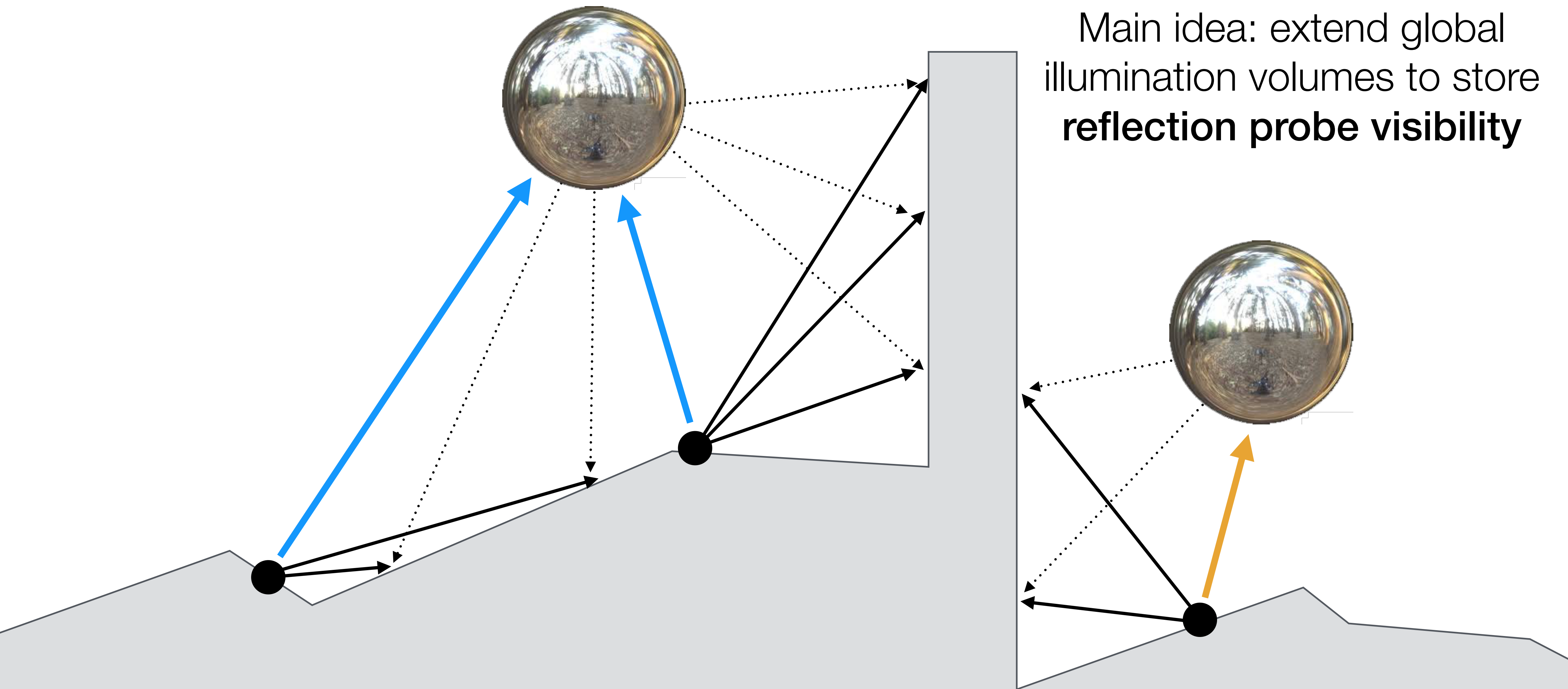
Reflection Probe Visibility



Reflection Probe Visibility

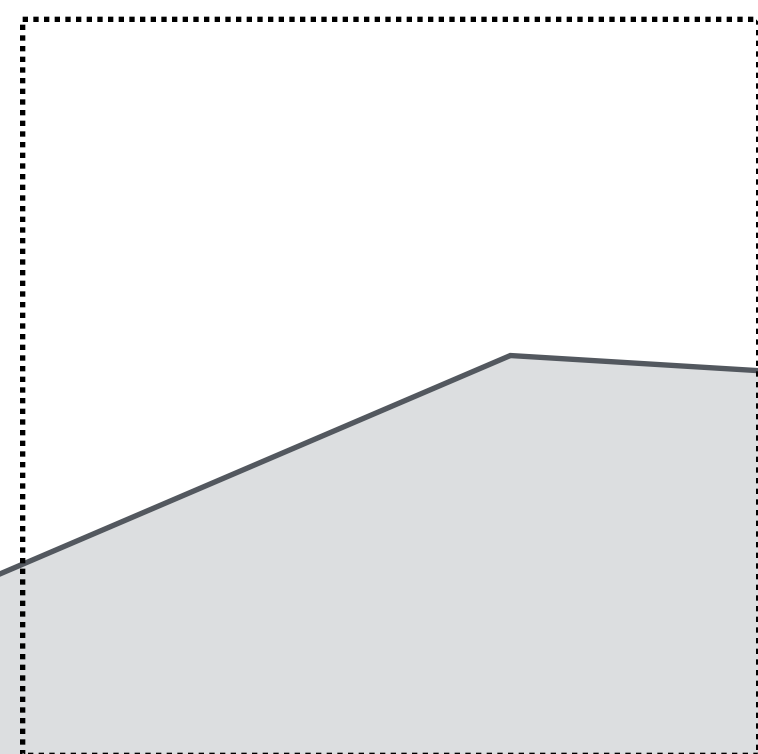


Reflection Probe Visibility



Main idea: extend global illumination volumes to store **reflection probe visibility**

Reflection Probe Visibility

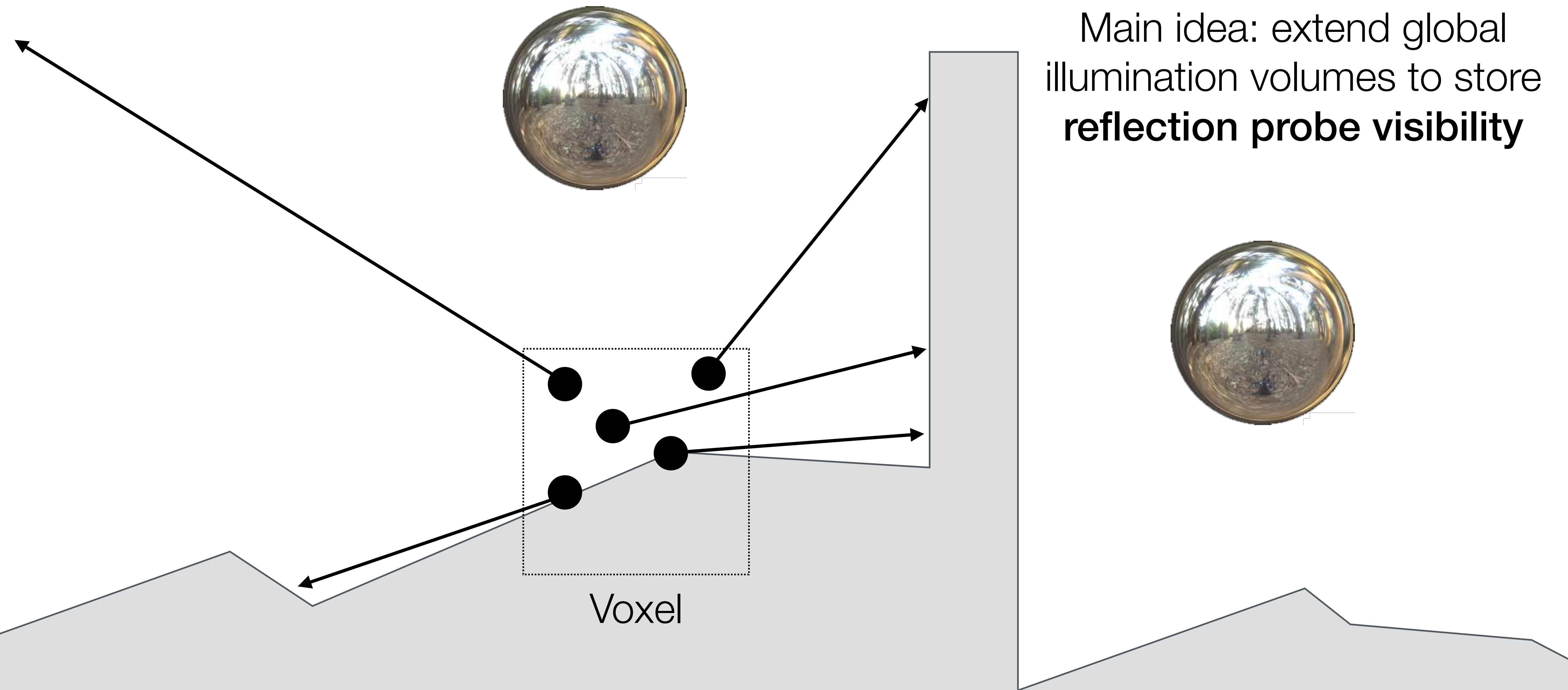


Voxel

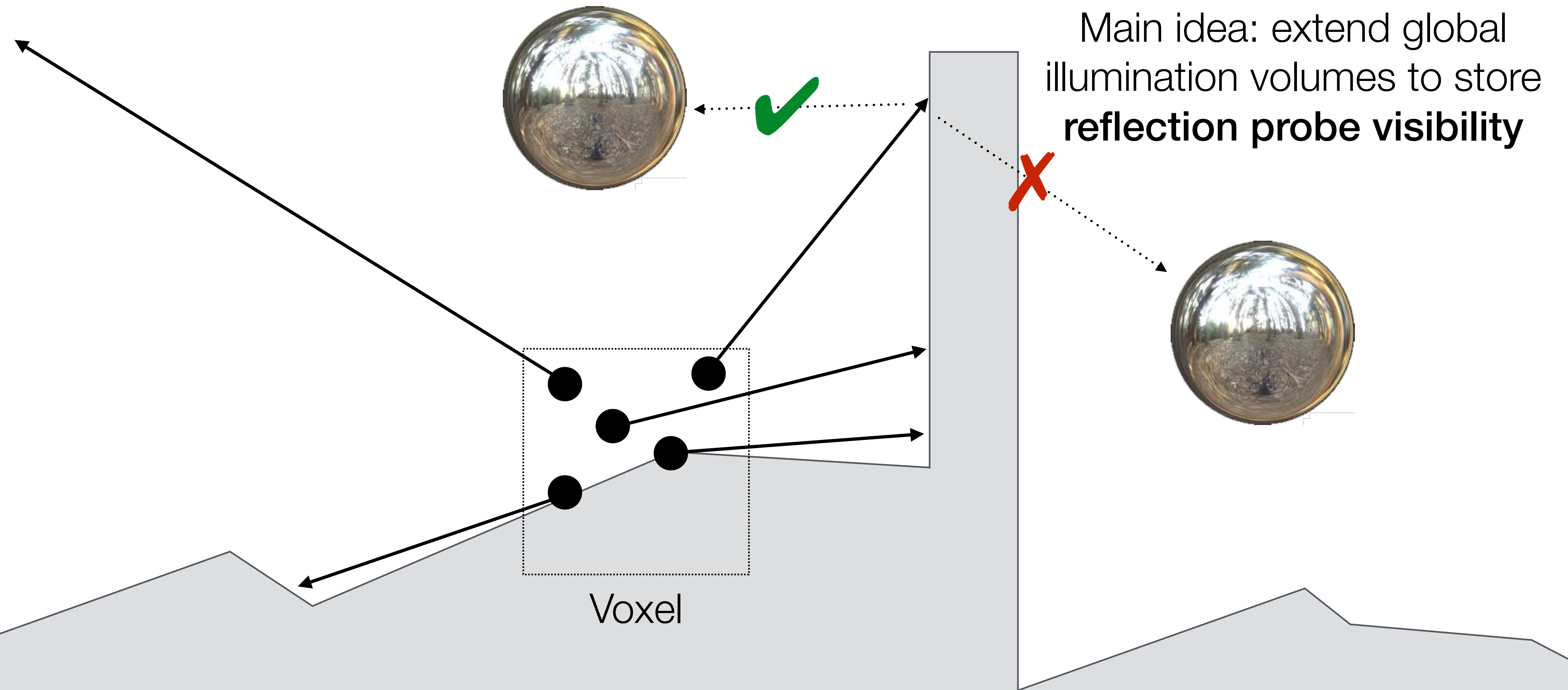
Main idea: extend global illumination volumes to store **reflection probe visibility**



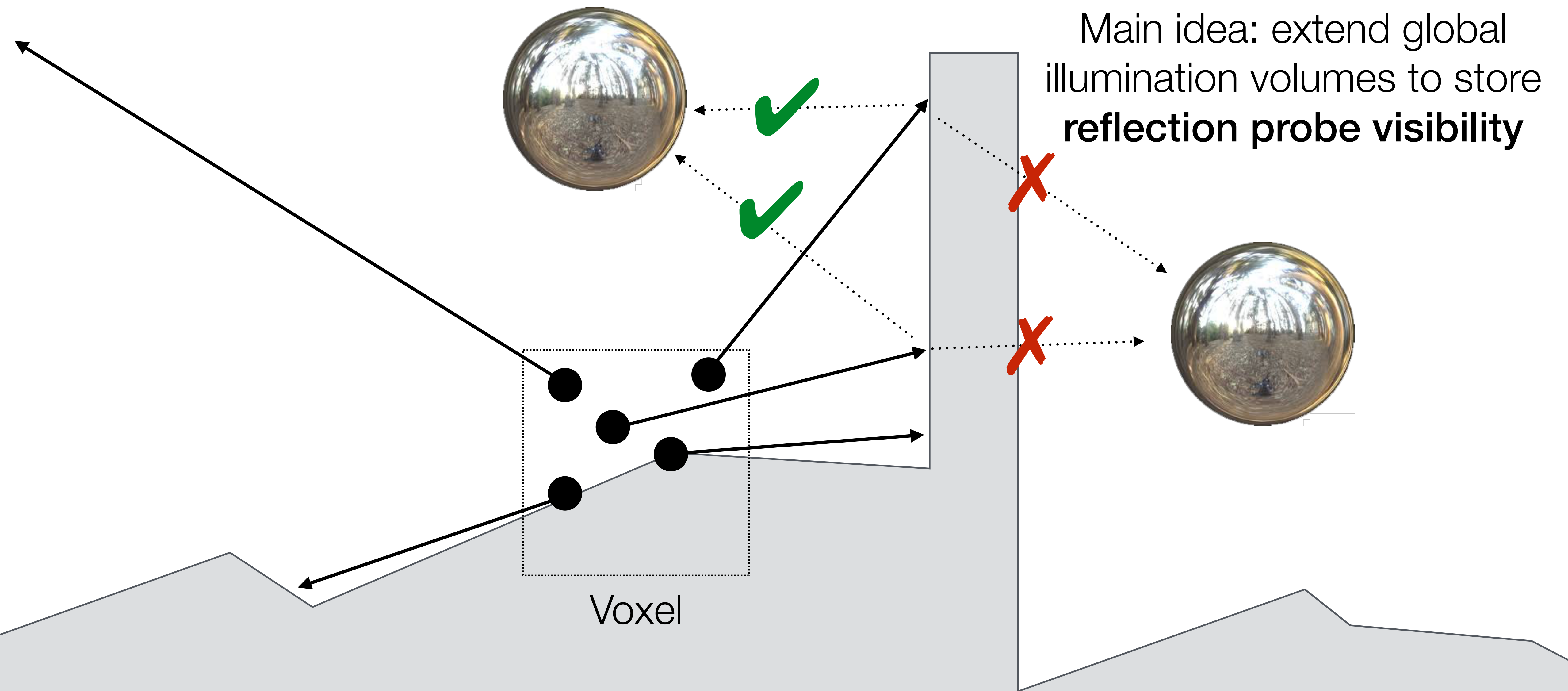
Reflection Probe Visibility



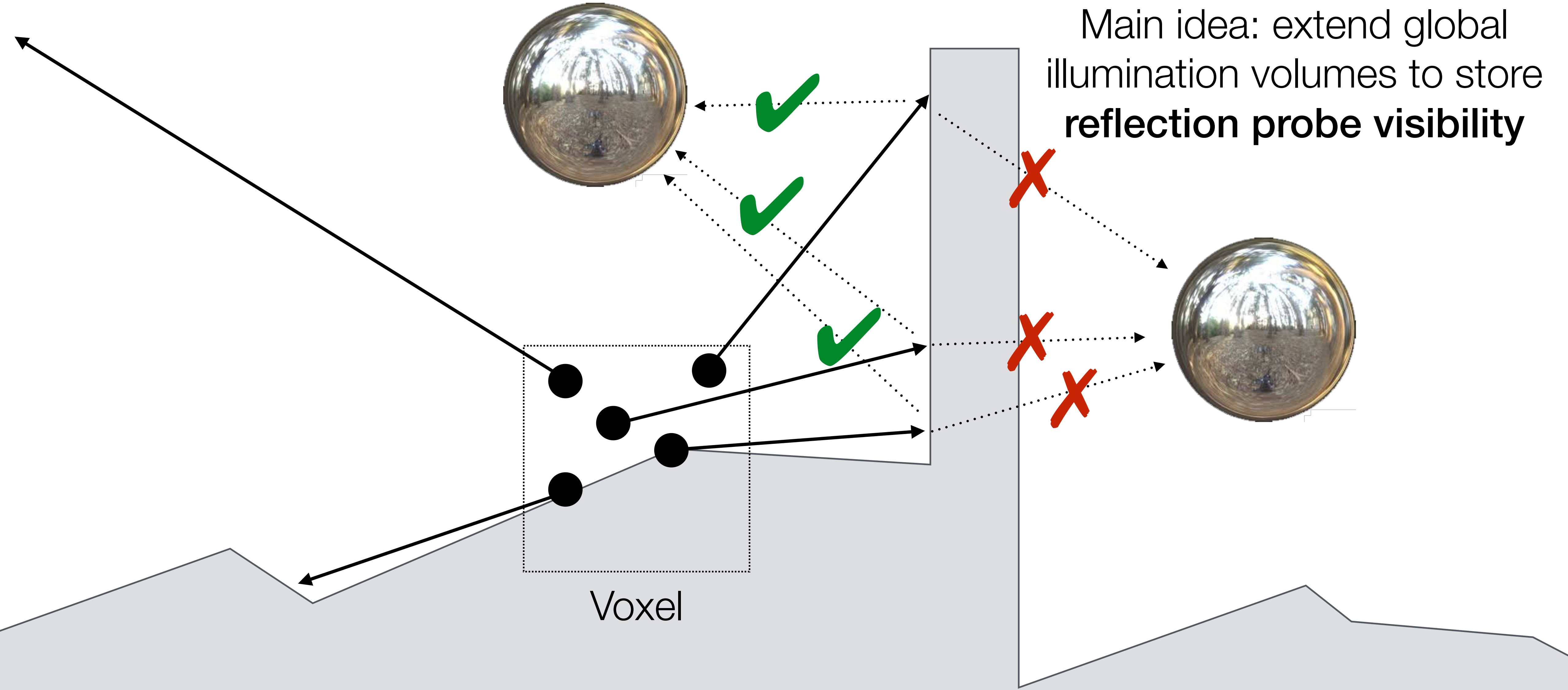
Reflection Probe Visibility



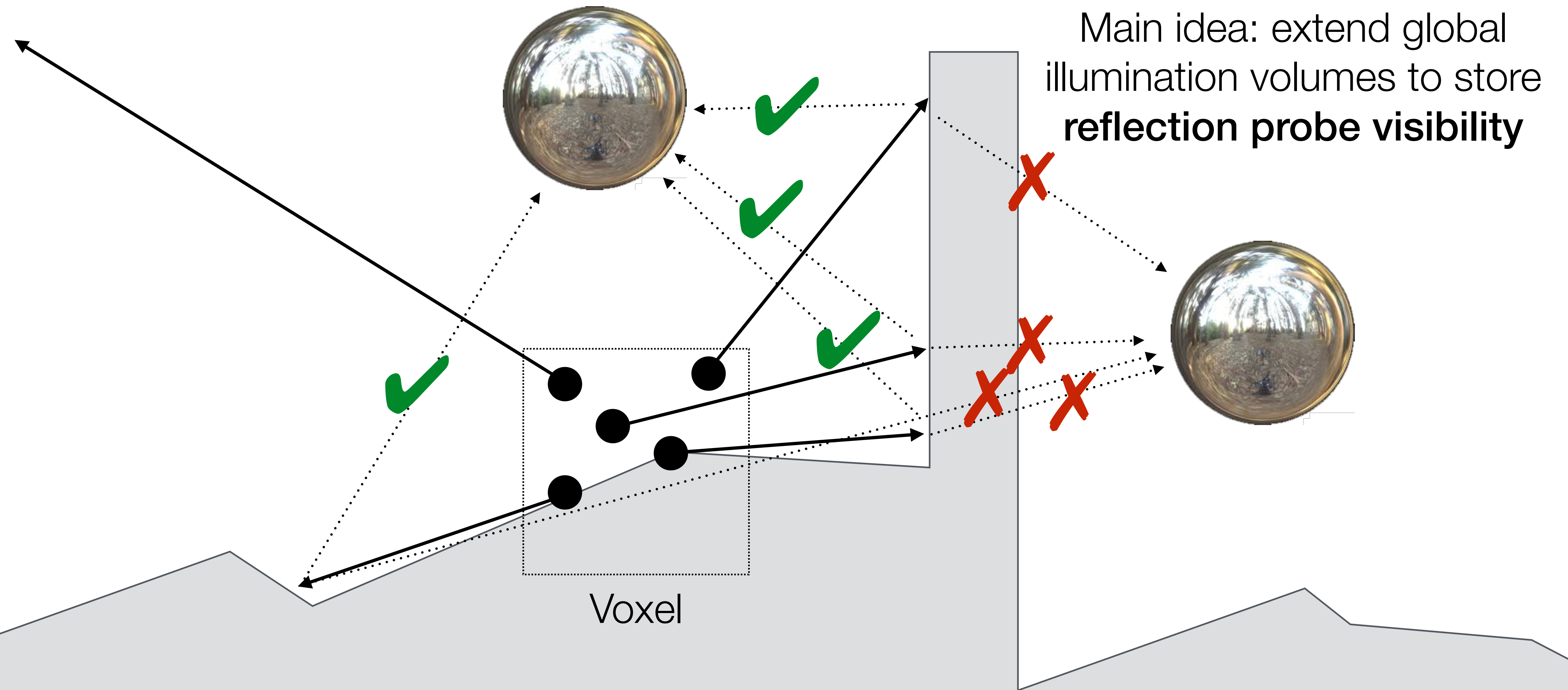
Reflection Probe Visibility



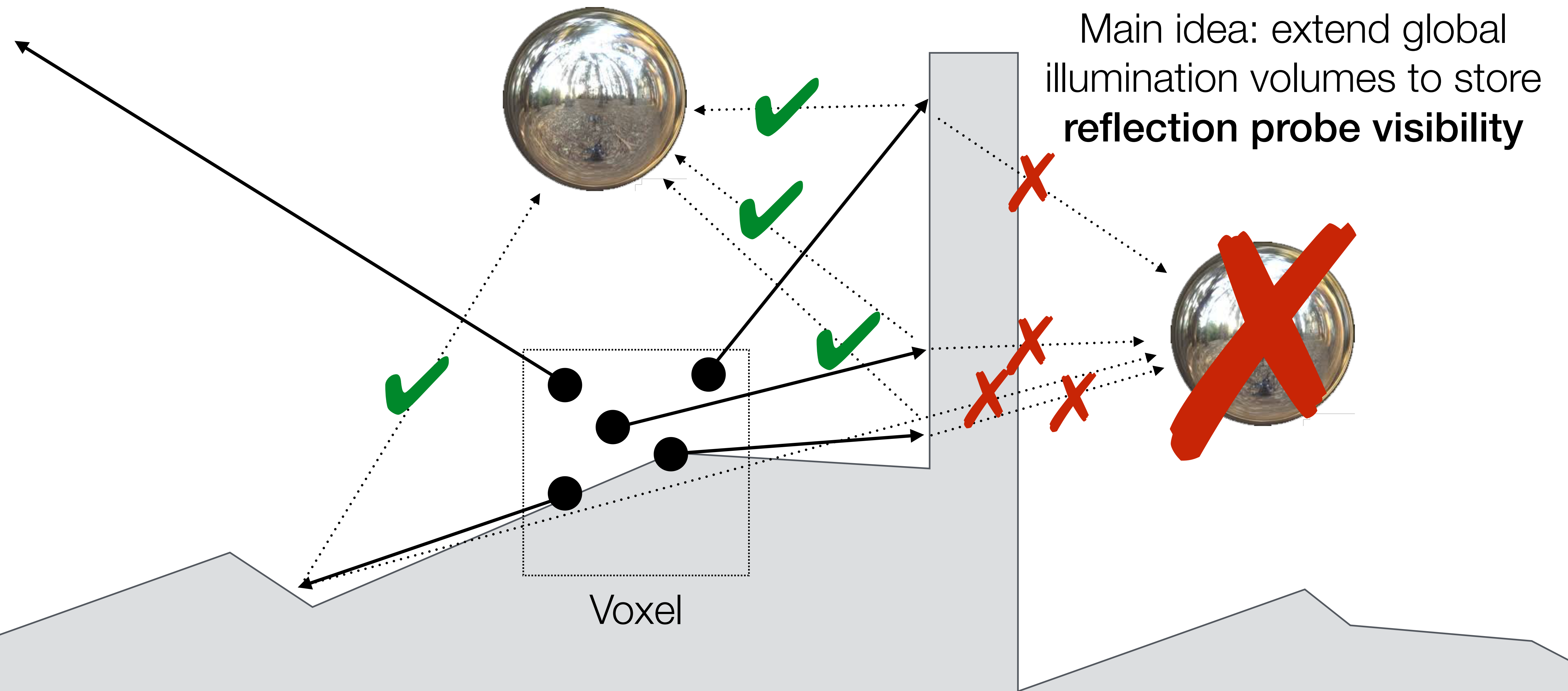
Reflection Probe Visibility



Reflection Probe Visibility



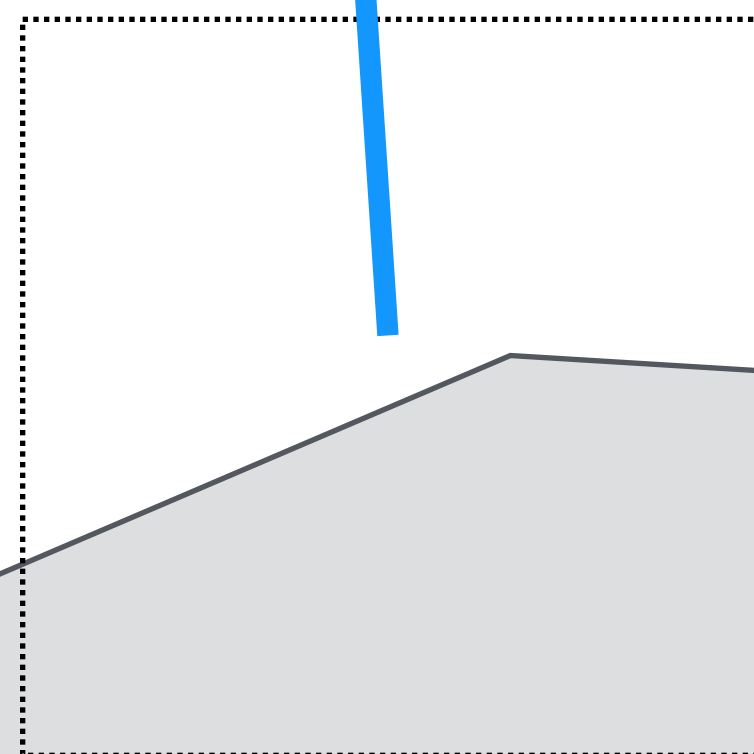
Reflection Probe Visibility



Reflection Probe Visibility



Store best reflection probes in the voxel



Voxel

Main idea: extend global illumination volumes to store **reflection probe visibility**



Reflection Probes



Reflection Probes



On



Off

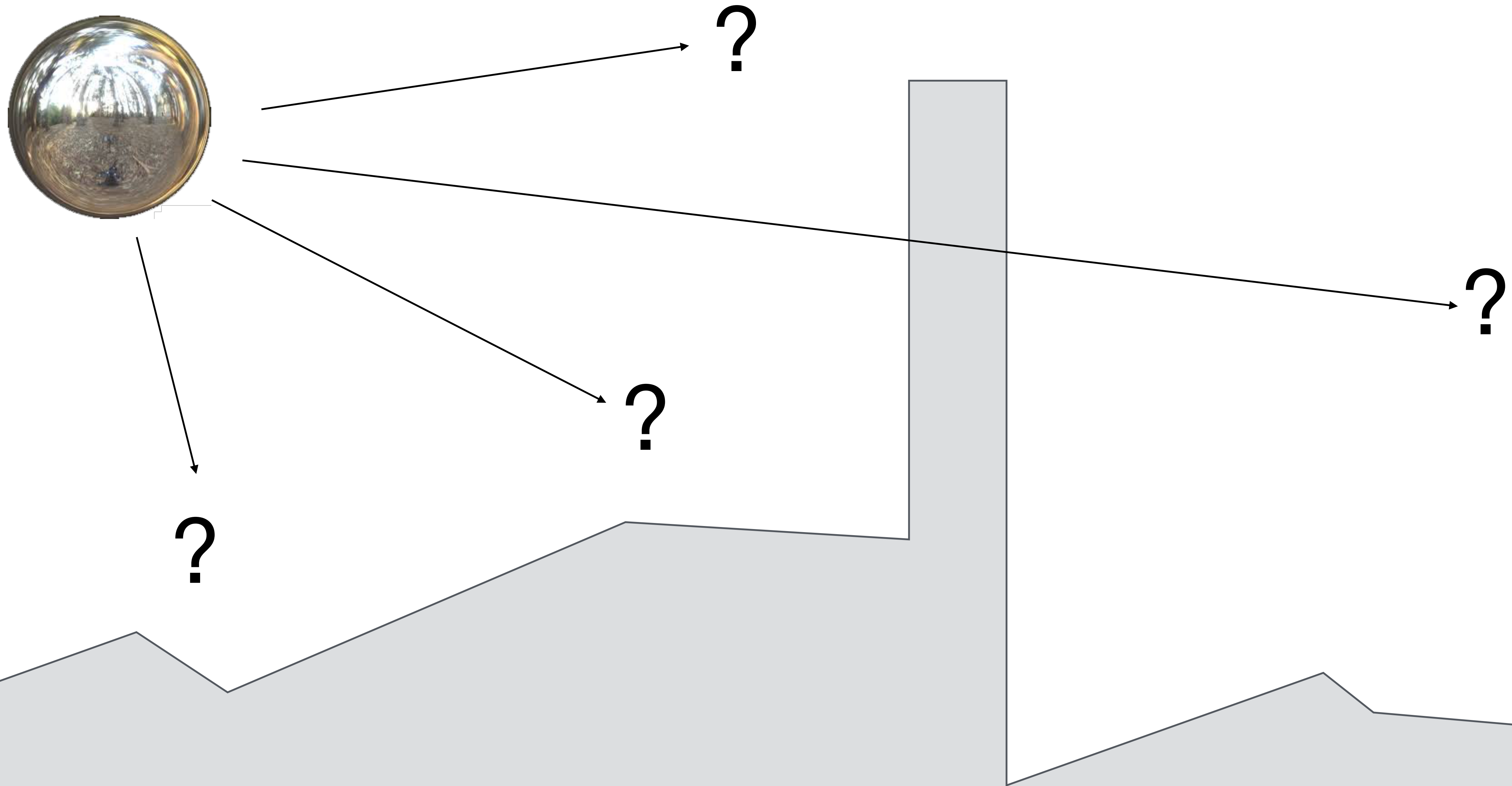


On

Off

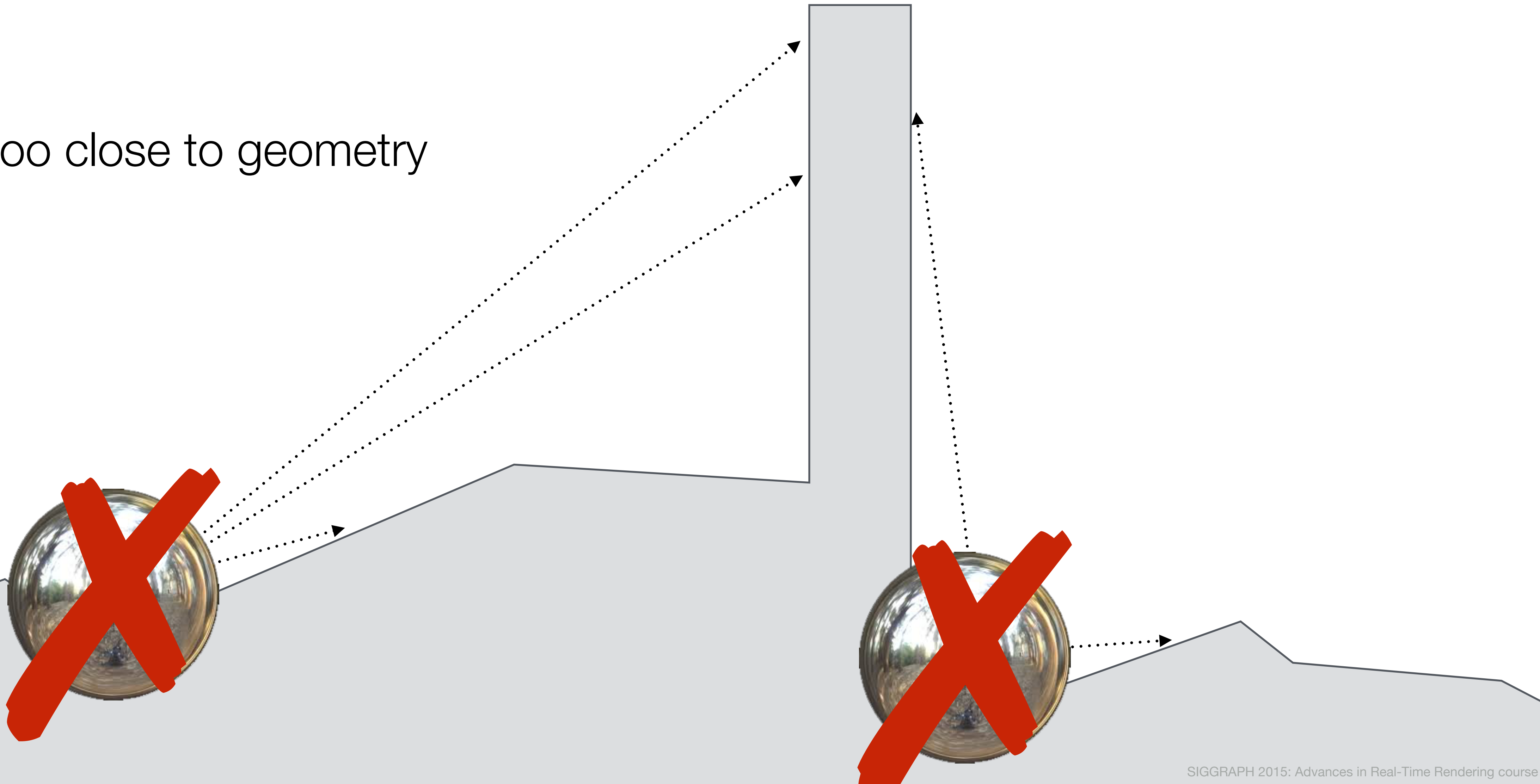


Where to Place Reflection Probes?



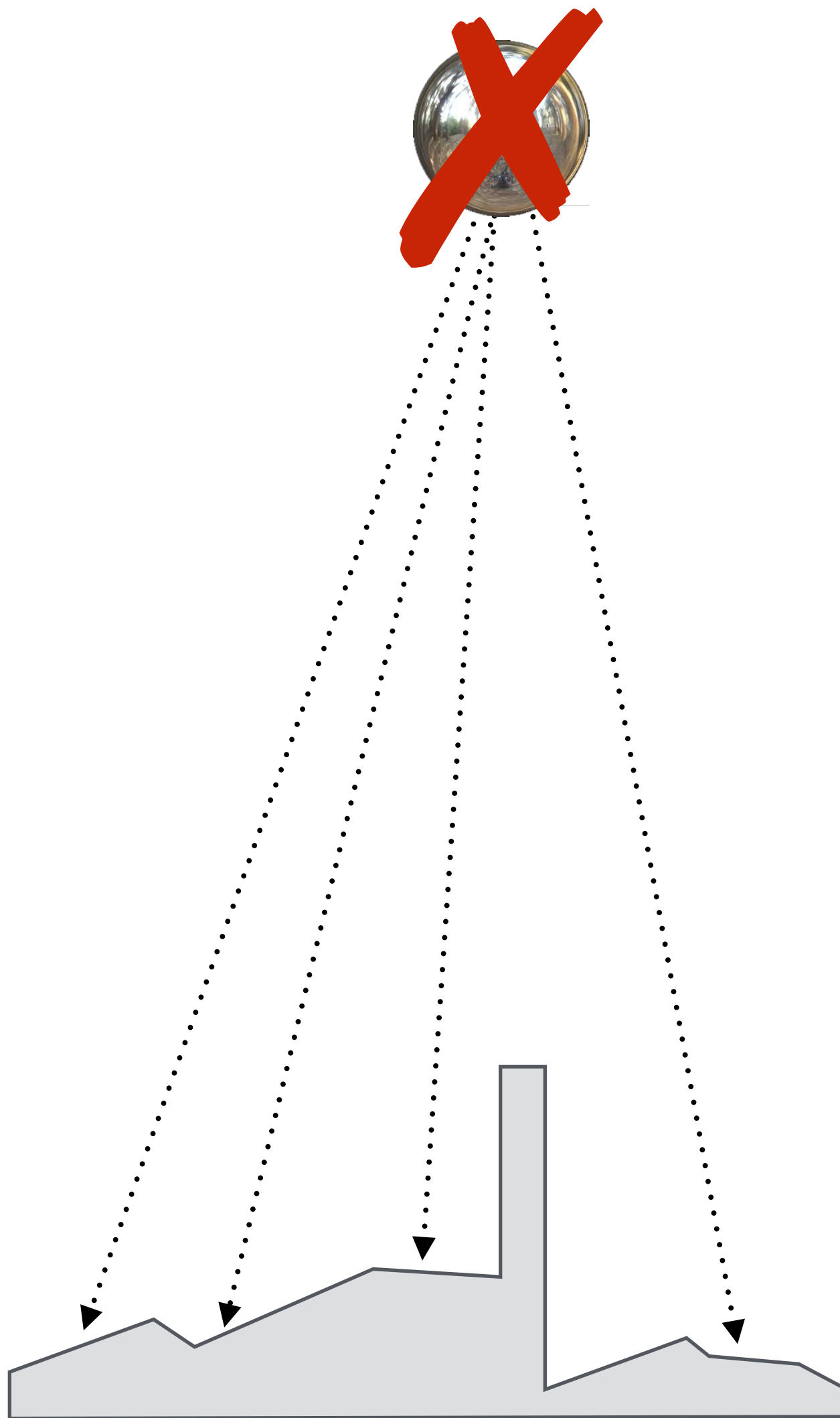
Where to Place Reflection Probes?

Not too close to geometry



Where to Place Reflection Probes?

Not too far from geometry



Observation

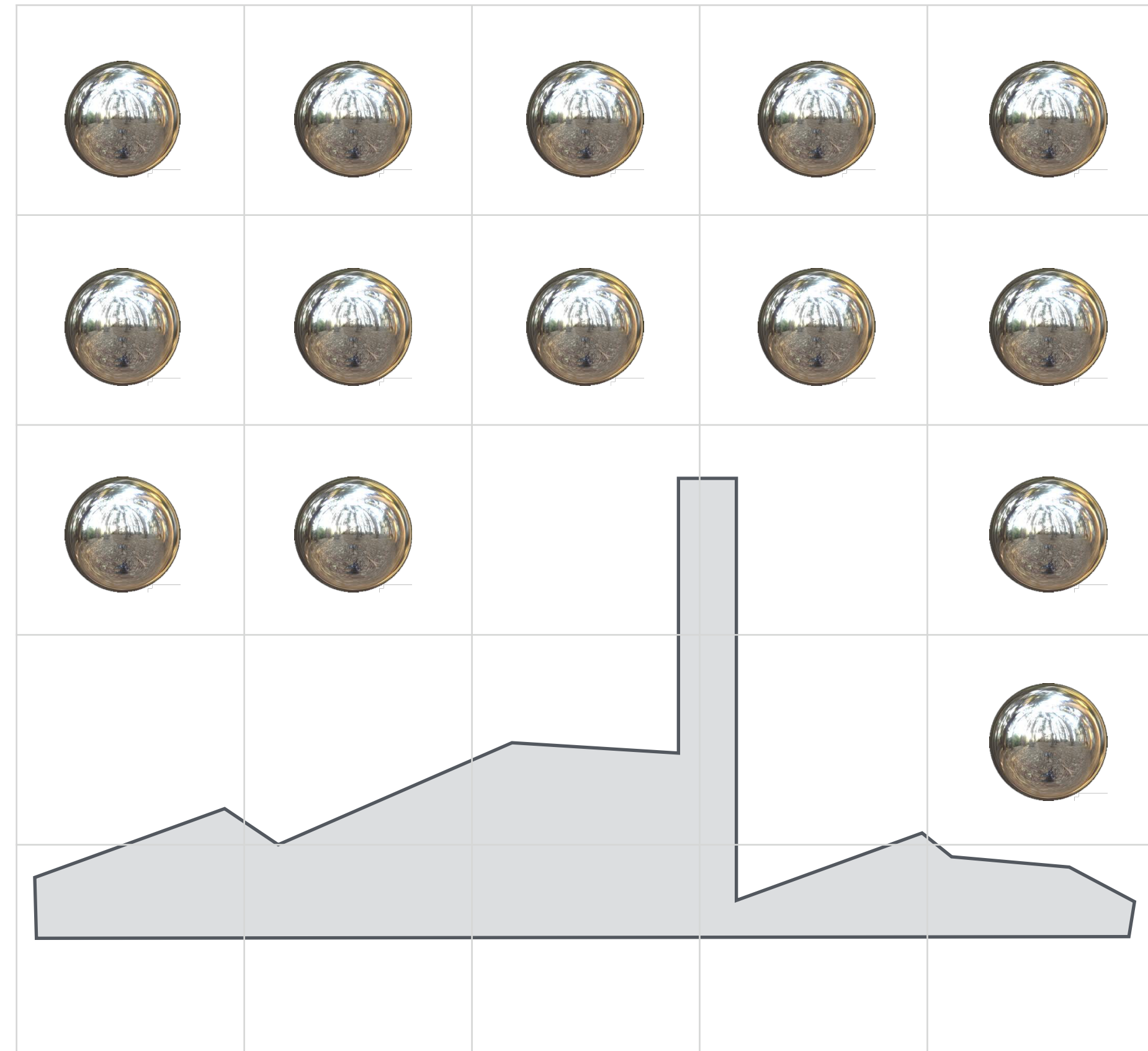
Maximise **visible surface area**

Minimize **distance** to surface

Automatic Probe Placement

Maximise **visible surface area**

Minimize **distance** to surface

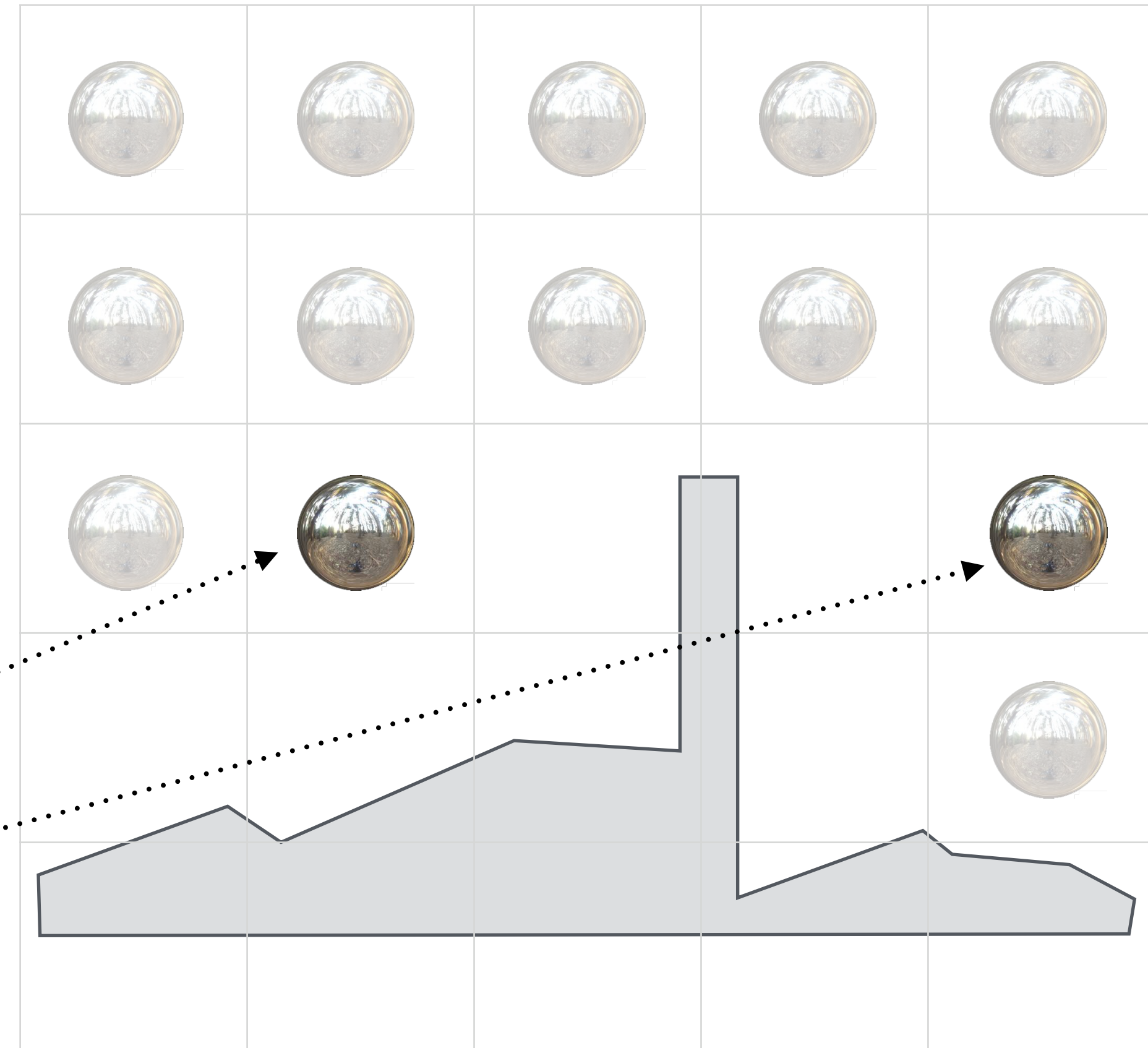


Automatic Probe Placement

Maximise **visible surface area**

Minimize **distance** to surface

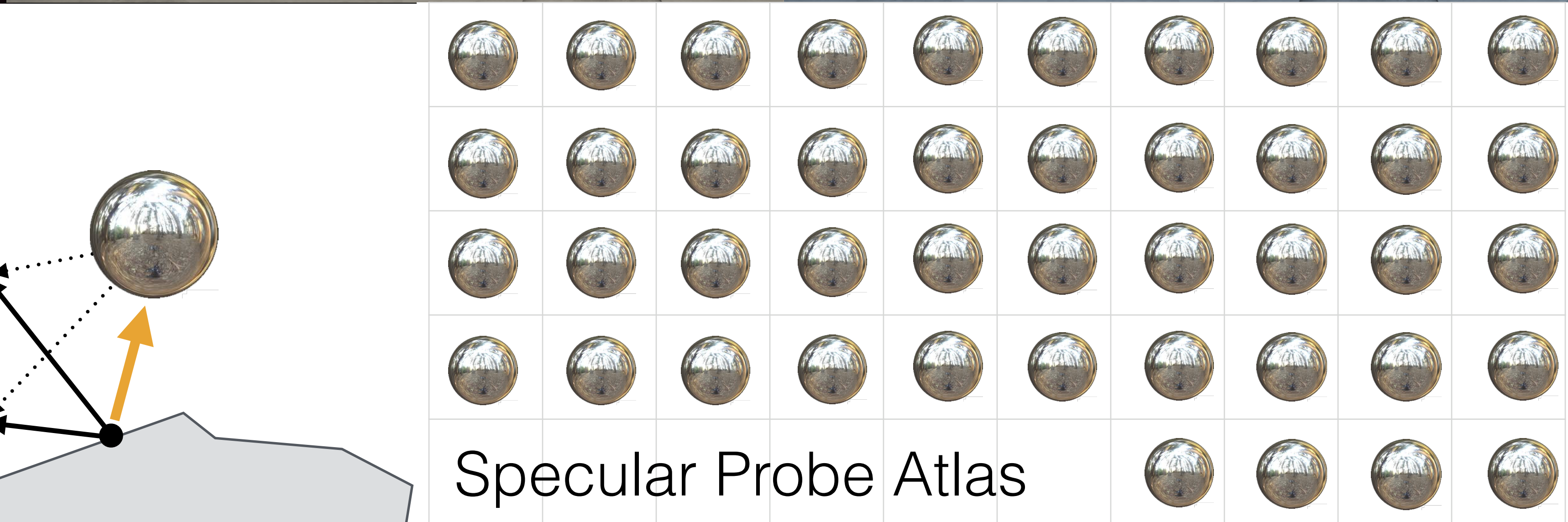
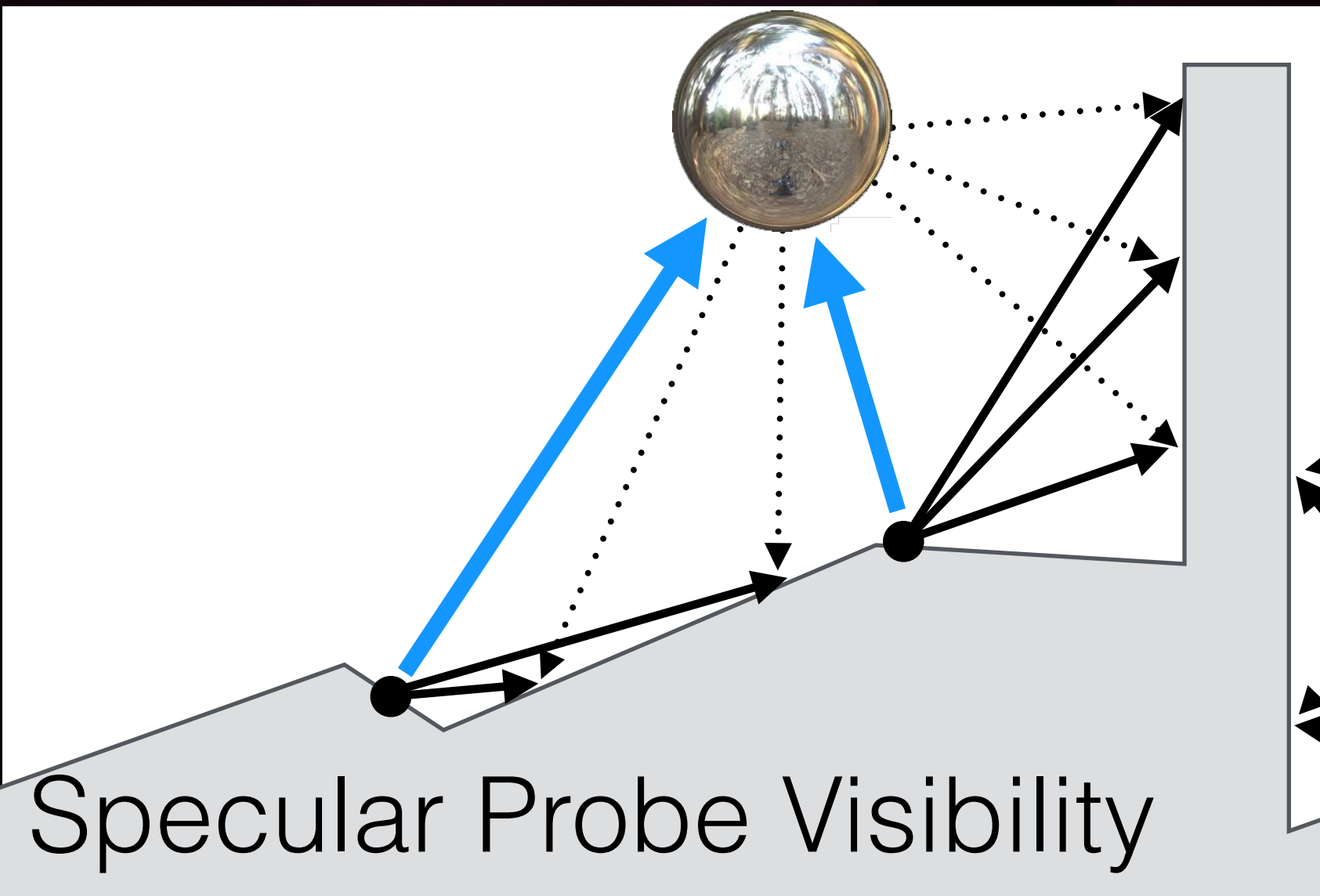
Choose K best probe locations



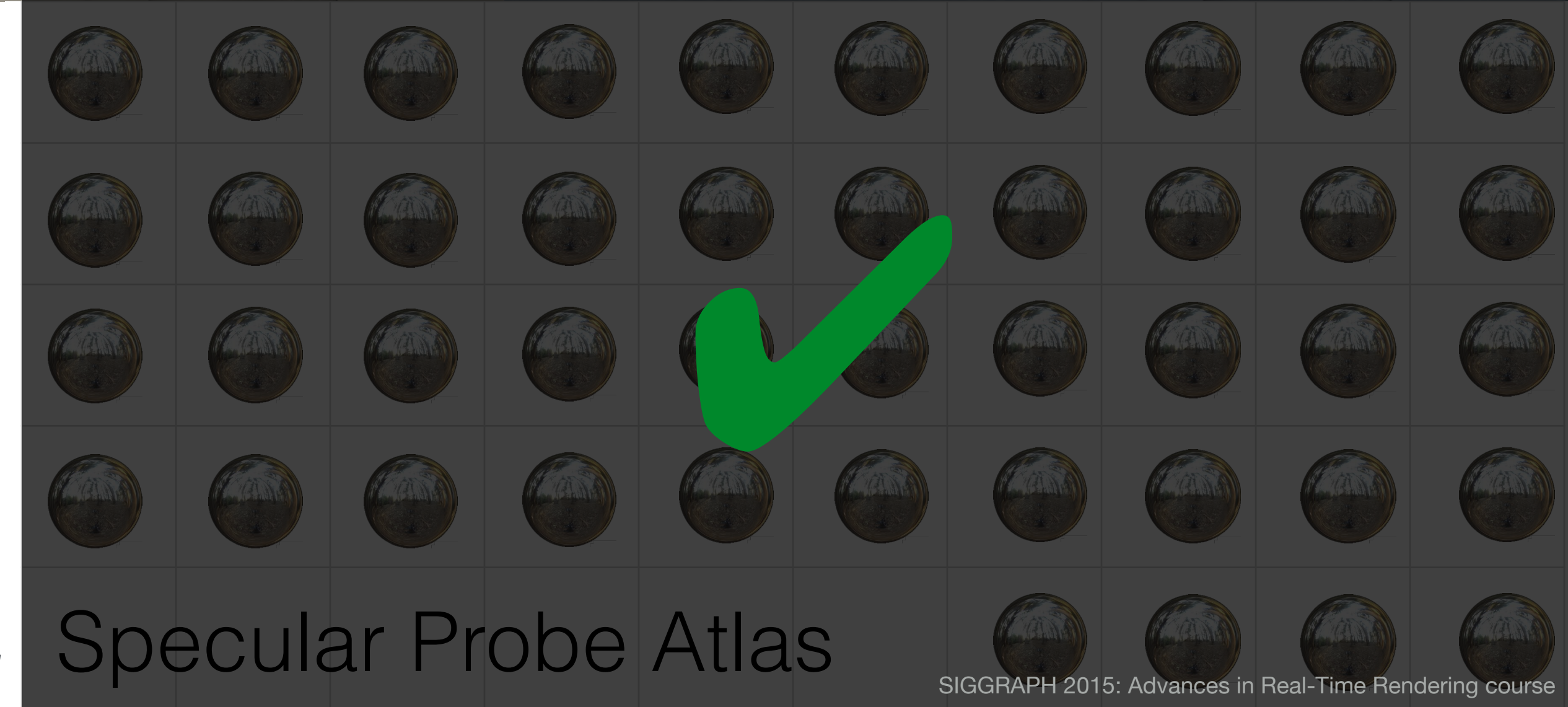
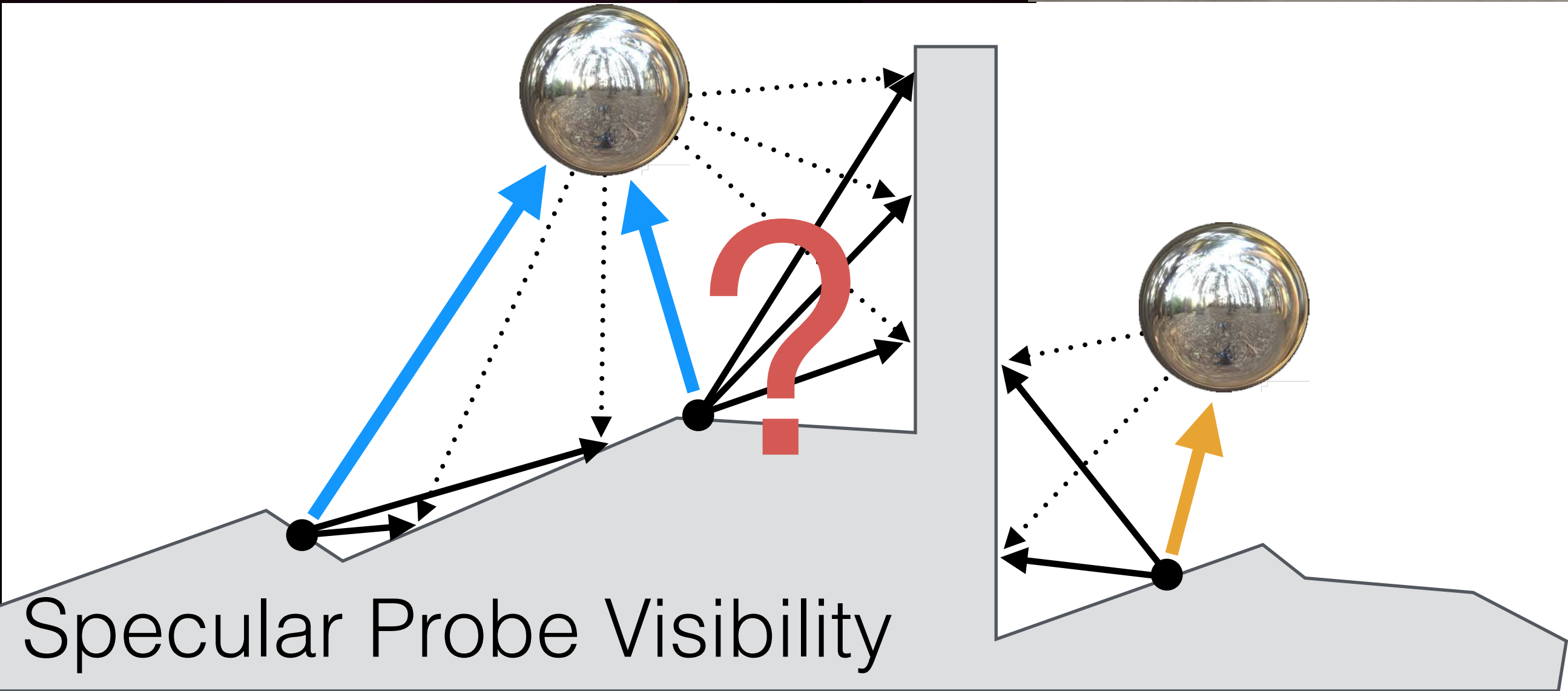
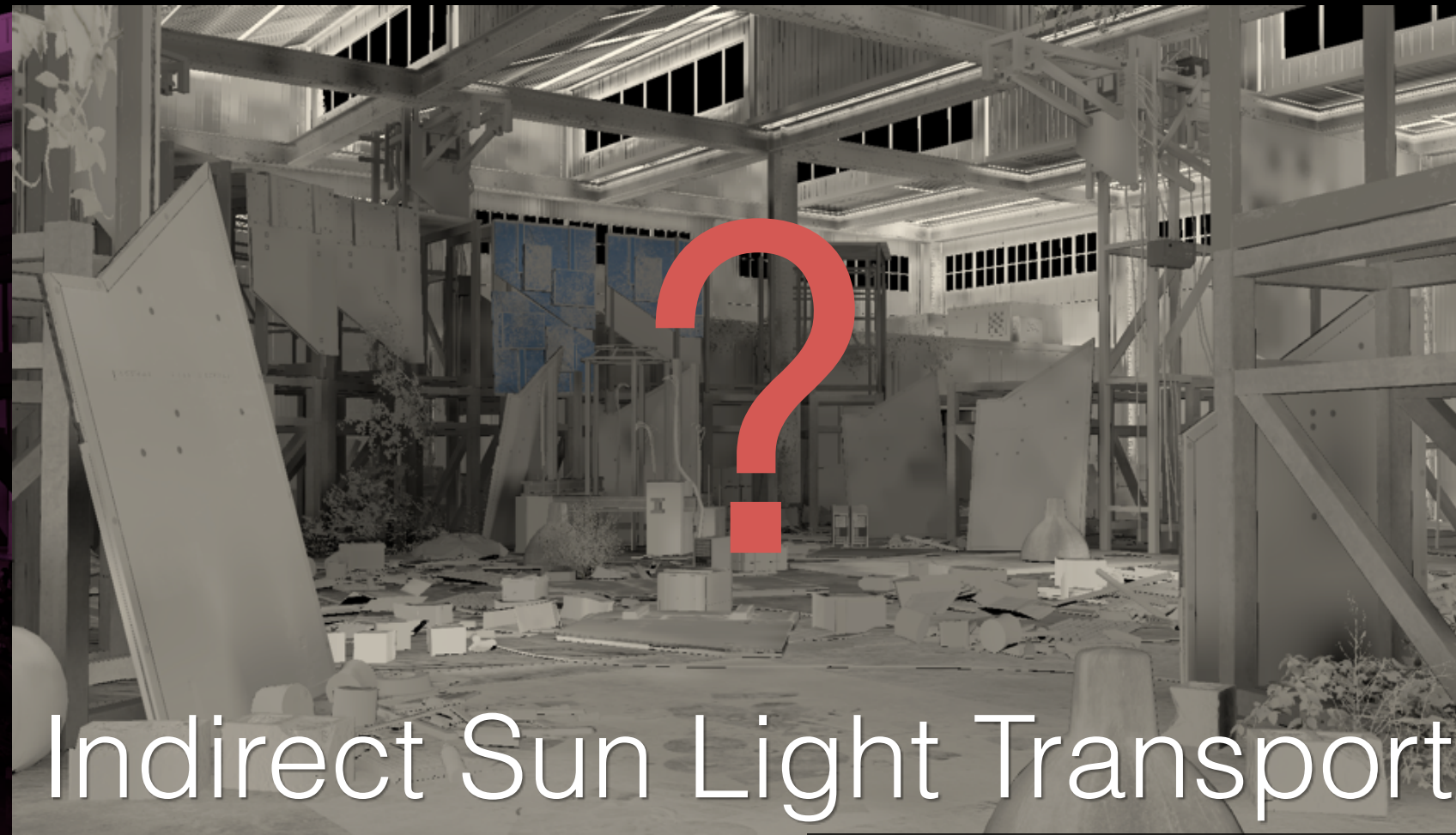
Probe Placement



Global Illumination Data



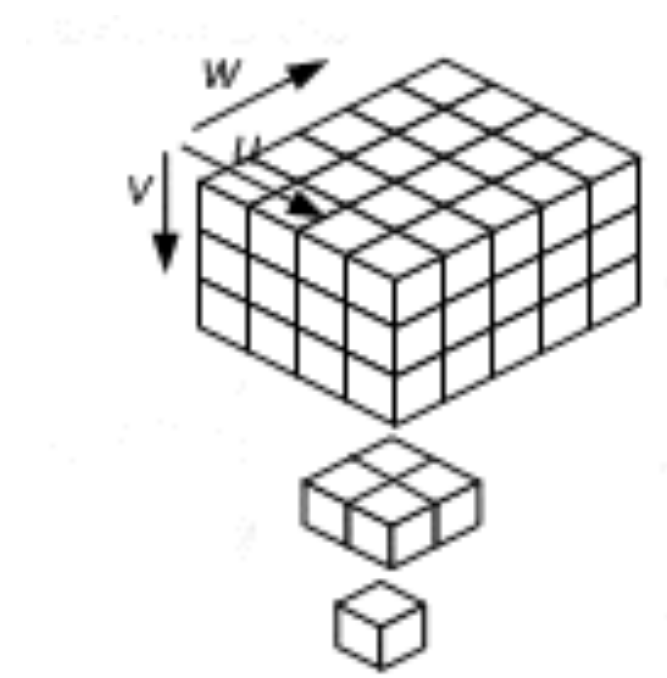
Global Illumination Data



Related Work

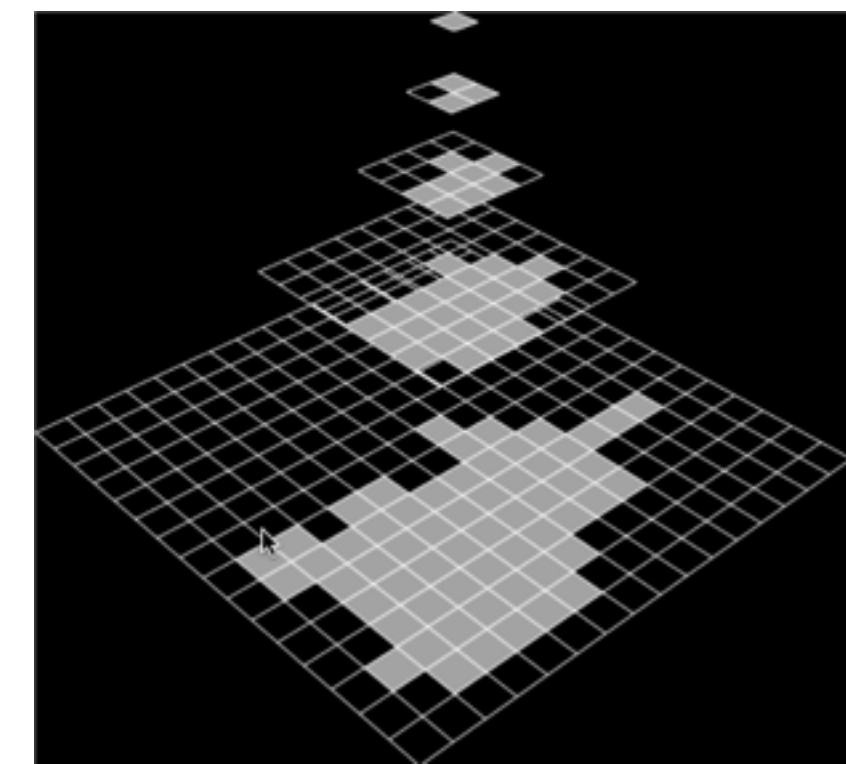
GPU Volume Textures

- Can't use native interpolation due to compression



GPU Sparse Textures

- Too large pages for fine grained tree structure
- May not be available on target platforms for future games



Related Work

Adaptive Volumetric Data Structures

- Irradiance Volumes [Greger98, Tatarchuk05]
- GigaVoxels [Crassin09]
- Sparse Voxel Octrees [Laine and Karras 2010]
- Tetrahedralization, e.g., [Cupisz12], [Bentley14], [Valient14]
- Sparse Voxel DAGs [Kämpe13]
- Open VDB [Muth13]

Adaptive Voxel Tree

Implicit spatial partitioning

Branching factor of 64

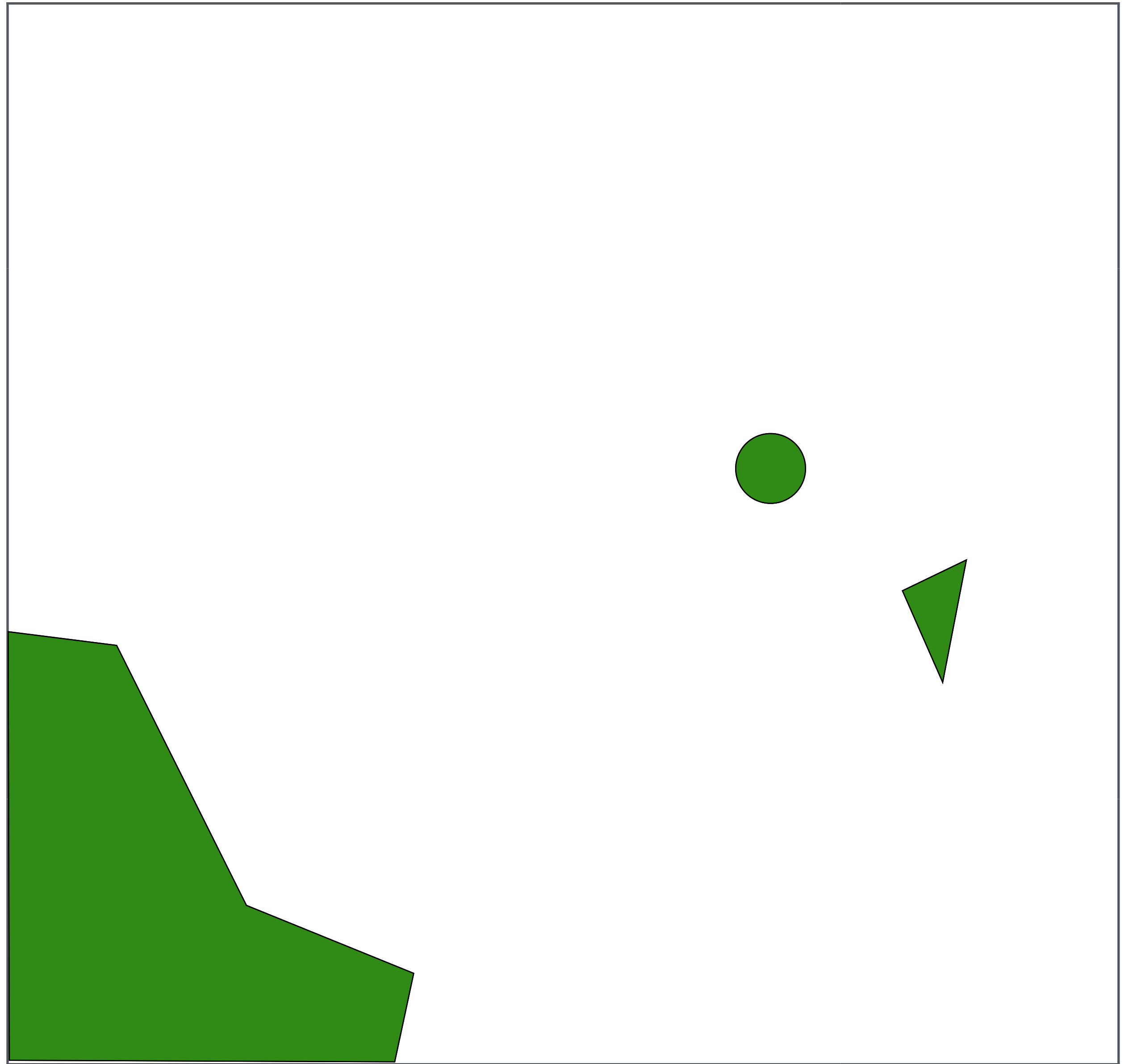
Multi-scale data

Adaptive Voxel Tree

Implicit spatial partitioning

Branching factor of 64

Multi-scale data

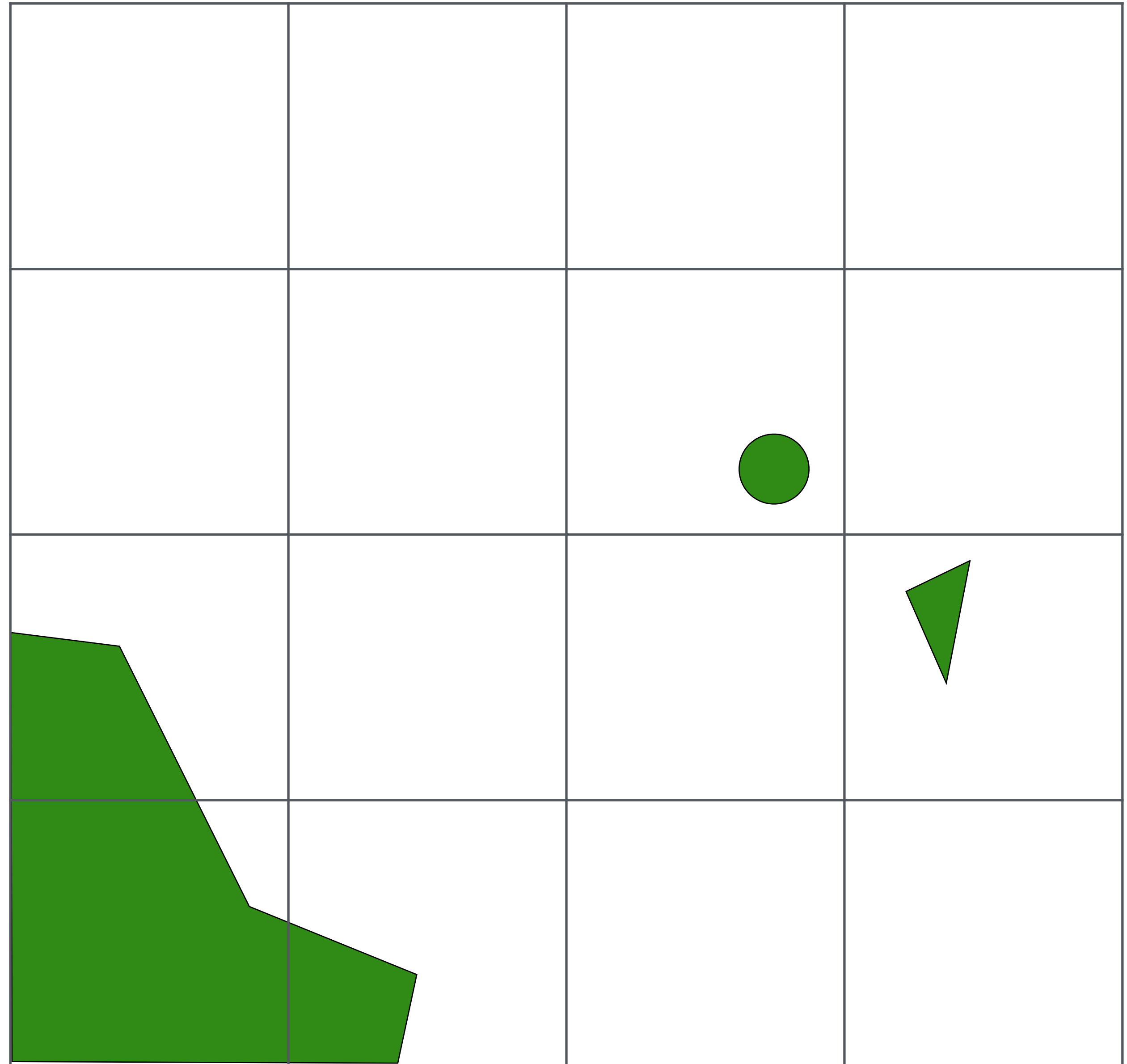


Adaptive Voxel Tree

Implicit spatial partitioning

Branching factor of 64

Multi-scale data

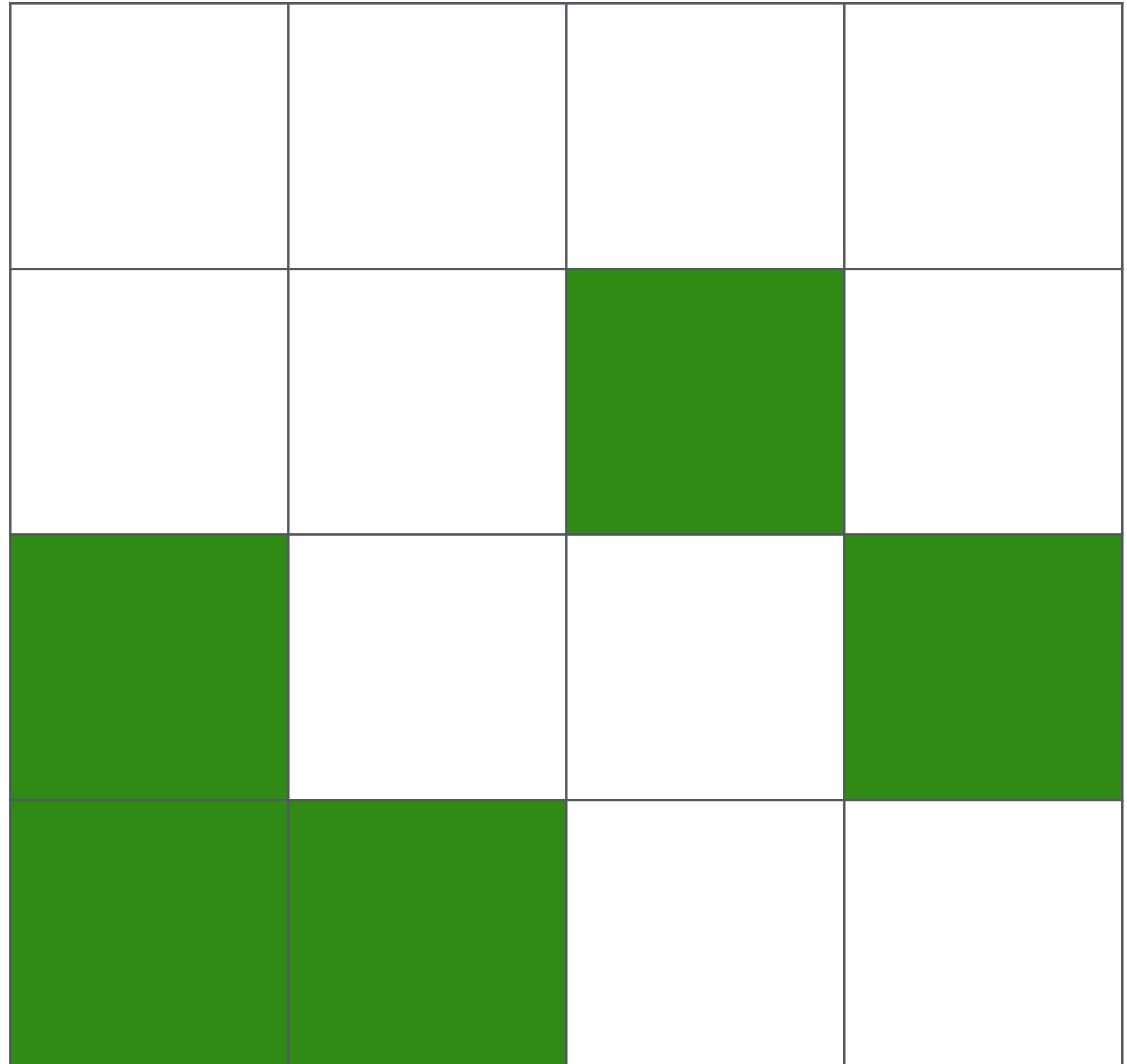


Adaptive Voxel Tree

Implicit spatial partitioning

Branching factor of 64

Multi-scale data

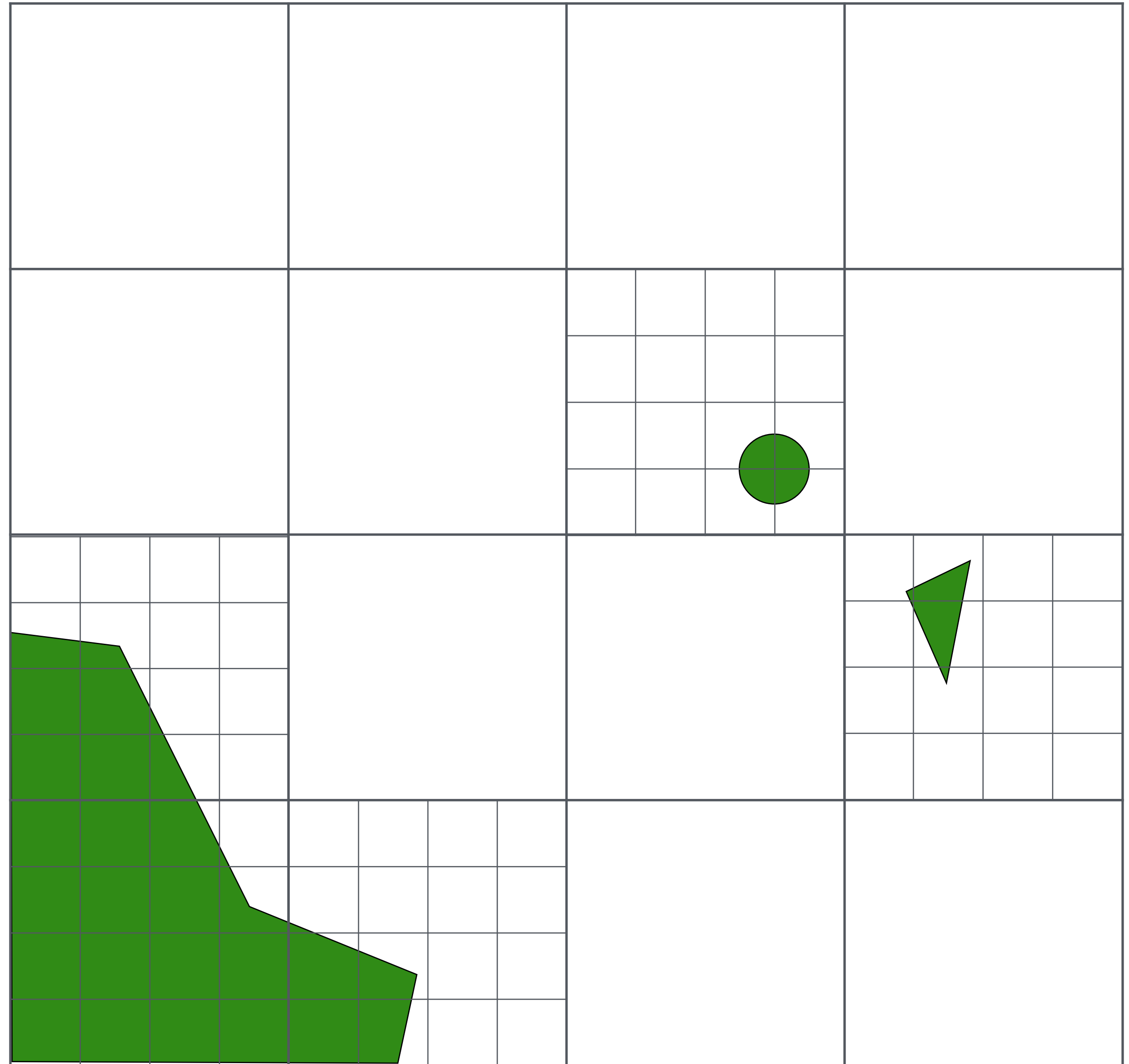


Adaptive Voxel Tree

Implicit spatial partitioning

Branching factor of 64

Multi-scale data

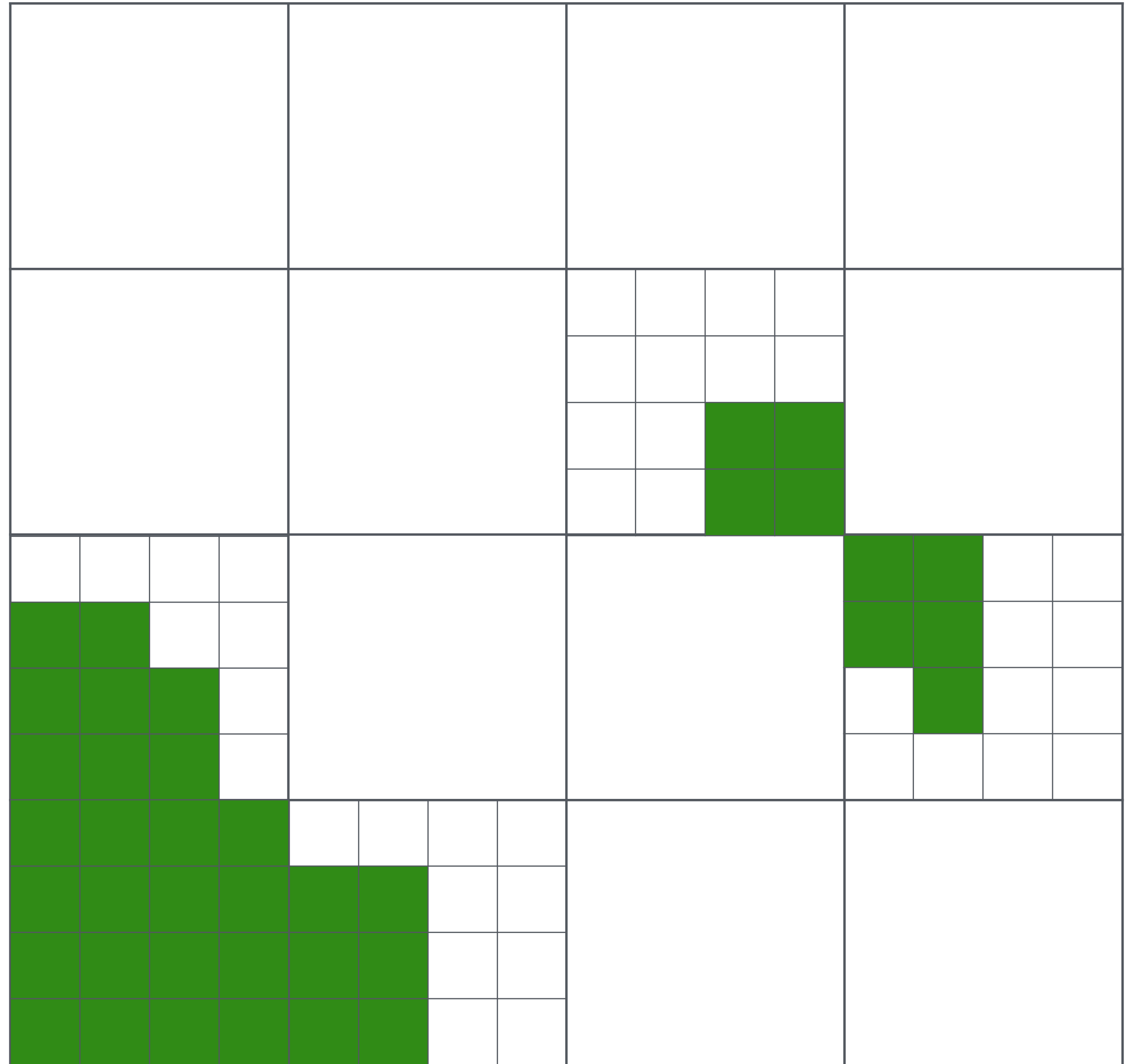


Adaptive Voxel Tree

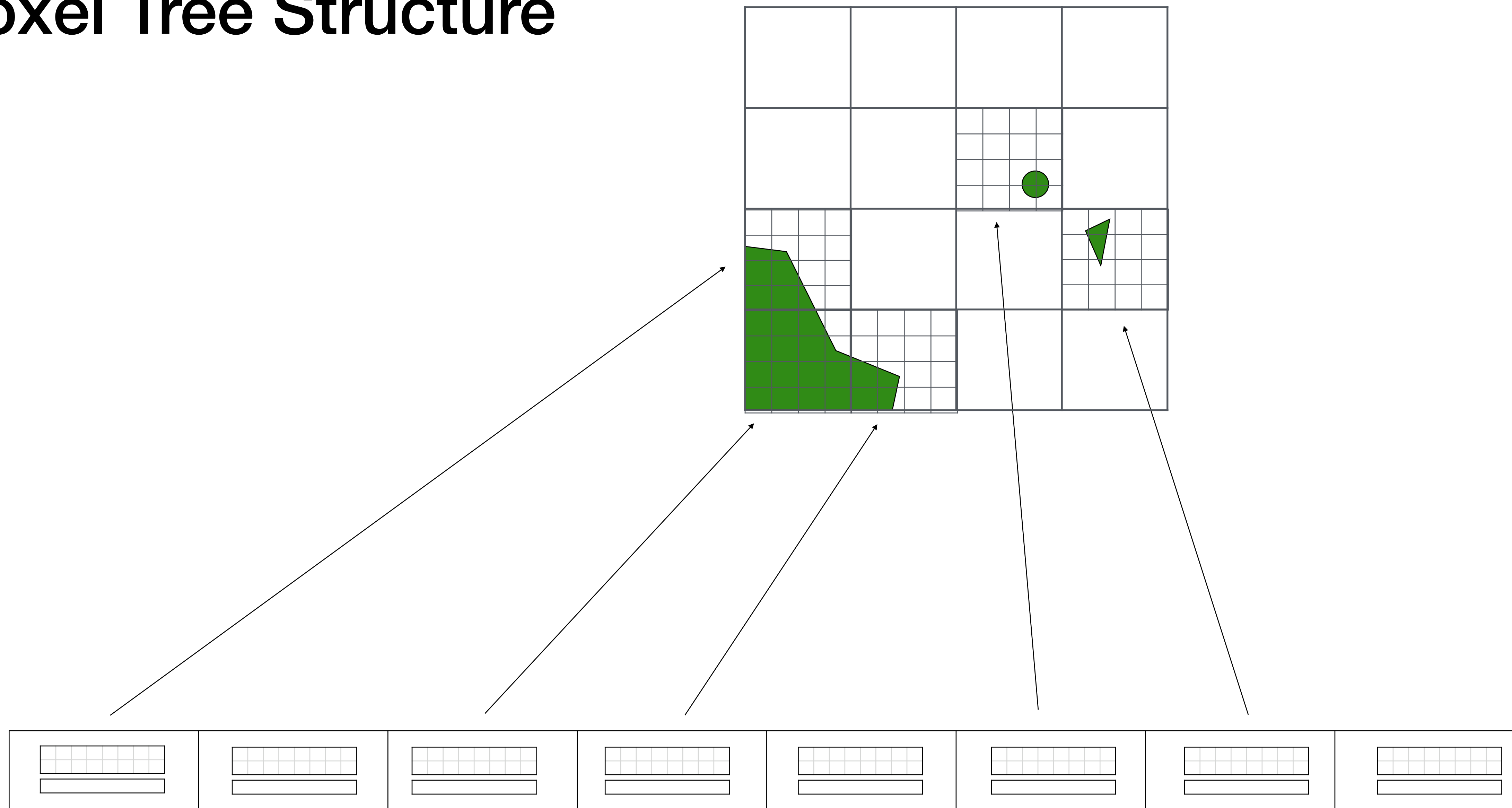
Implicit spatial partitioning

Branching factor of 64

Multi-scale data



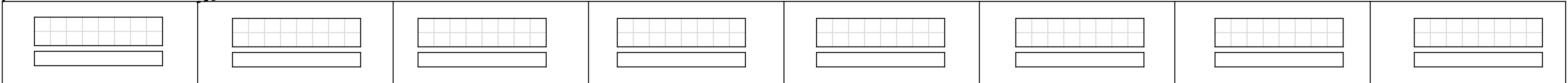
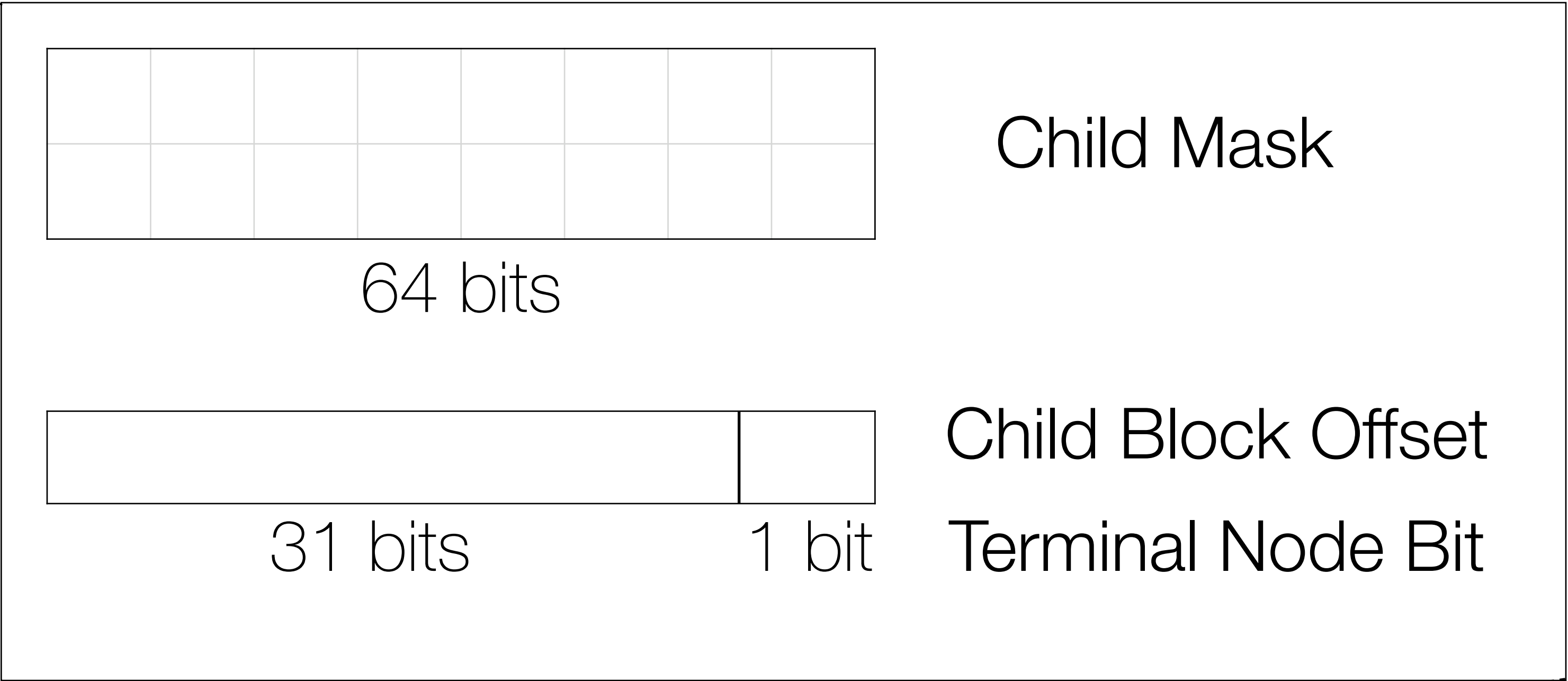
Voxel Tree Structure



Voxel Node Array

Node Structure

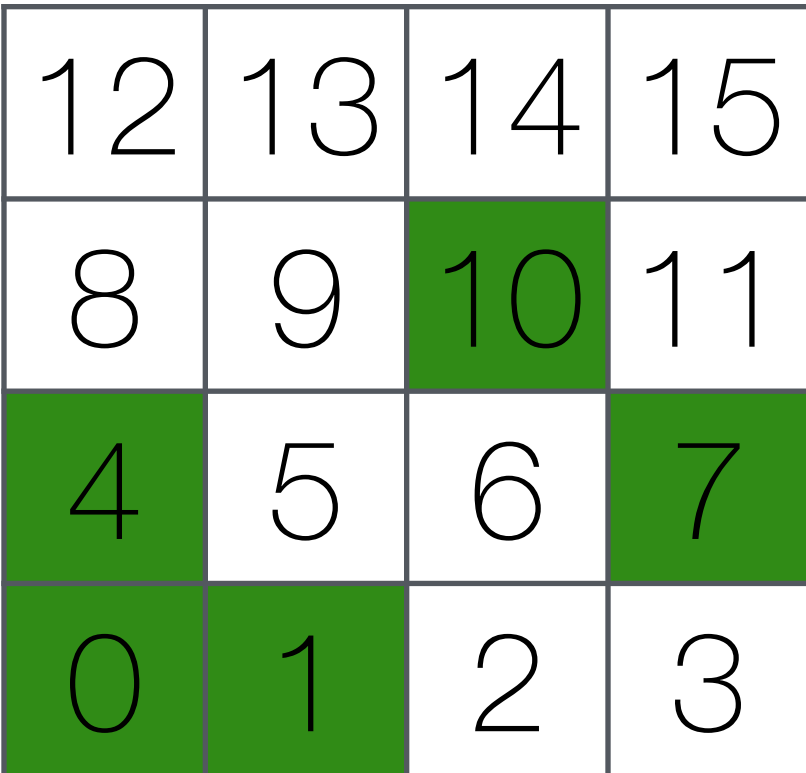
Node Structure



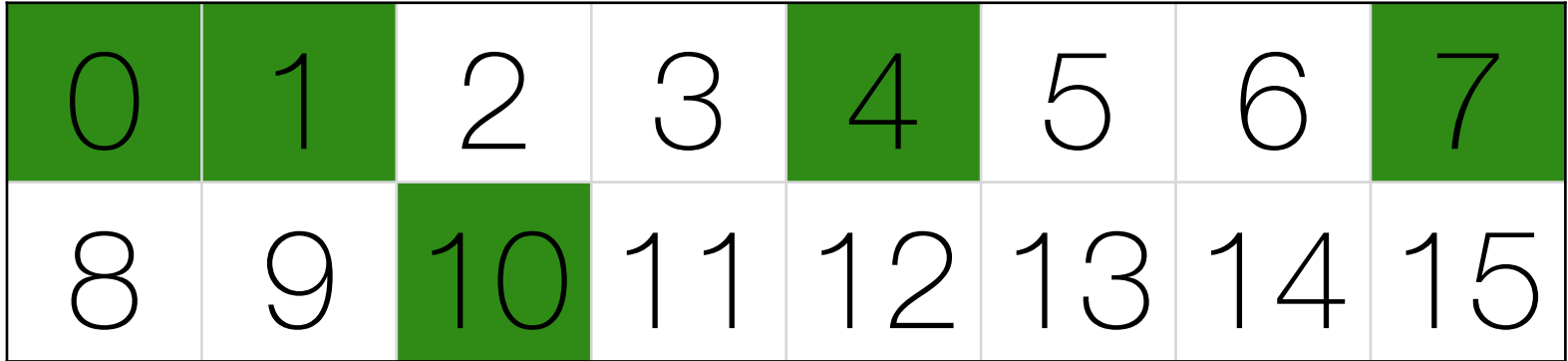
Voxel Node Array

Child Mask

Node Structure



Voxel Grid



64 bits

Child Mask

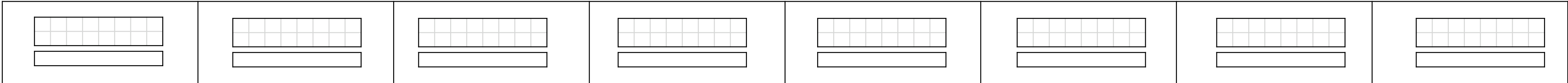


31 bits

1 bit

Child Block Offset

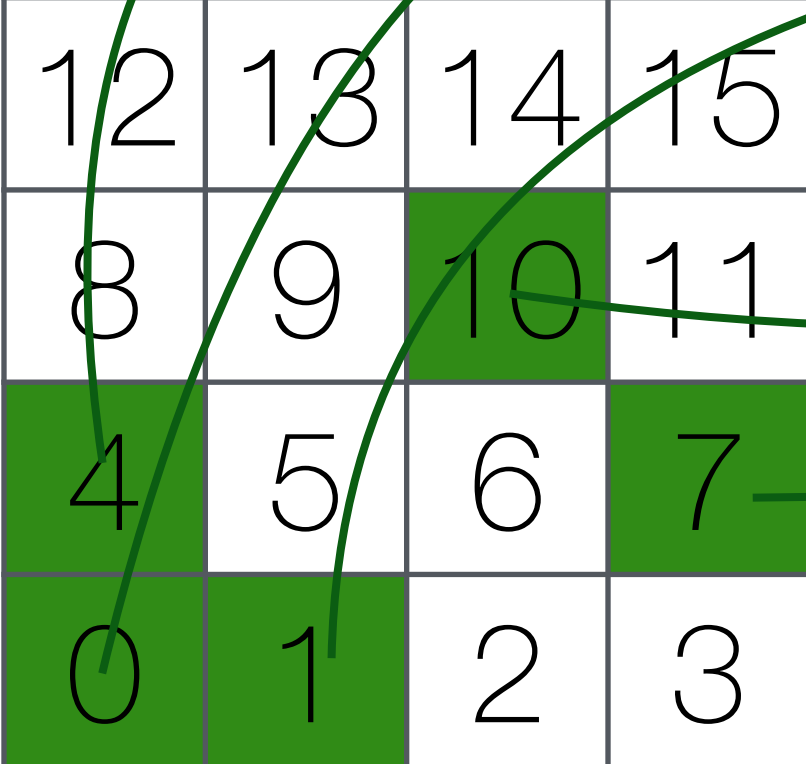
Terminal Node Bit



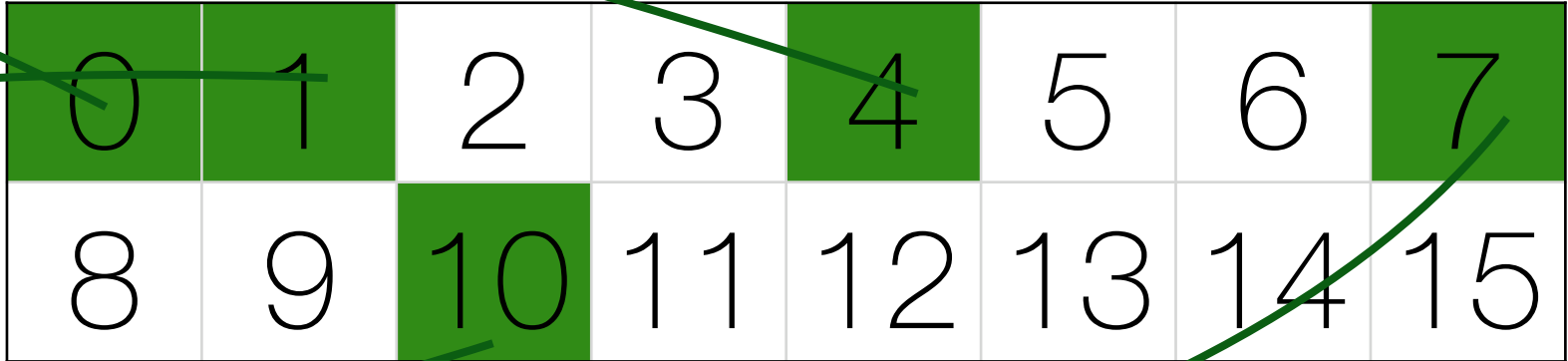
Voxel Node Array

Child Mask

Node Structure



Voxel Grid



Child Mask

64 bits

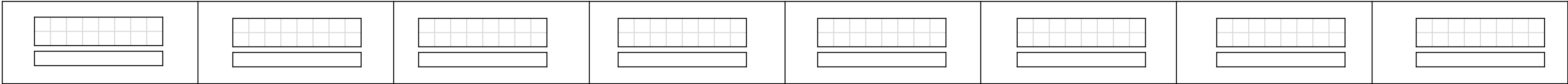


31 bits

1 bit

Child Block Offset

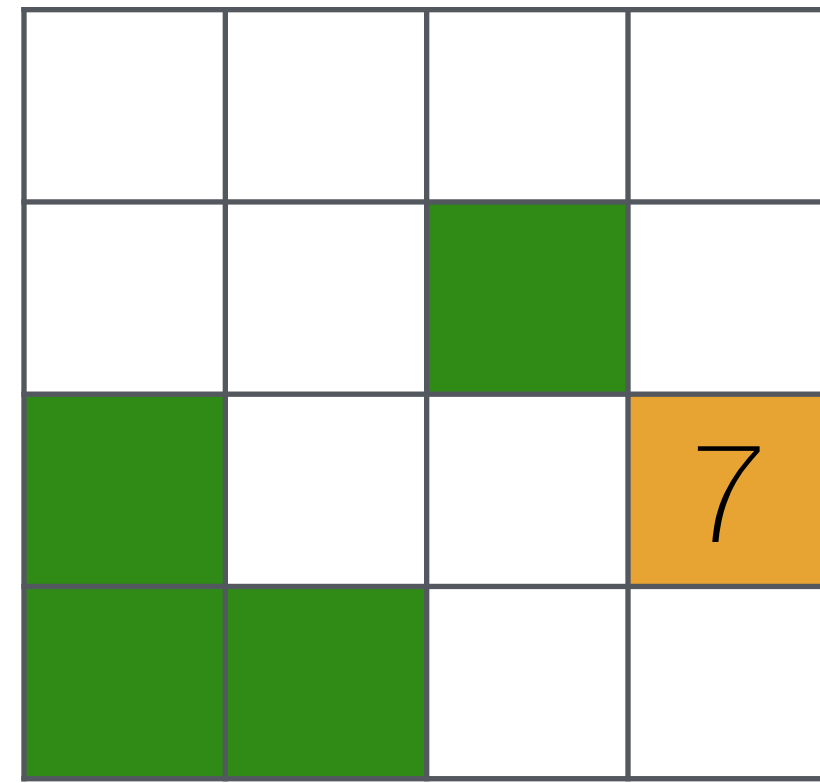
Terminal Node Bit



Voxel Node Array

Tree Traversal

Node Structure



Voxel Grid



64 bits

Child Mask



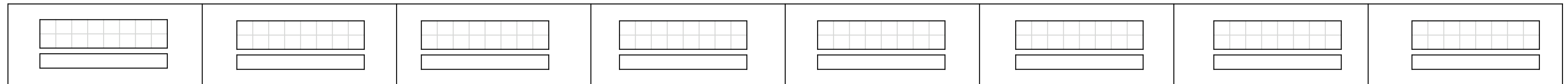
31 bits

1 bit

Child Block Offset

Terminal Node Bit

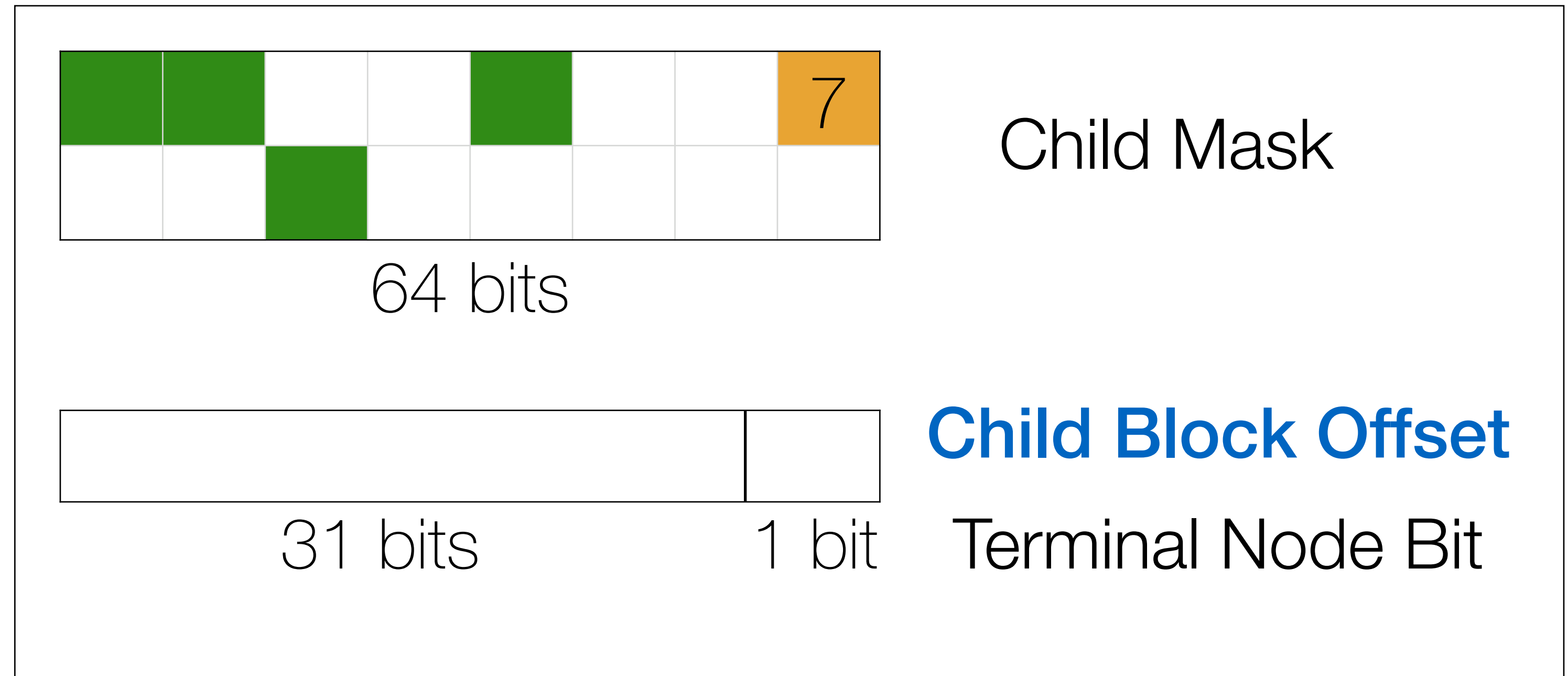
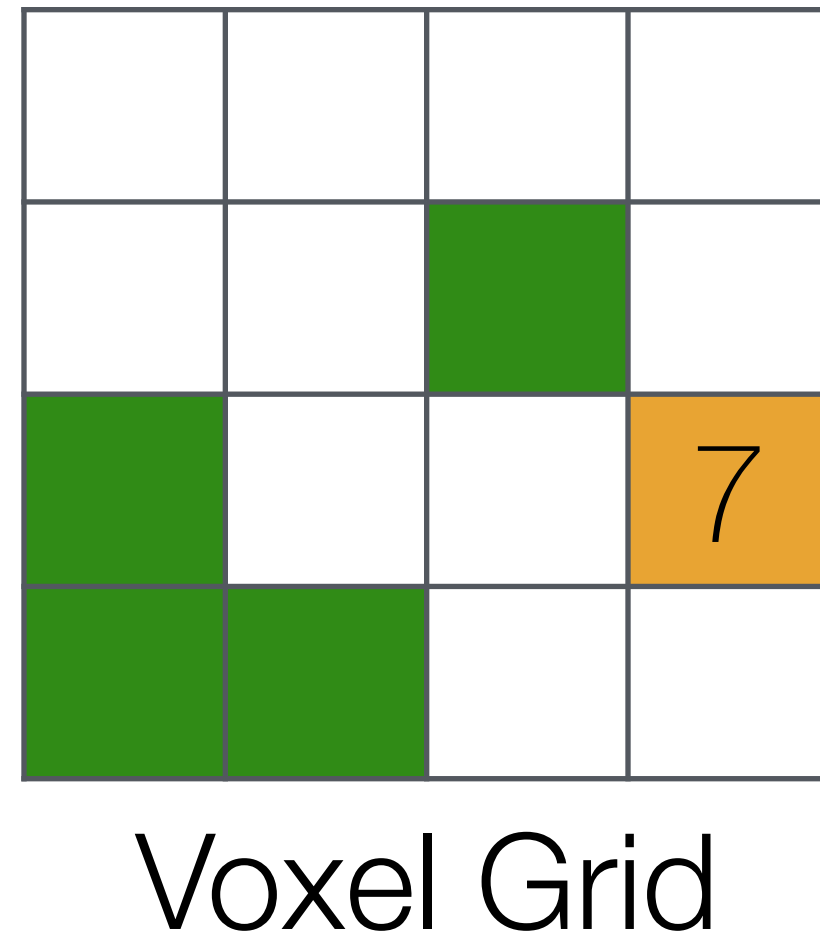
Child Index = ?



Voxel Node Array

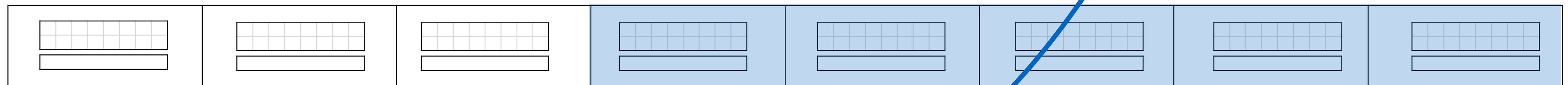
Tree Traversal

Node Structure



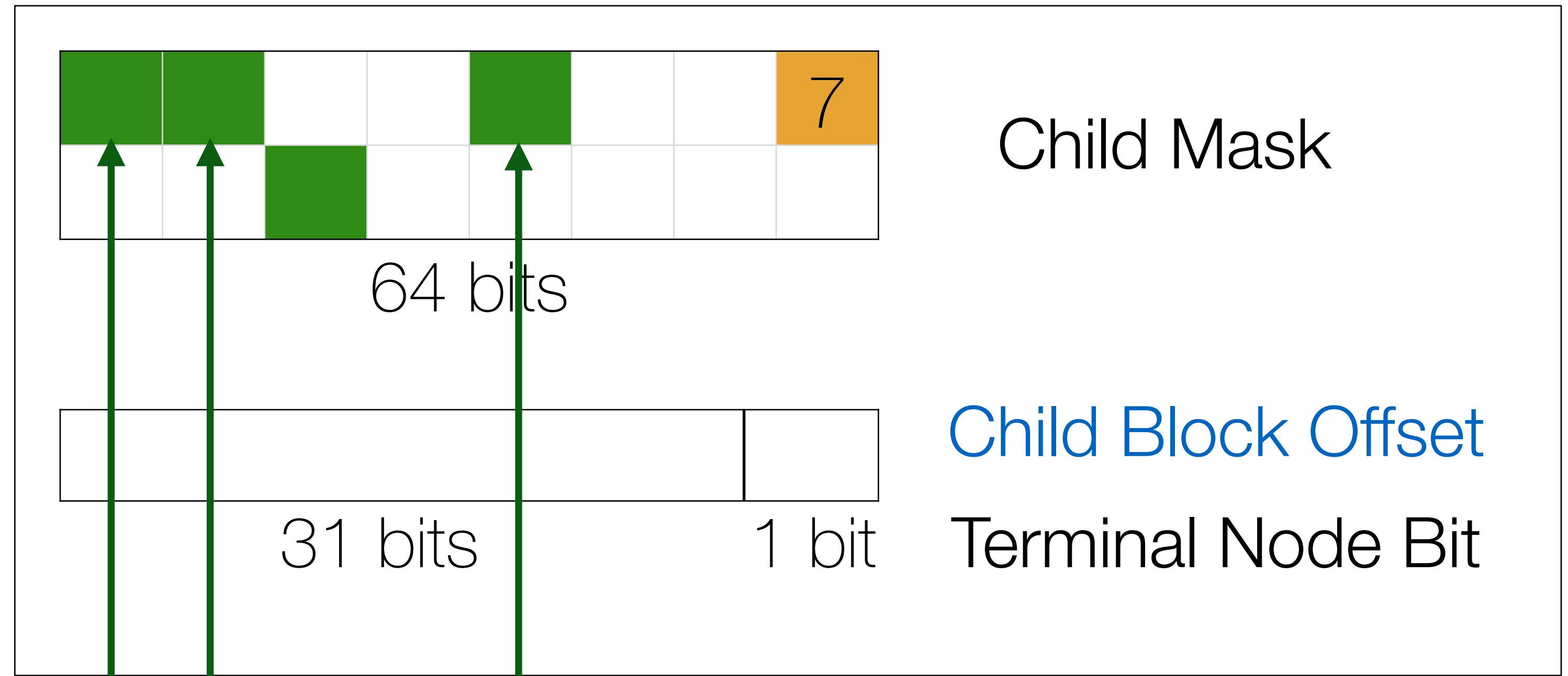
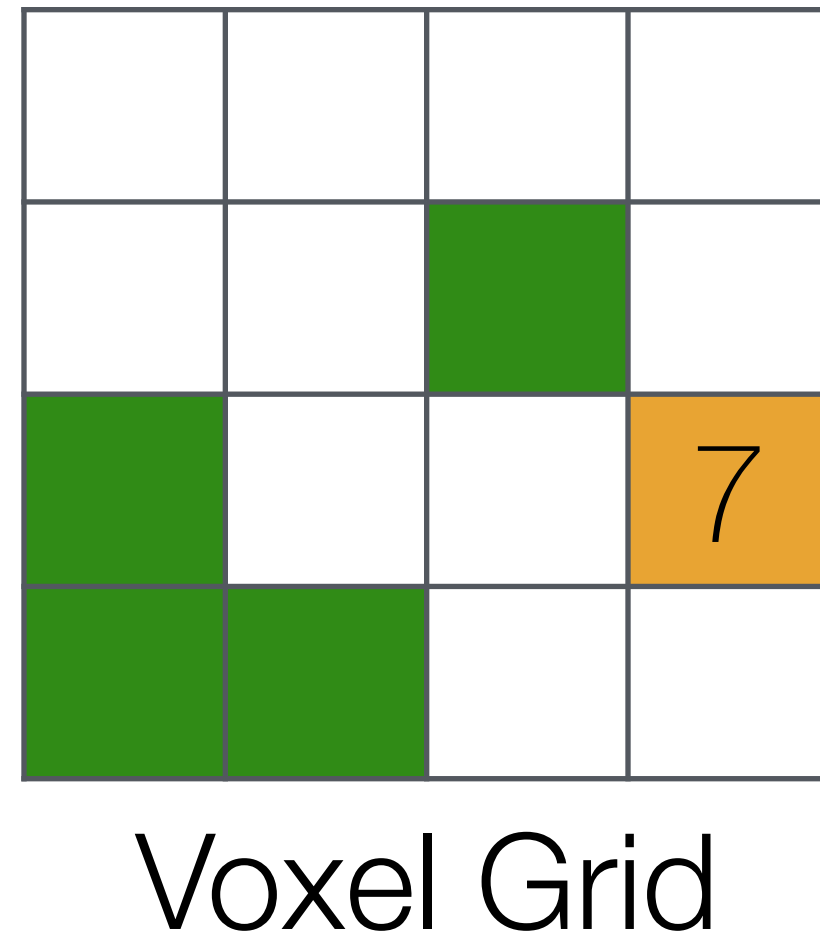
Child Index =

+ Child Block Offset

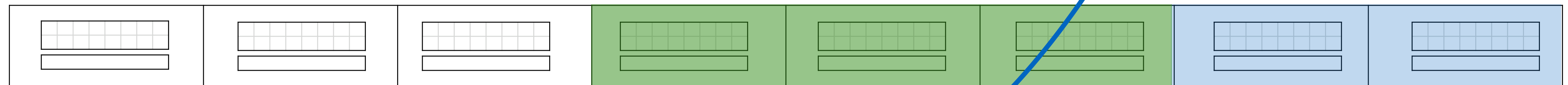


Tree Traversal

Node Structure

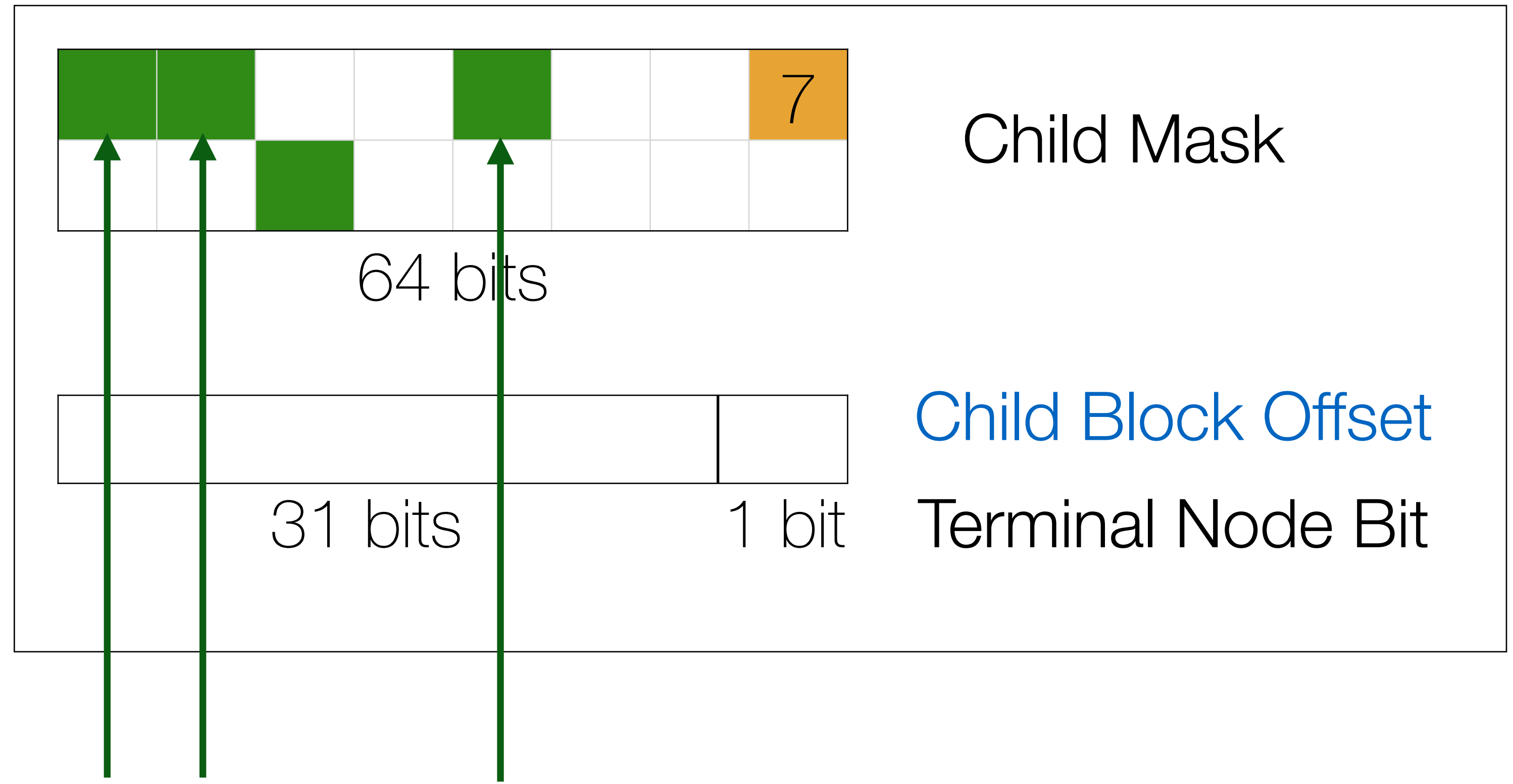
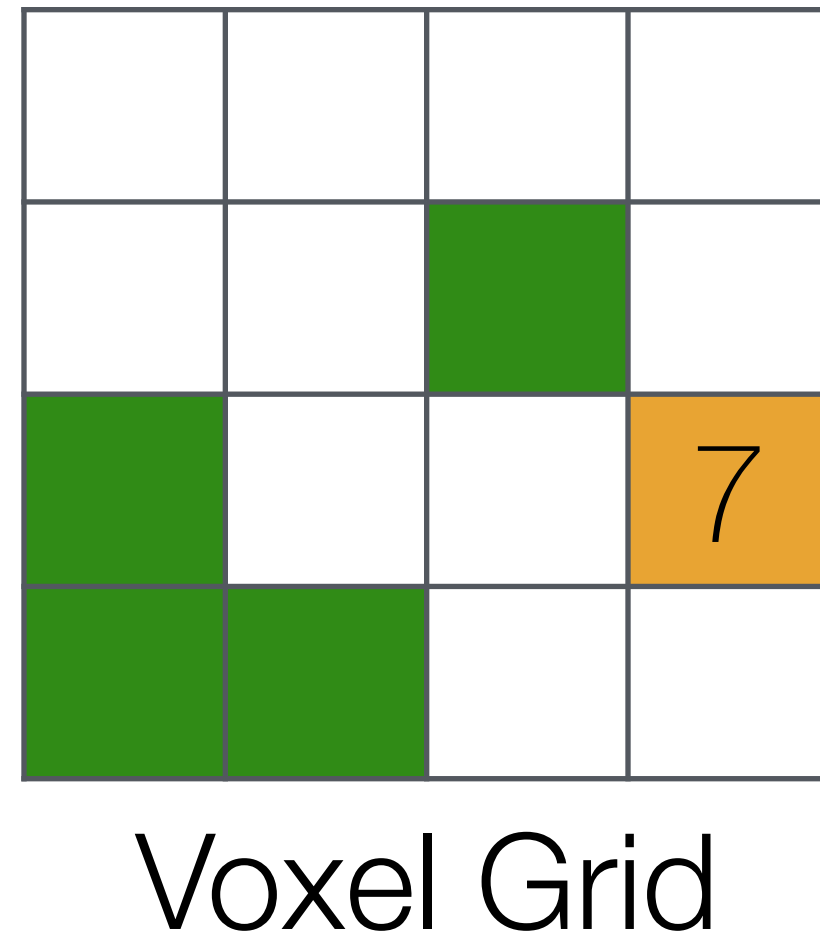


Child Index = **3 set bits** + Child Block Offset



Tree Traversal

Node Structure

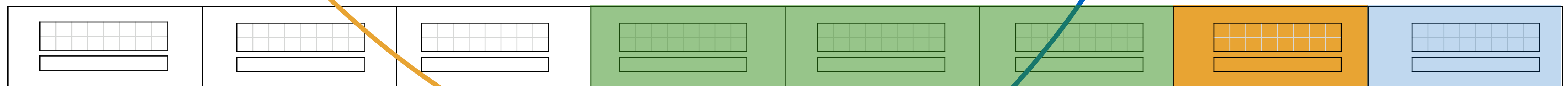


Child Index =

3 set bits

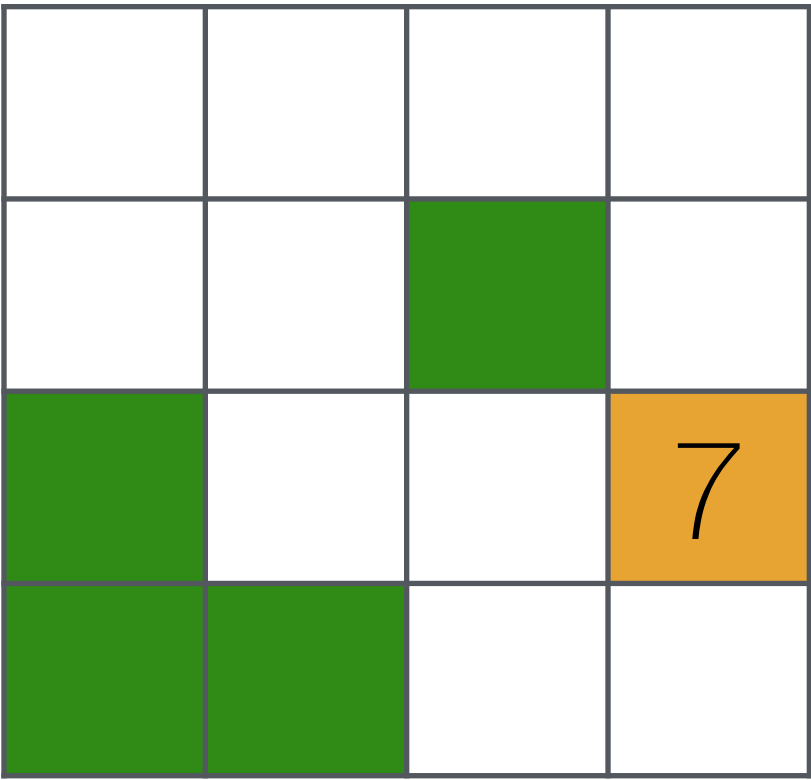
+

Child Block Offset

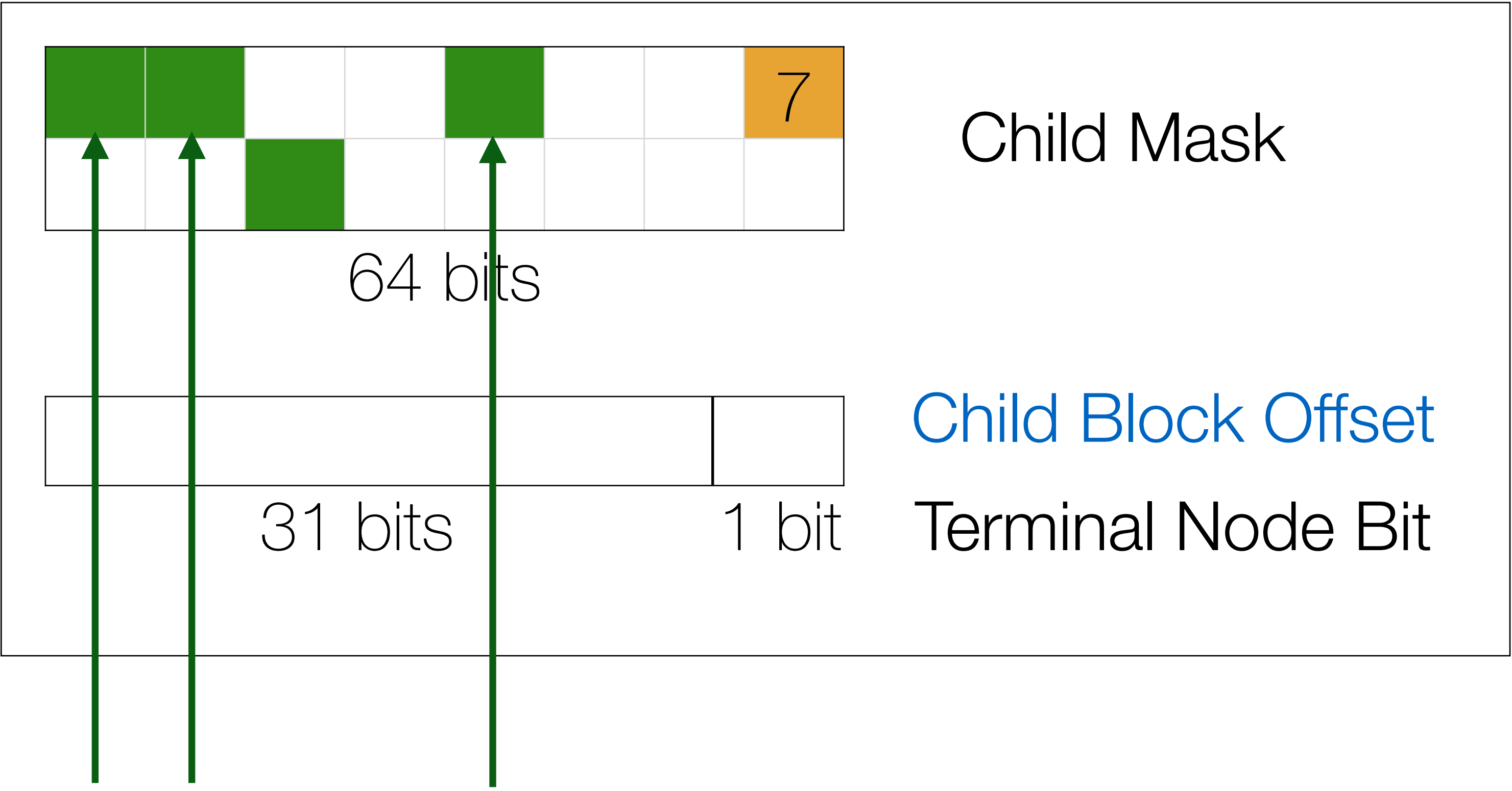


Payload Data

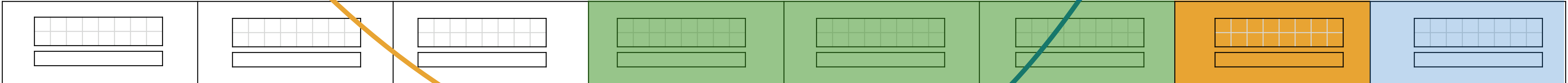
Node Structure



Voxel Grid






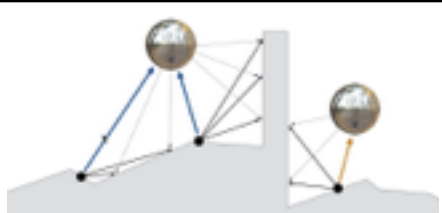
Payload Index = Child Index = 3 set bits + Child Block Offset

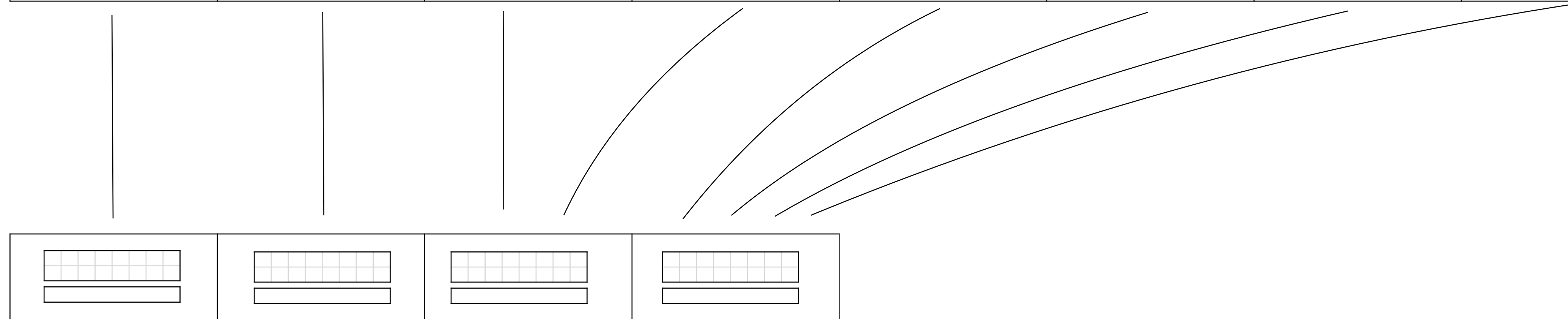


Voxel Node Array

Payload Data



Local Light Irradiance					
Indirect Sun Light Transport					
Sky Light Transport					
Specular Probe Visibility					



Voxel Node Array

What About Leaf Nodes?

Leaf nodes are **implicit**: they only show up in the child masks of their parent voxels

Compact trees encoding only the **topology**

Only a **few hundred kilobytes** for an entire level

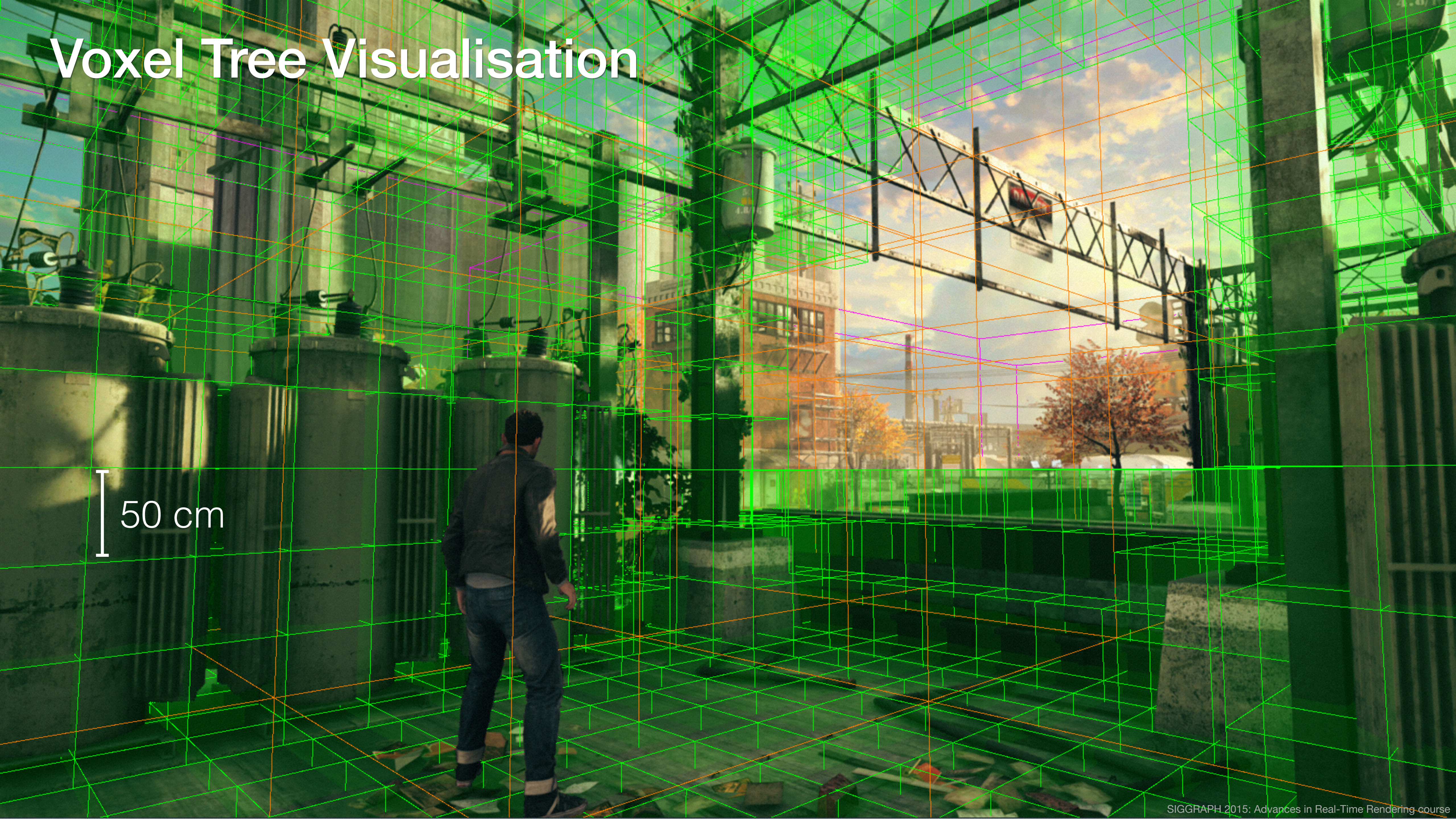
First Level Lookup

First level of the tree can have **arbitrary** dimensions

We use a **dense** grid of 8x8x8 meter cells to guarantee coverage for large dynamic objects

Voxel Tree Visualisation

50 cm

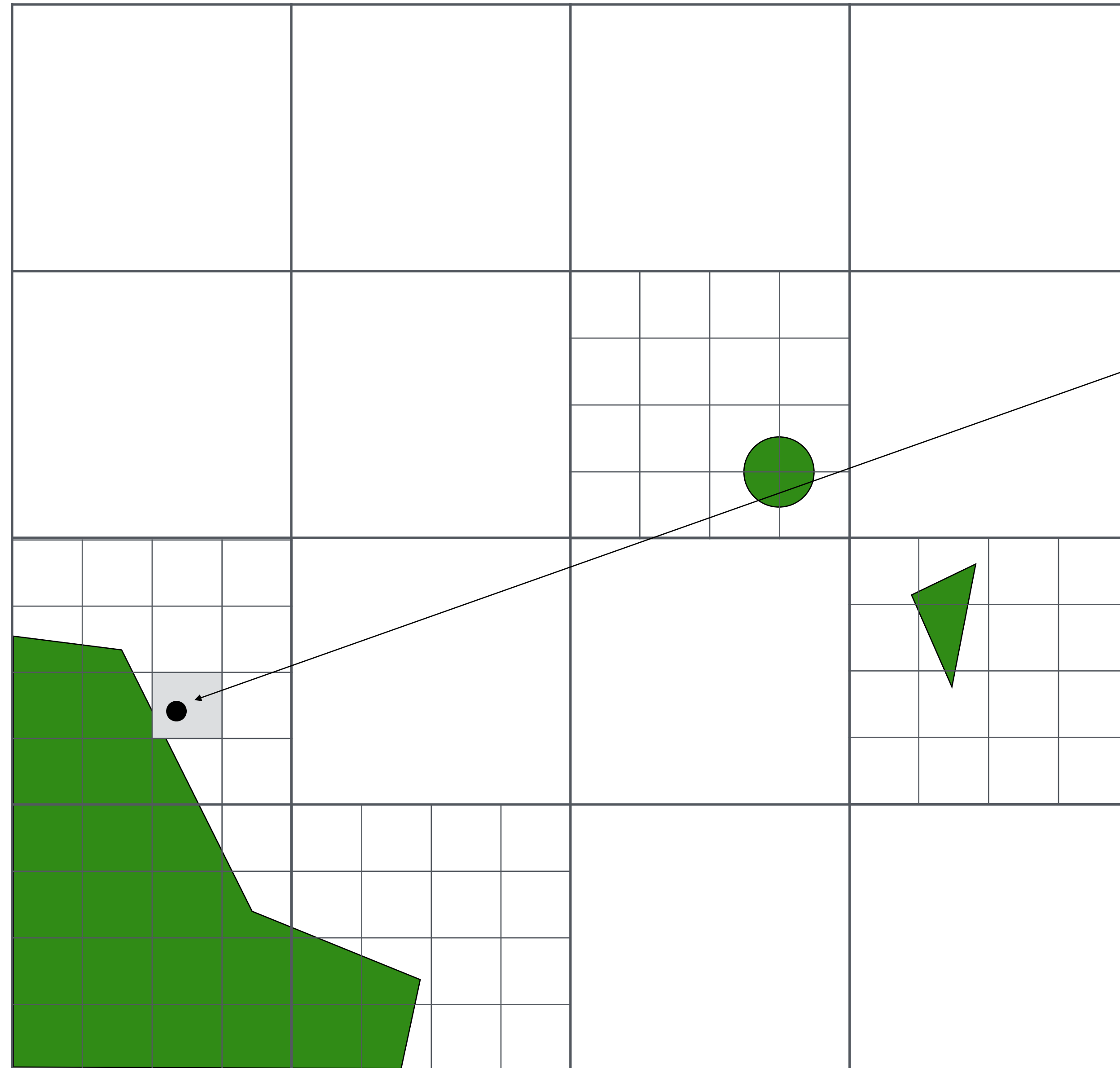


Seamless Interpolation

Dynamic and static objects lit by **same** data

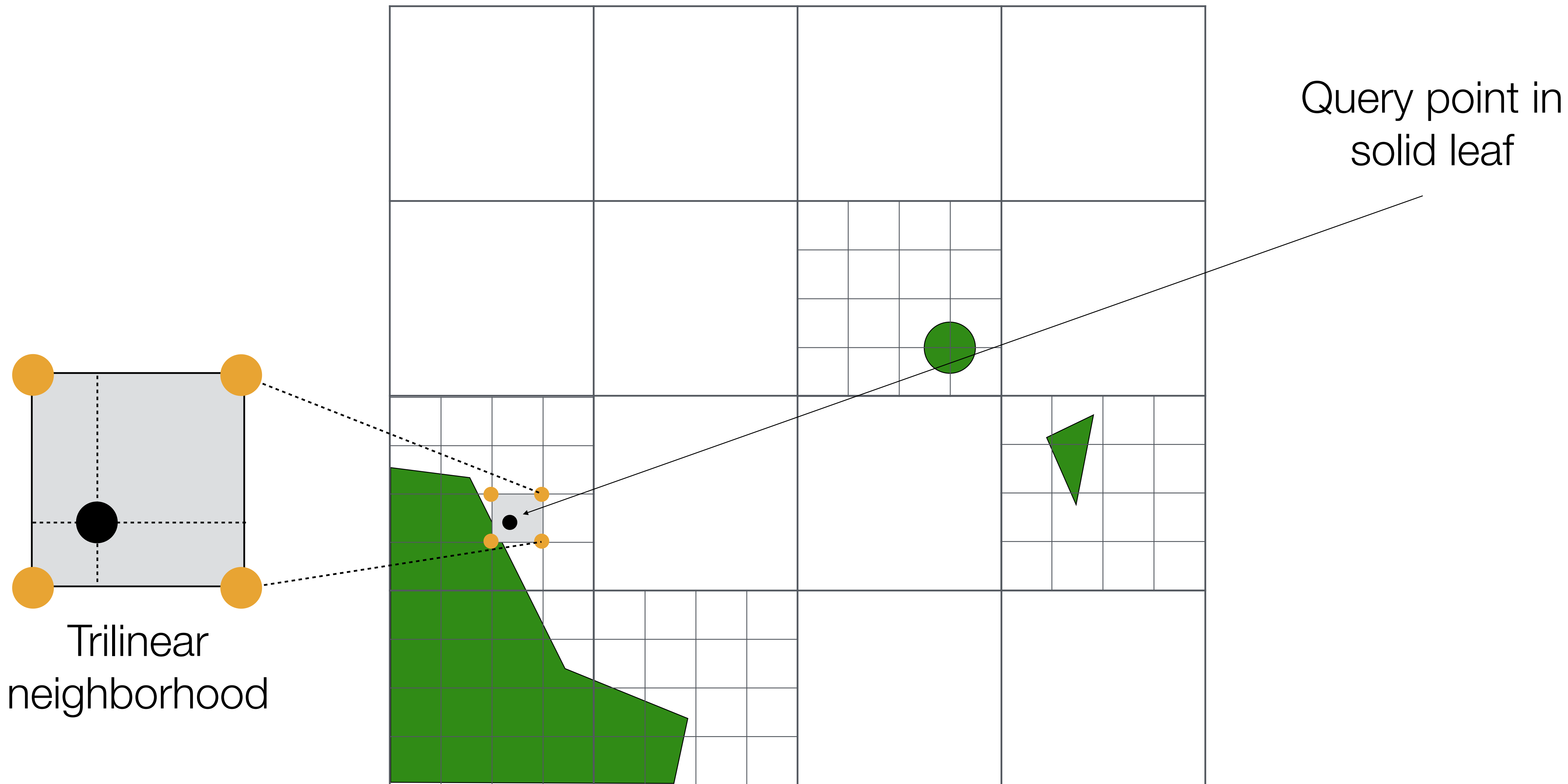
Need **seamless** interpolation everywhere

Seamless Interpolation



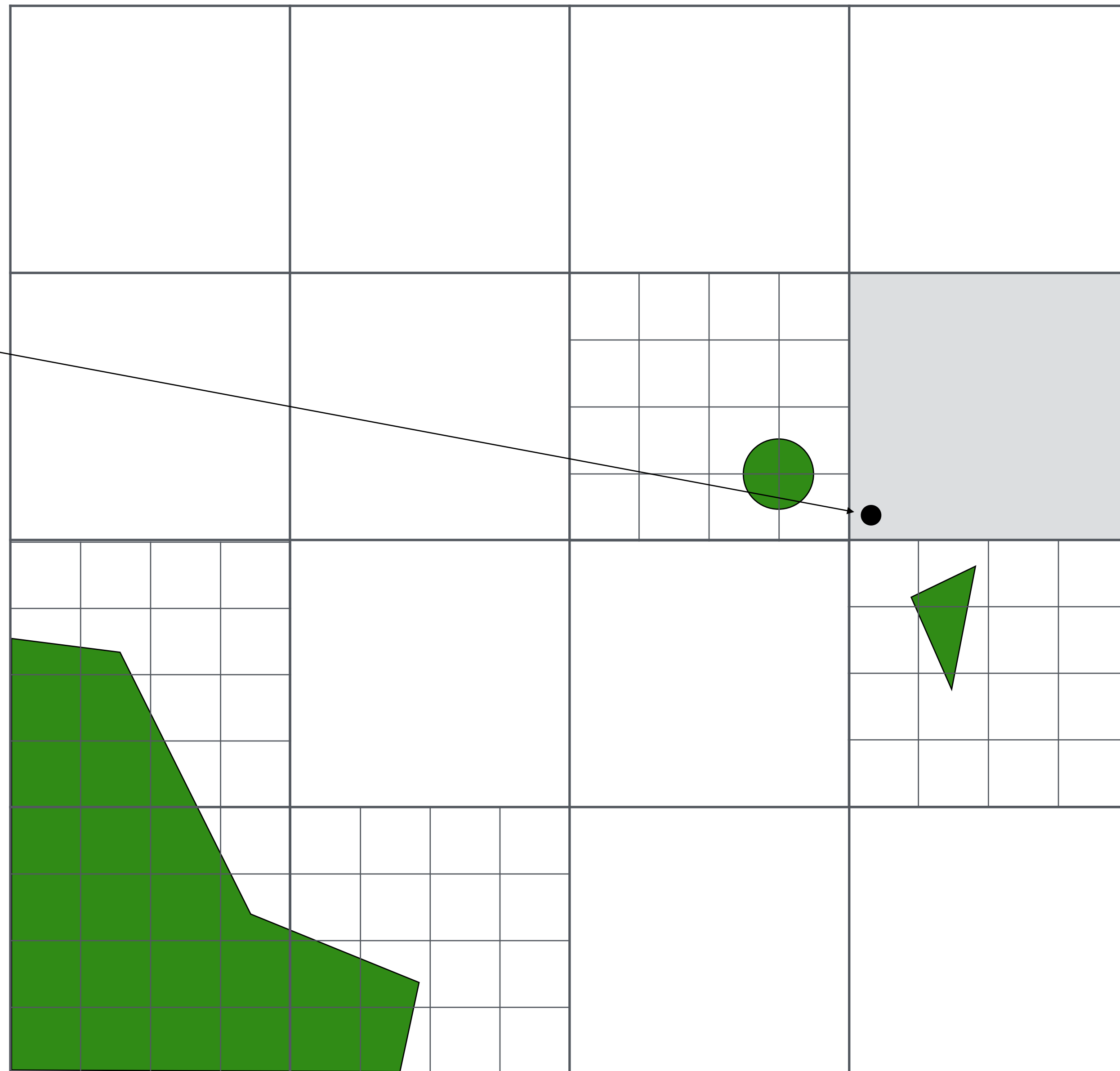
Query point in
solid leaf

Seamless Interpolation



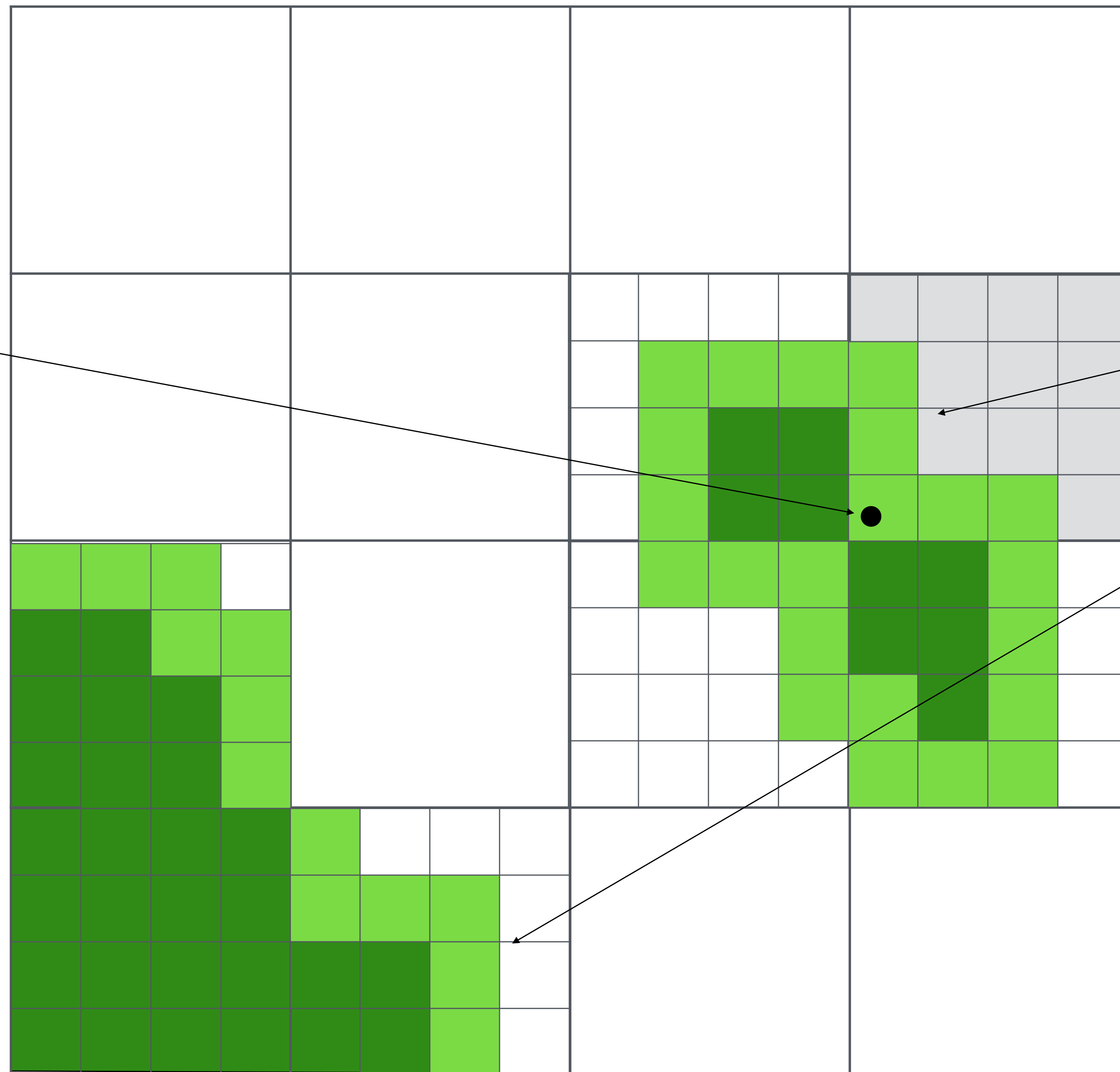
Seamless Interpolation

Query point in
empty leaf



Seamless Interpolation

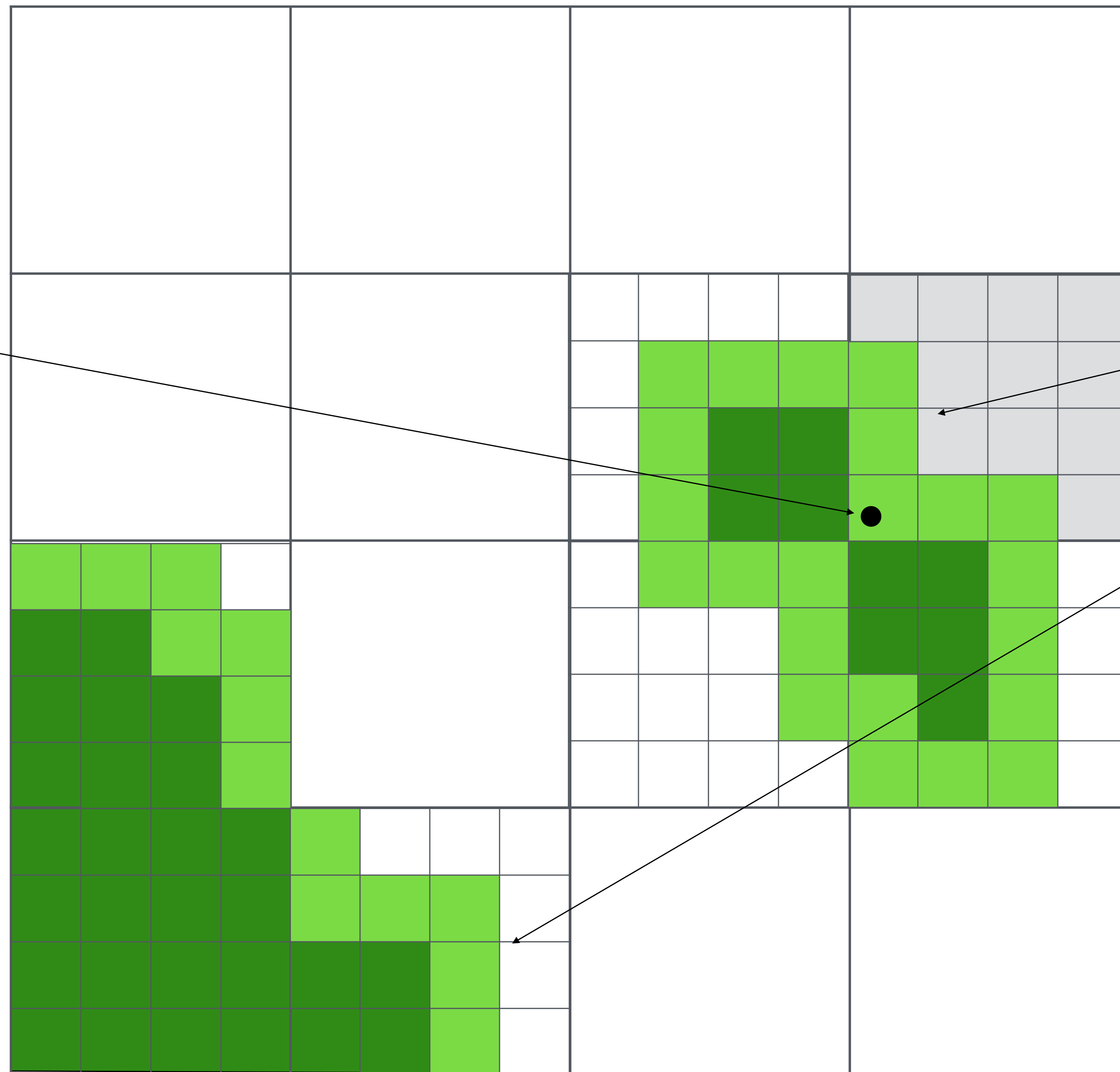
Query point in empty leaf



Use **dilated** tree?

Seamless Interpolation

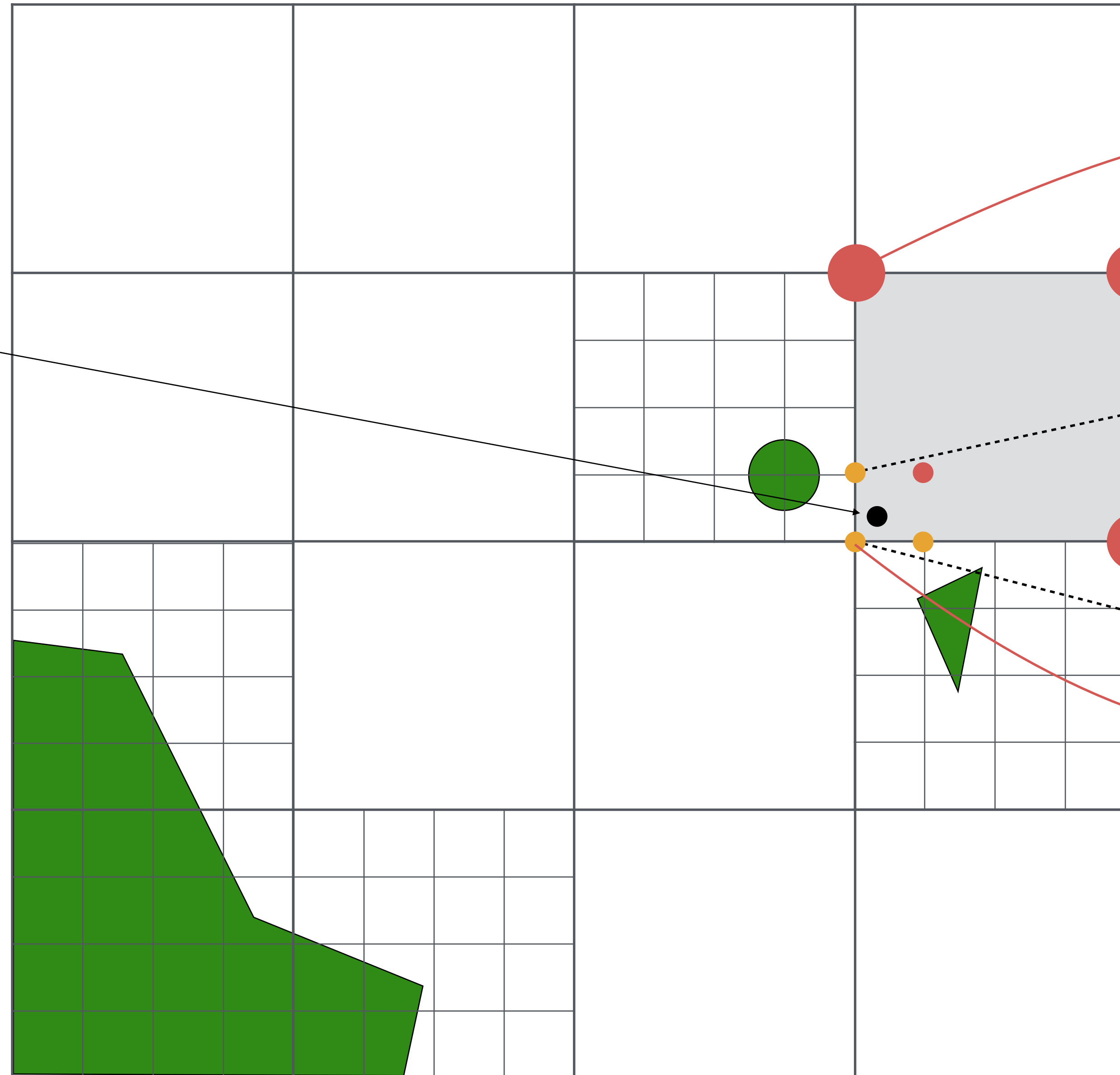
Query point in empty leaf



~~Use dilated tree?~~

Seamless Interpolation

Query point in empty leaf



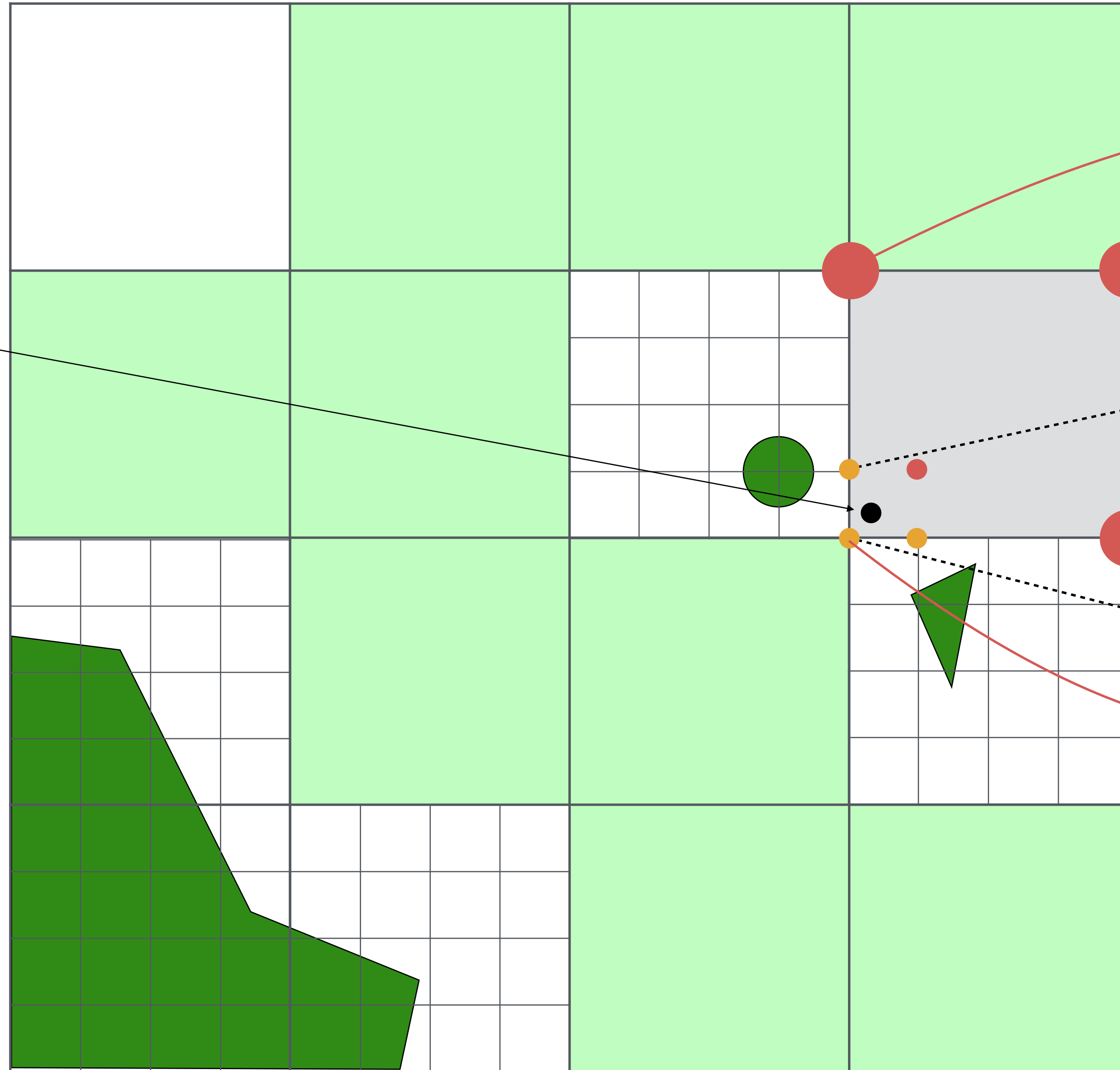
Interpolate from parent node

Trilinear neighborhood

Seamless Interpolation

Query point in empty leaf

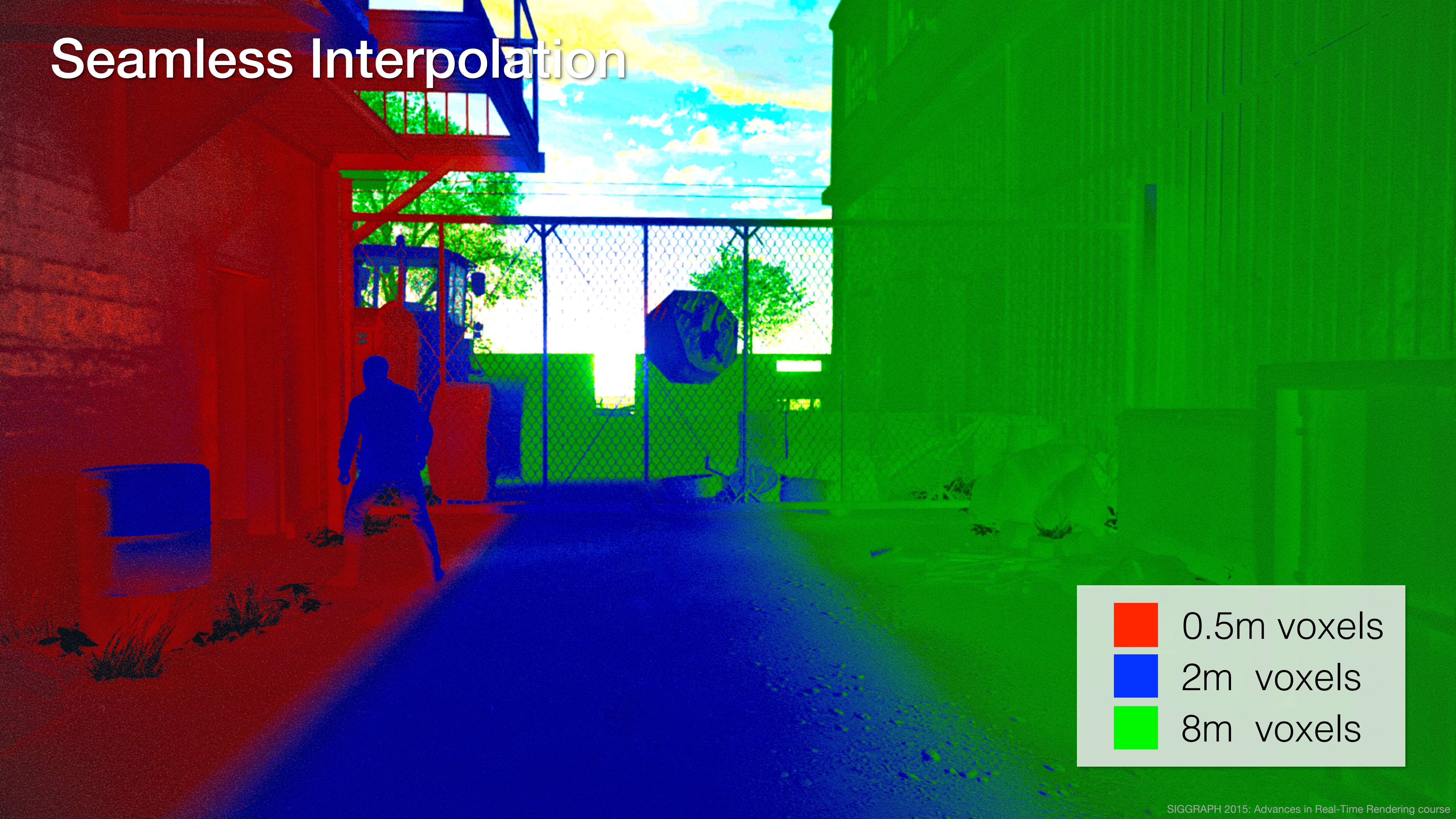
Apply partial dilation to **avoid recursion**



Interpolate from parent node

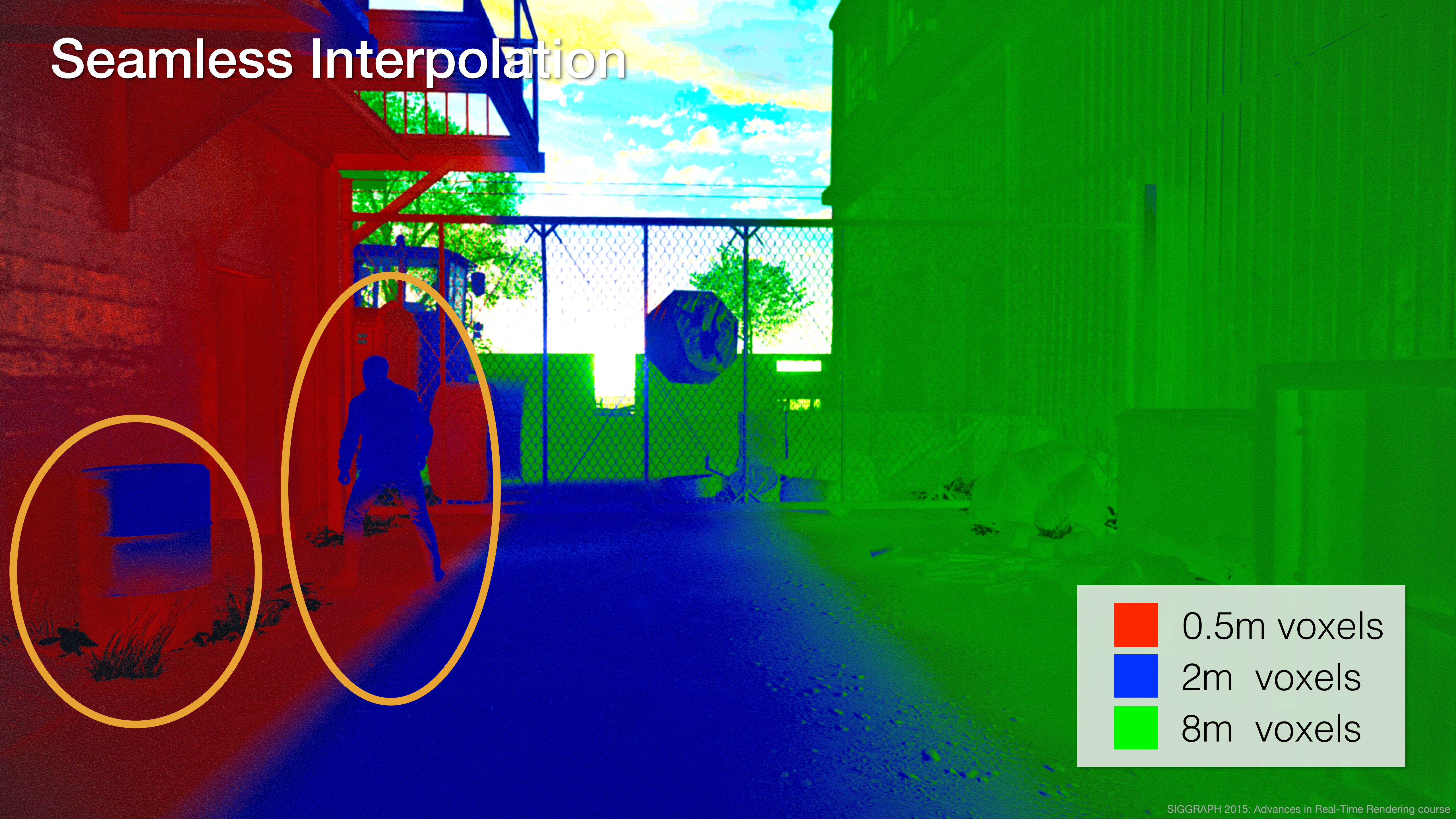
Trilinear neighborhood

Seamless Interpolation



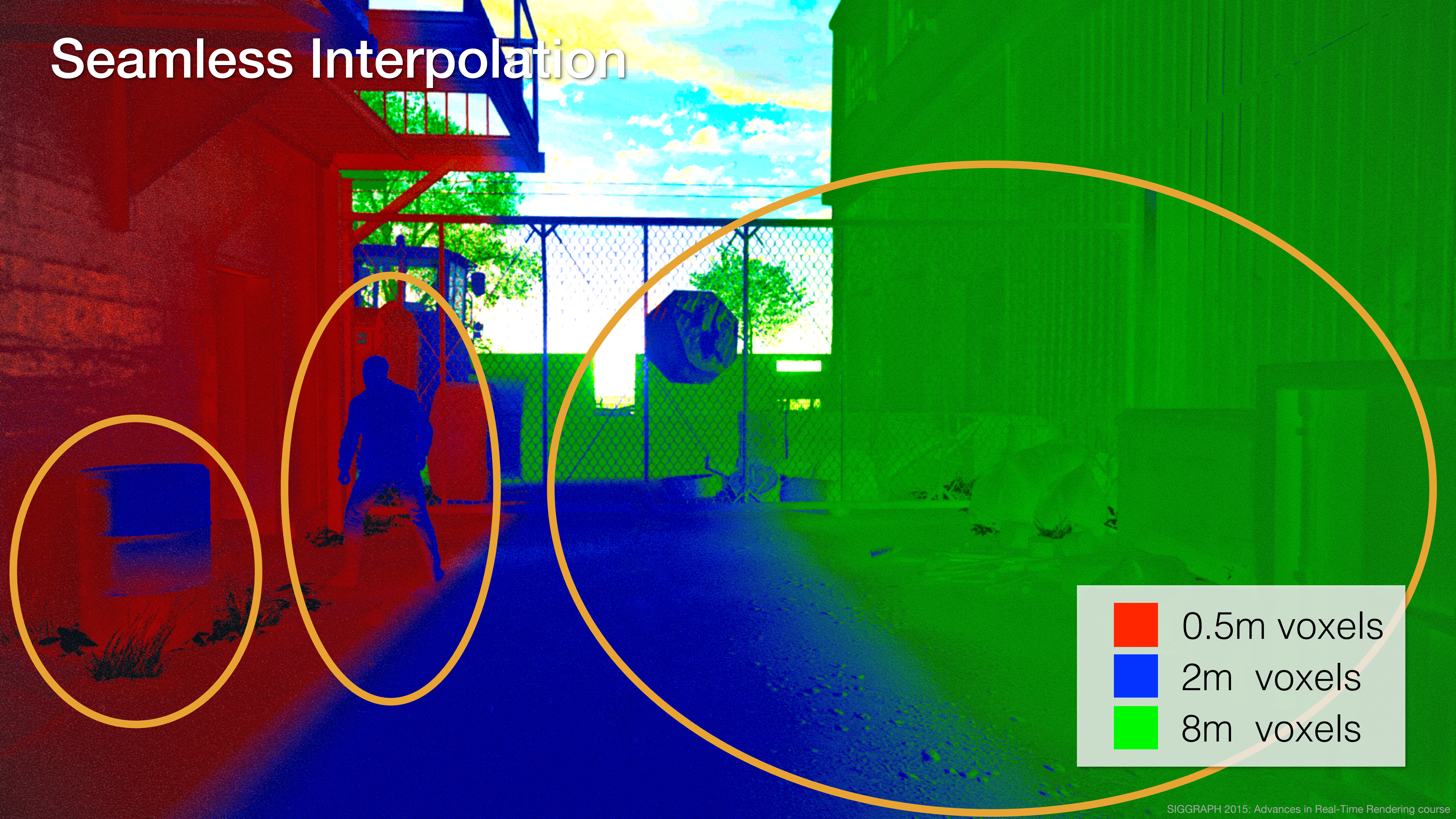
- 0.5m voxels
- 2m voxels
- 8m voxels

Seamless Interpolation



- 0.5m voxels
- 2m voxels
- 8m voxels

Seamless Interpolation

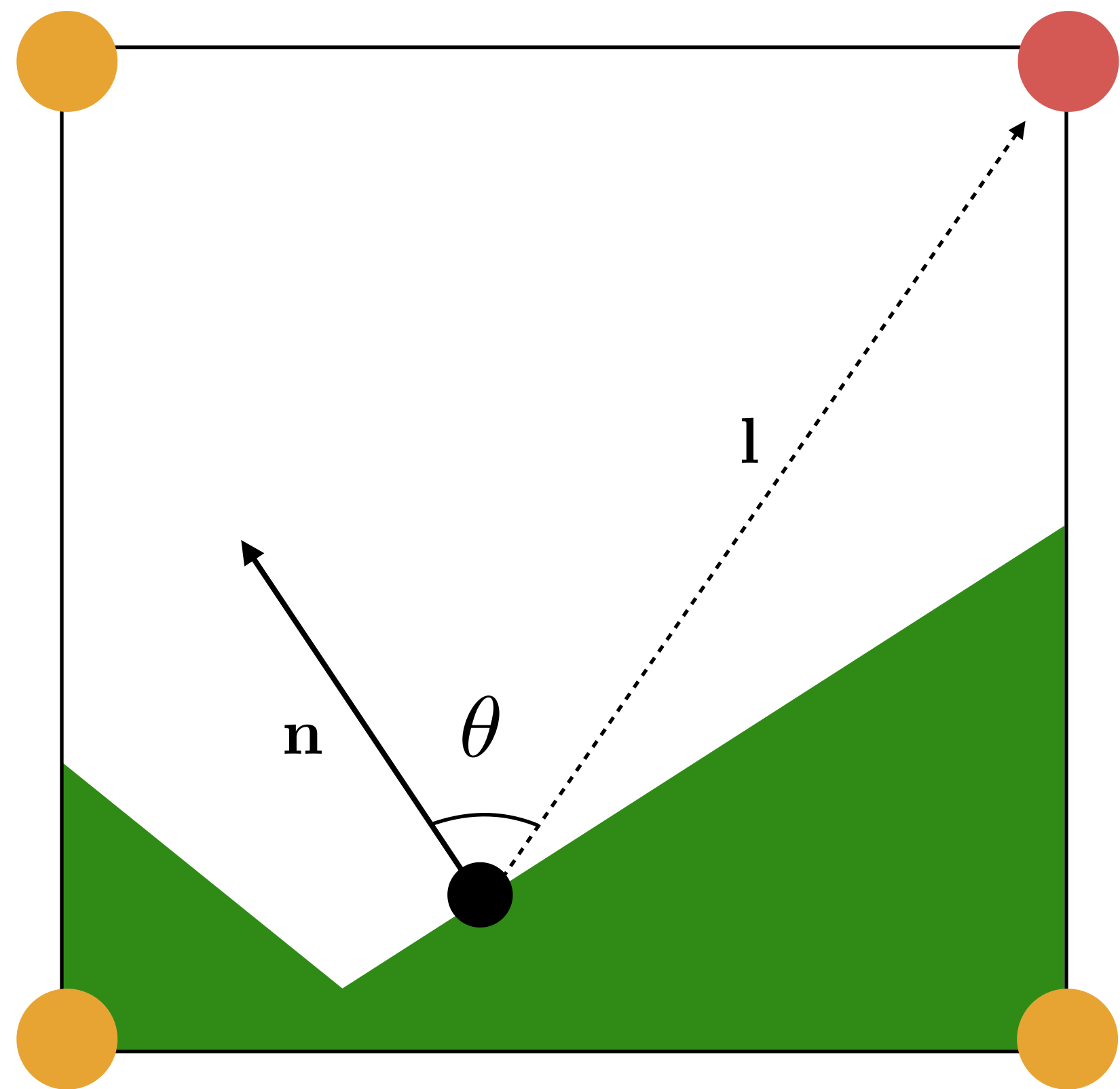


- 0.5m voxels
- 2m voxels
- 8m voxels

Seamless Interpolation



Geometry Weights



Multiply trilinear weight with $\max(0, \cos \theta)$



On



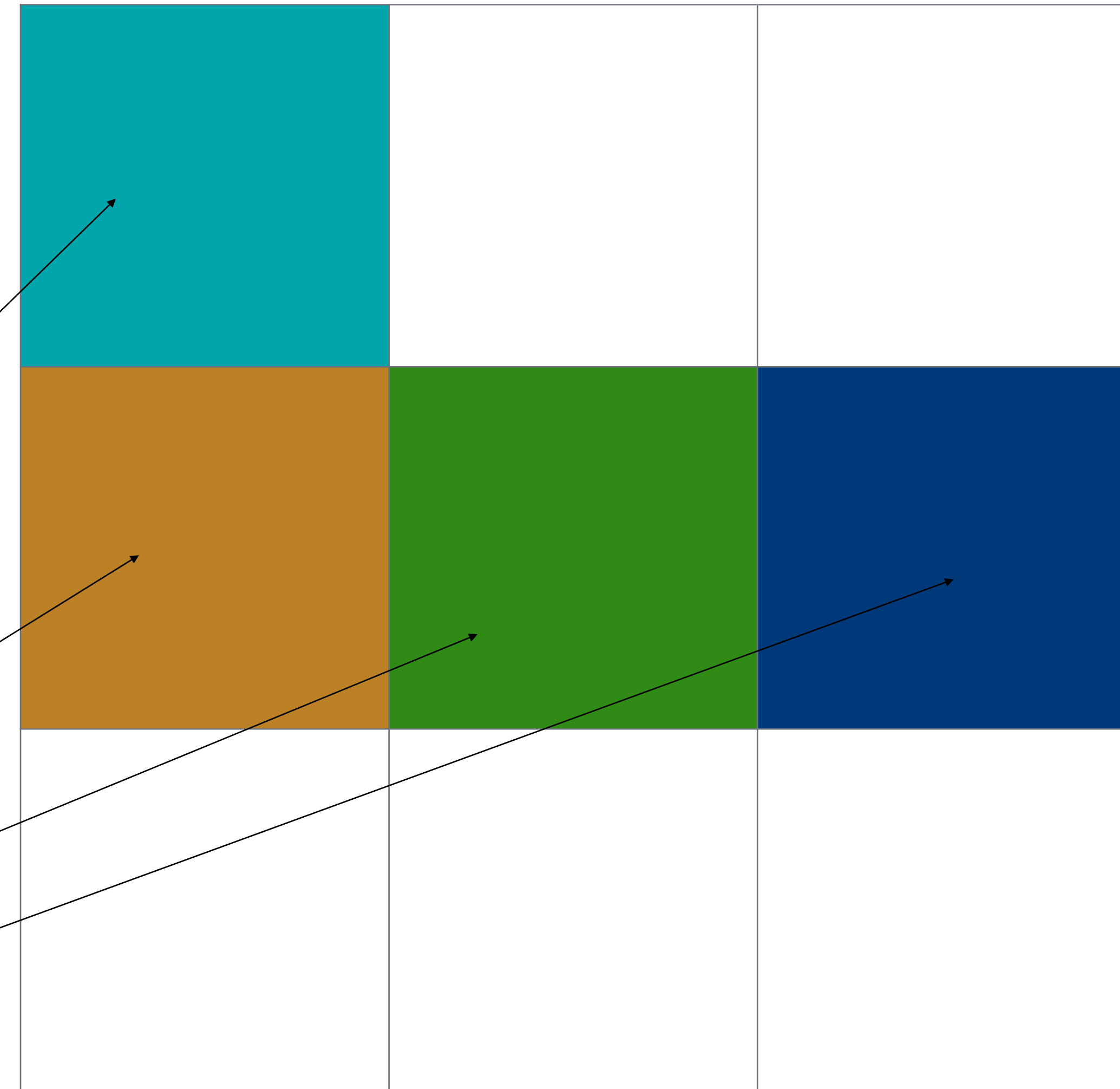
Off

Scaling to Large Scenes

World Atlas

World is divided into a **cell grid** for streaming

Per cell voxel tree

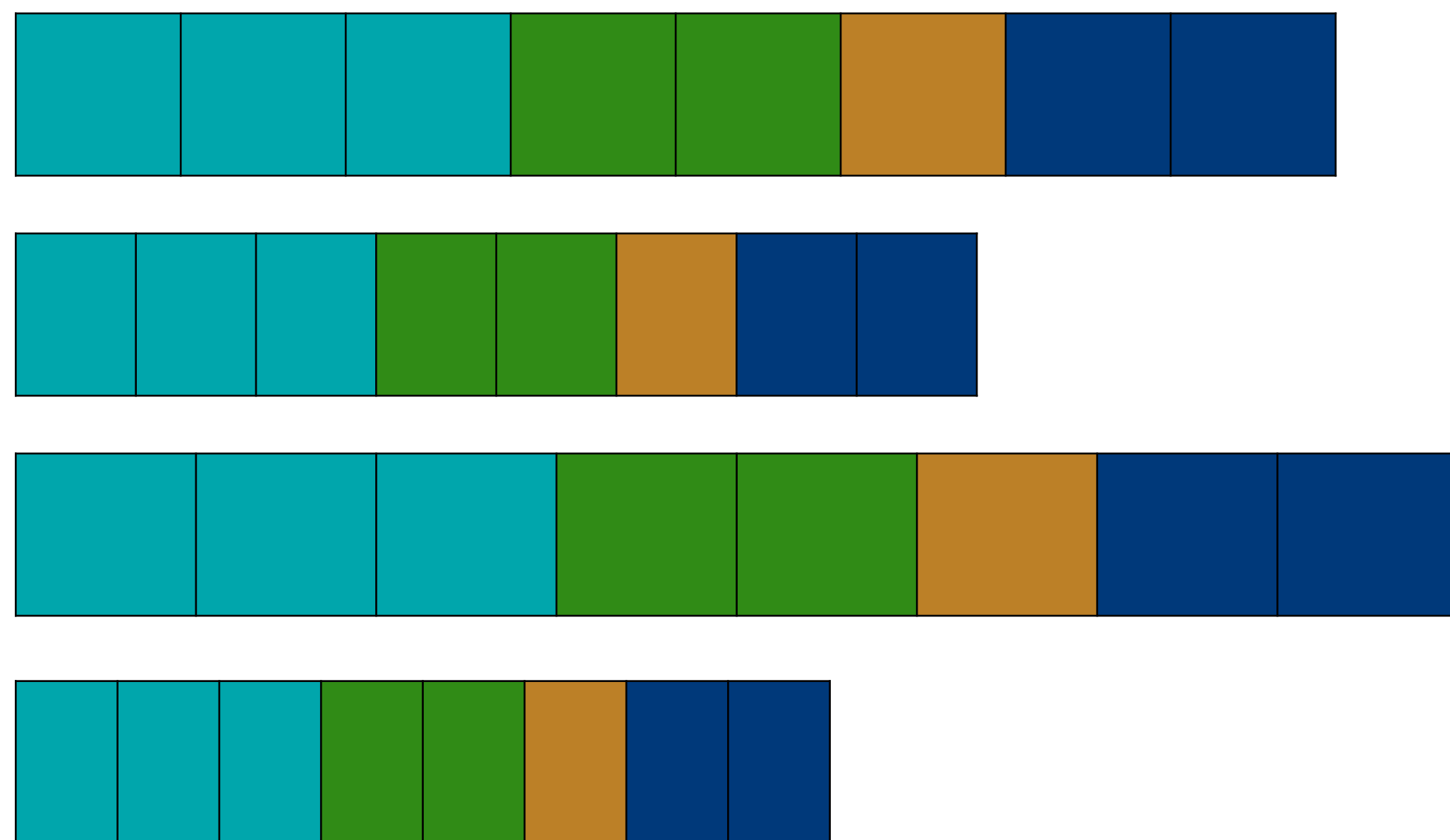


128 m

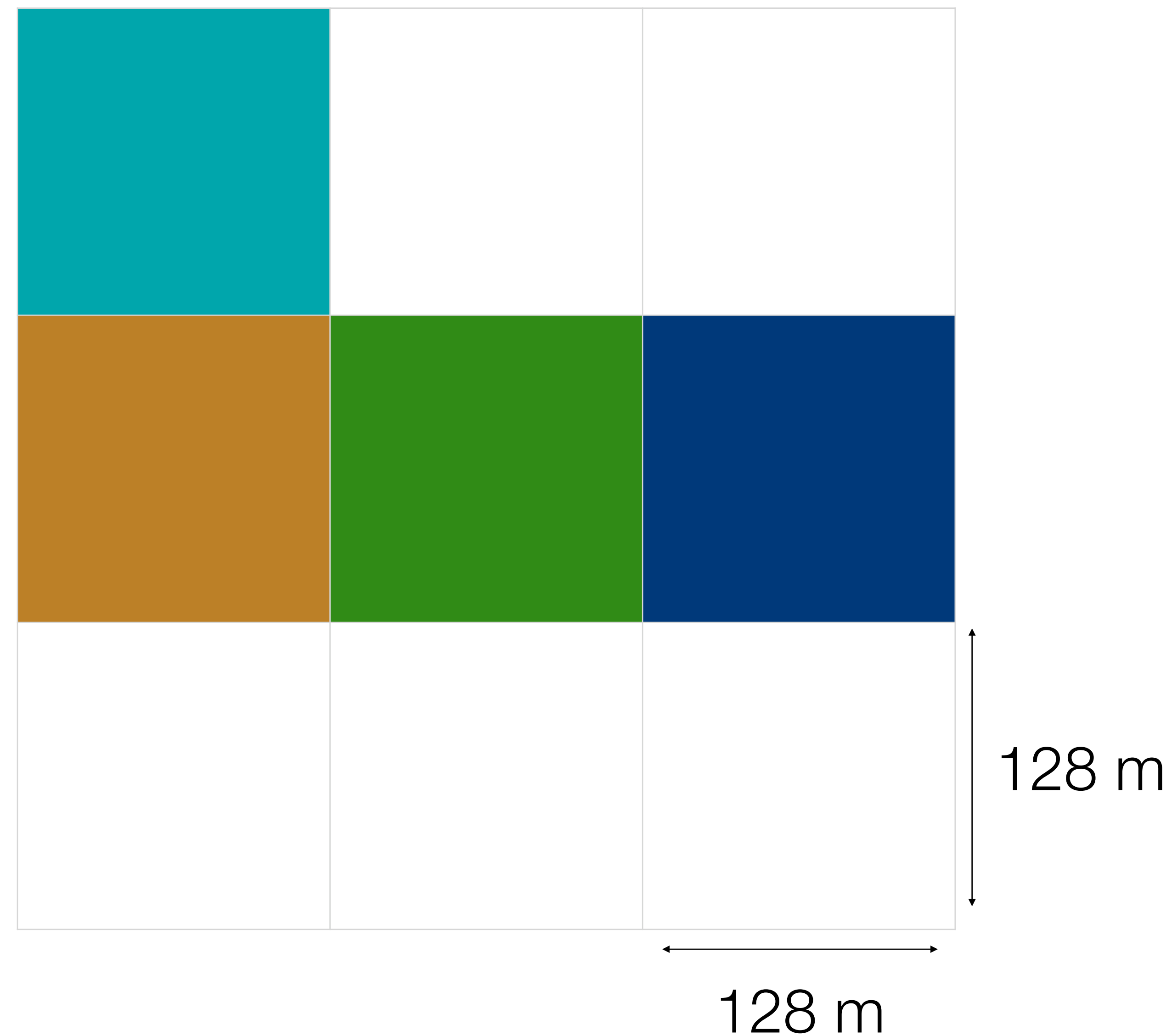
128 m

Scaling to Large Scenes

World Atlas



Linear GPU arrays



Global Illumination



Screen Space + Ambient





Global Illumination



Screen-Space + Ambient





Global Illumination



Screen-Space + Ambient



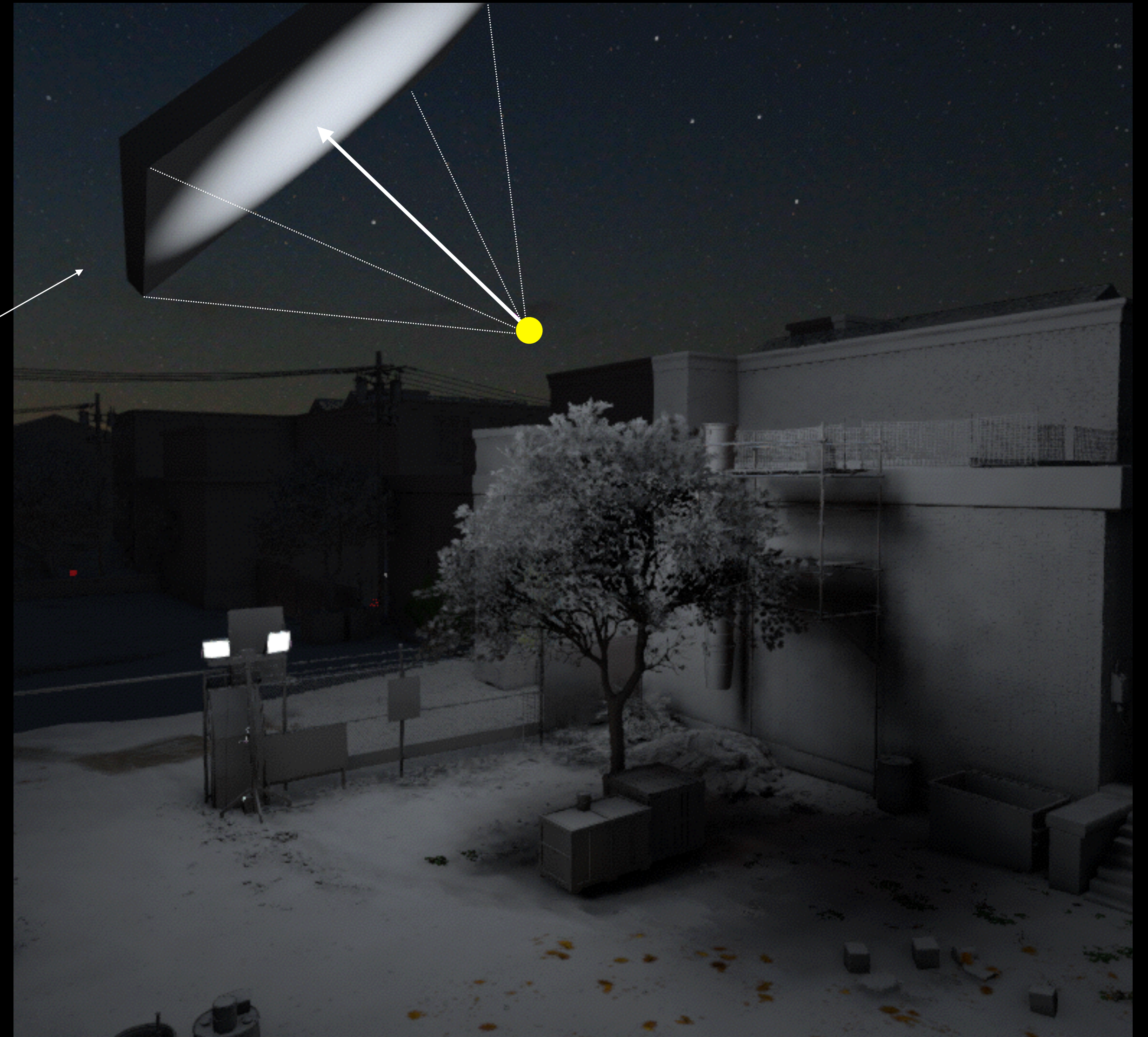
Performance

Each world cell has max 65K diffuse GI data points

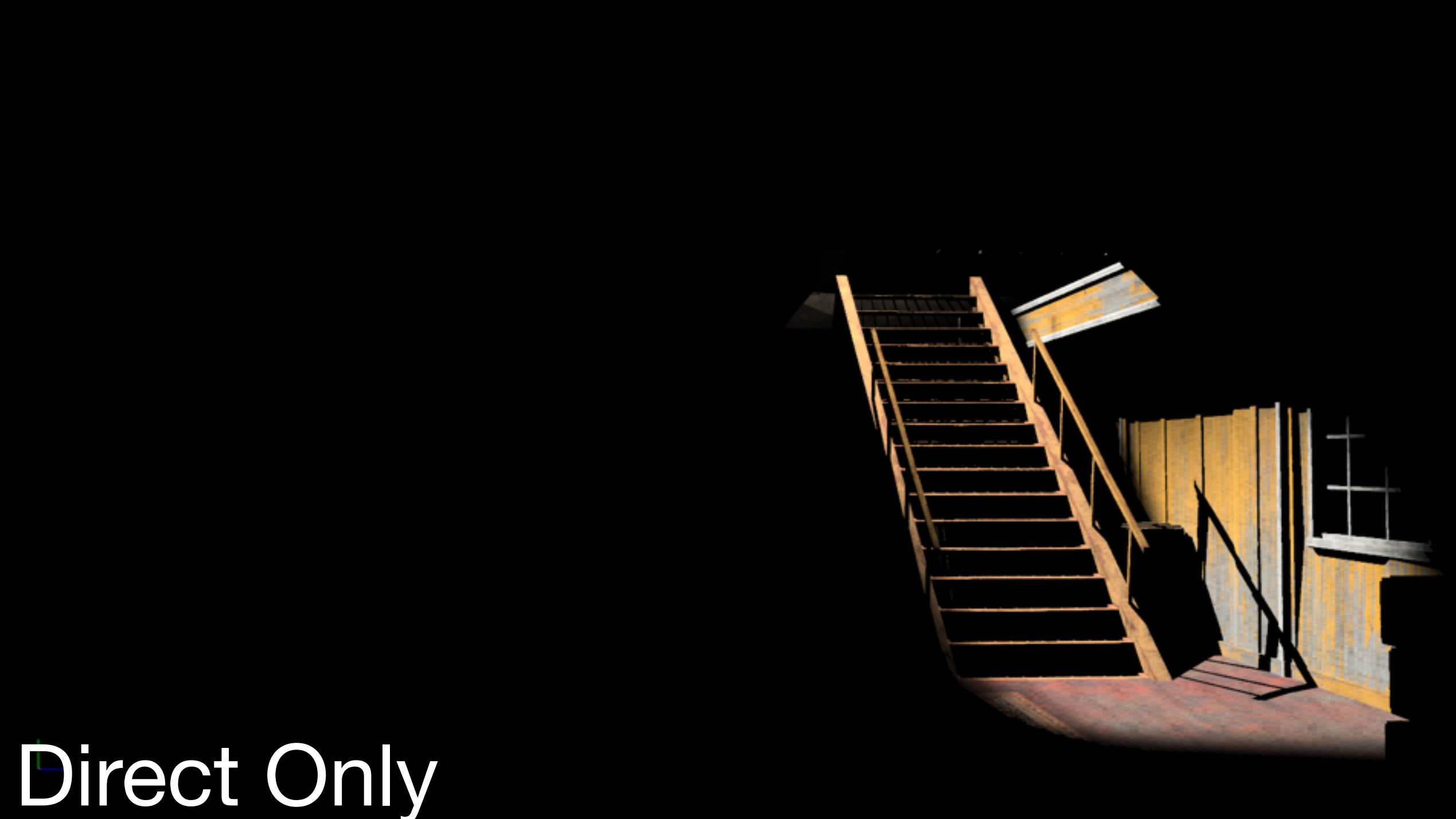
Comparable to **256x256** light map

Performance

Use **reflector lights**
to avoid dynamic fill lights



Local Irradiance



Direct Only



Global Illumination



Reference Indirect



Real-Time Indirect

Volumetric Global Illumination



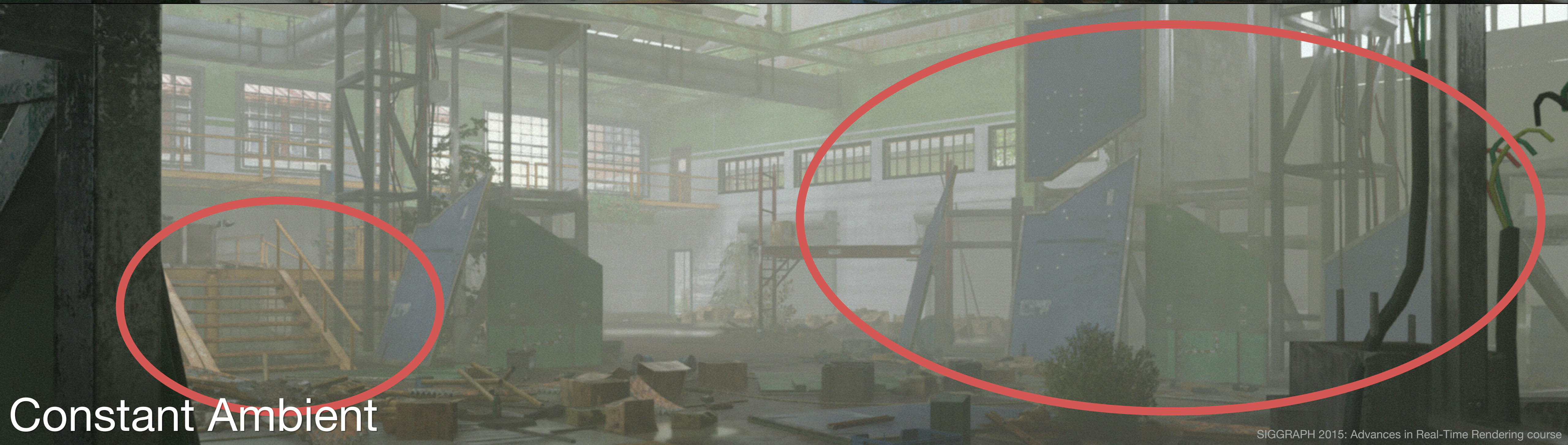


Global Illumination

Constant Ambient



Global Illumination



Constant Ambient

Summary

Unified approach to large scale lighting

Fully **automatic** specular probe system

Talk Outline

The background image is a grayscale rendering of a large, industrial interior space. It features a complex steel structure with numerous vertical and horizontal beams. The floor is cluttered with various pieces of equipment, including what looks like a large metal cabinet or machine on the right, and several smaller objects scattered around. The lighting is somewhat dim, creating a sense of depth and shadow.

Part I: Large-scale lighting

Part II: Screen space lighting

Screen-Space Techniques

Requirements

- Occlude larger scale lighting
- Fill in with screen-space sampled lighting

Screen-Space Ambient Occlusion and Diffuse



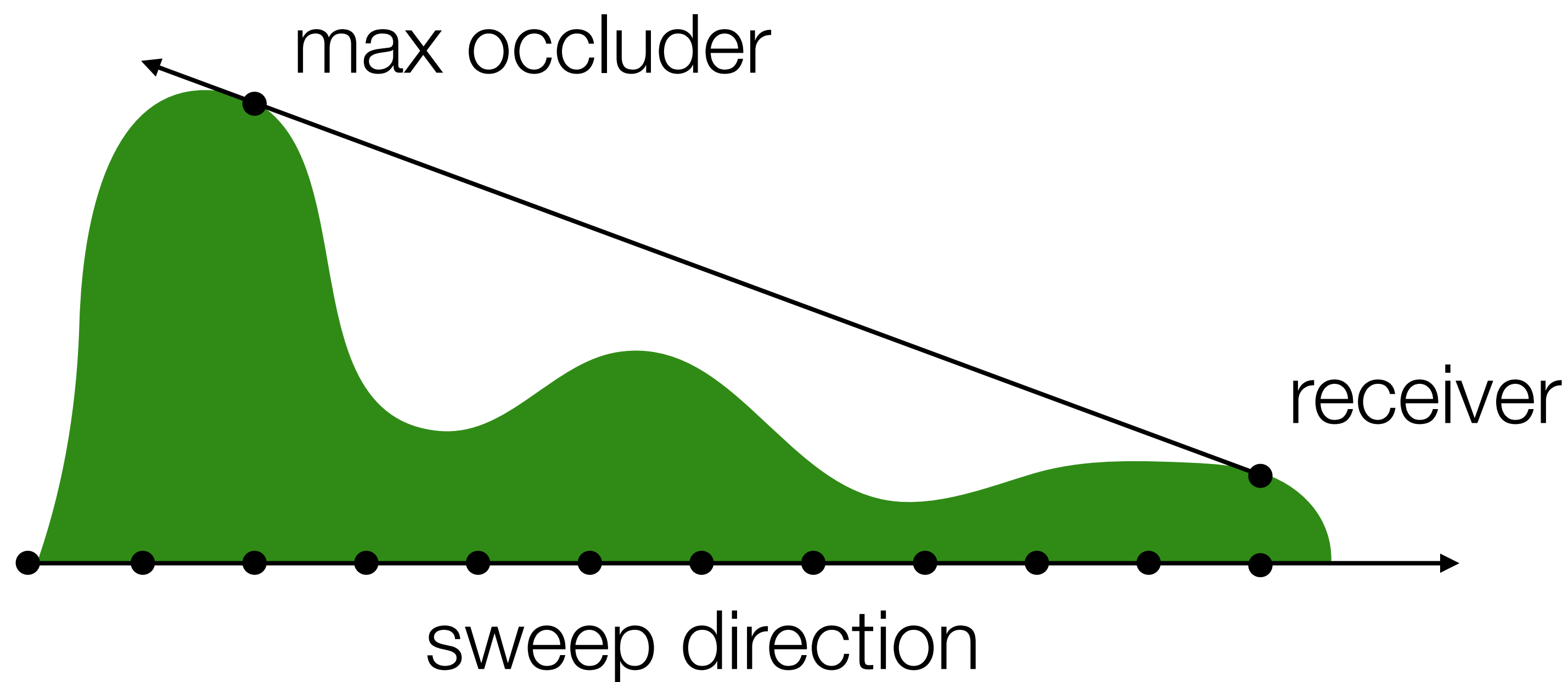
GI diffuse occlusion



Screen-Space Diffuse

Screen-Space Ambient Occlusion

Based on Line-Sweep Ambient Obscurance [Timonen2013]:
LSAO locates most contributing occluders

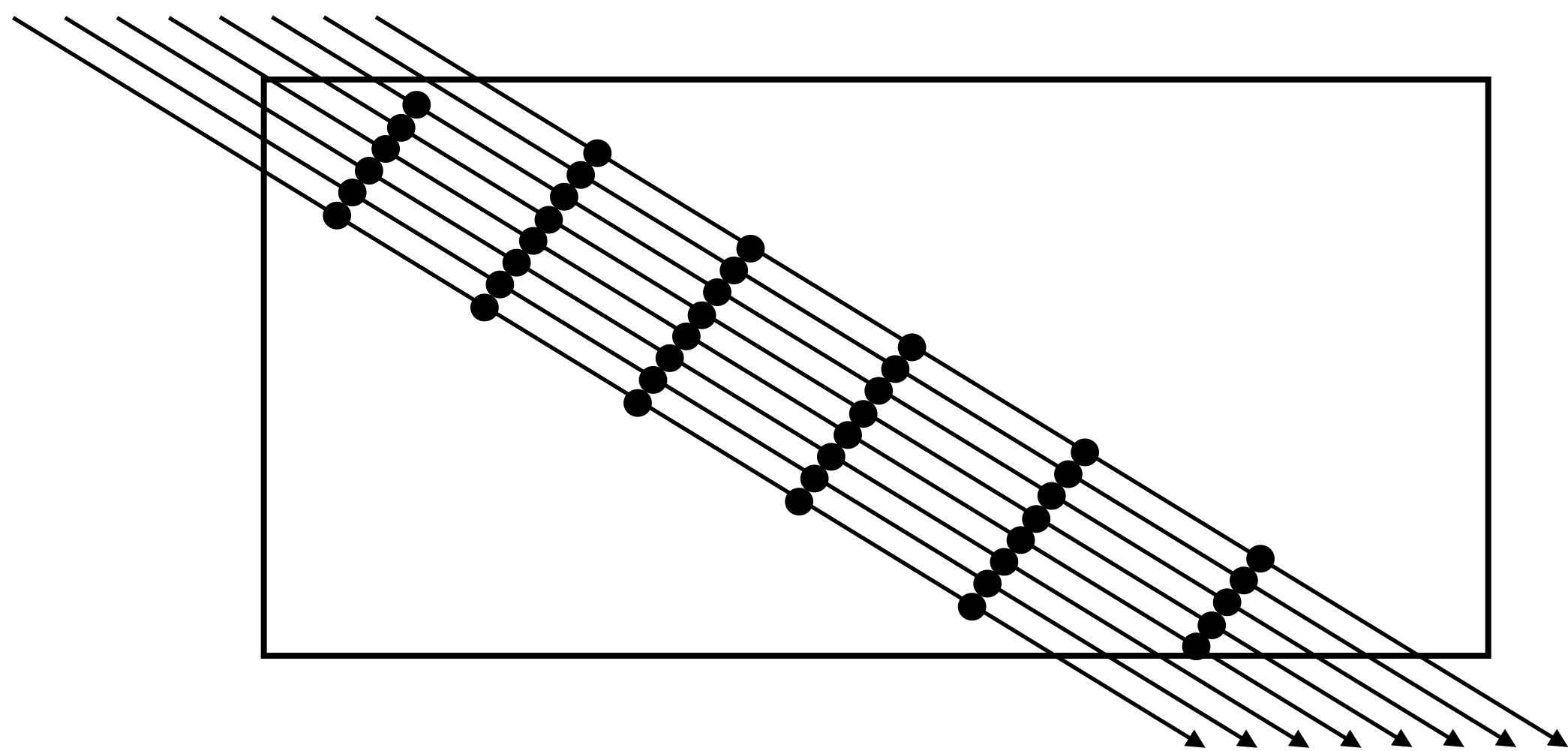


Screen-Space Ambient Occlusion

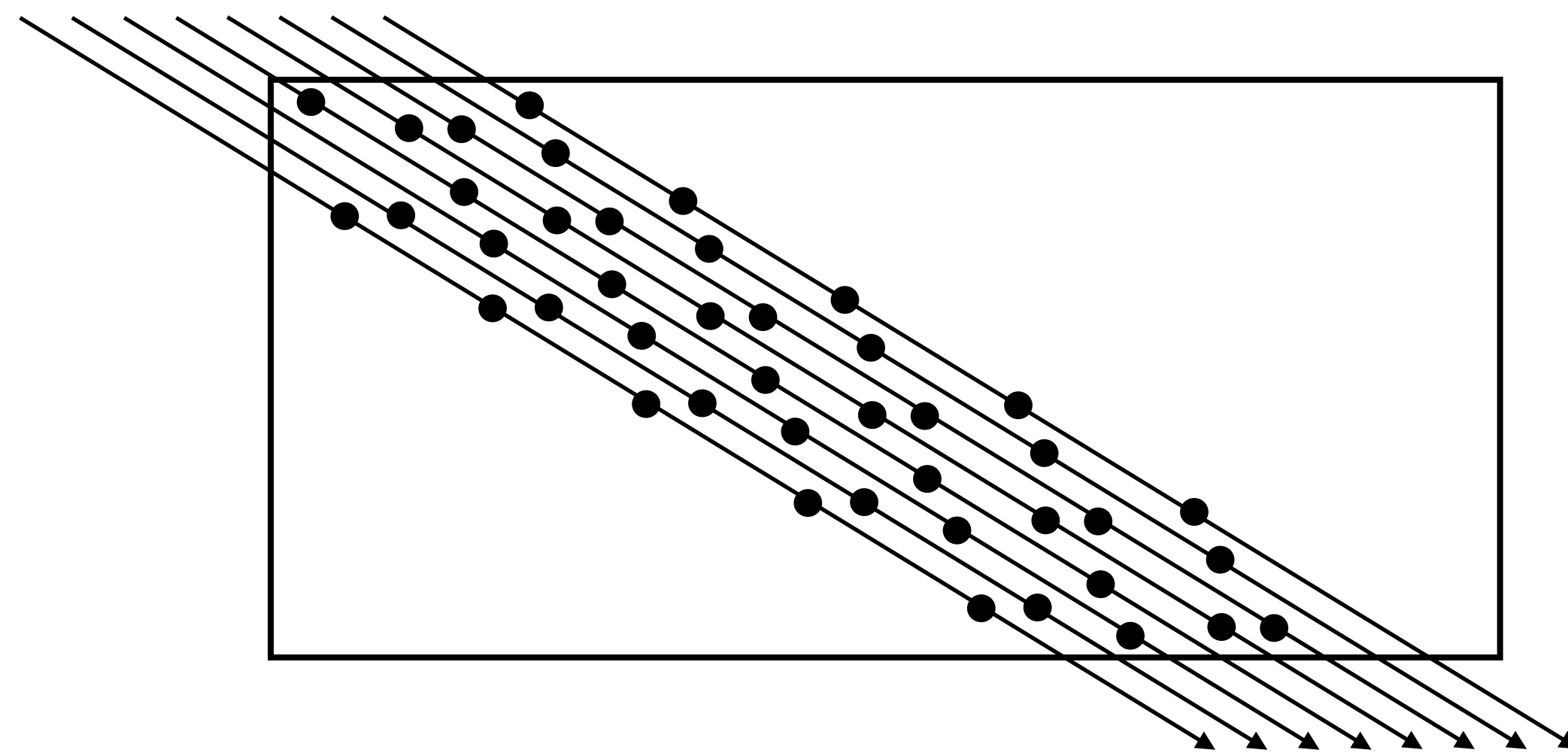
We scan in 36 directions, long steps ($\sim 10\text{px}$) and short line spacing ($\sim 2\text{px}$ apart)

- Scheduling friendly for the GPU
- Scan is 0.75ms on Xbox One at 720p

Screen-Space Ambient Occlusion



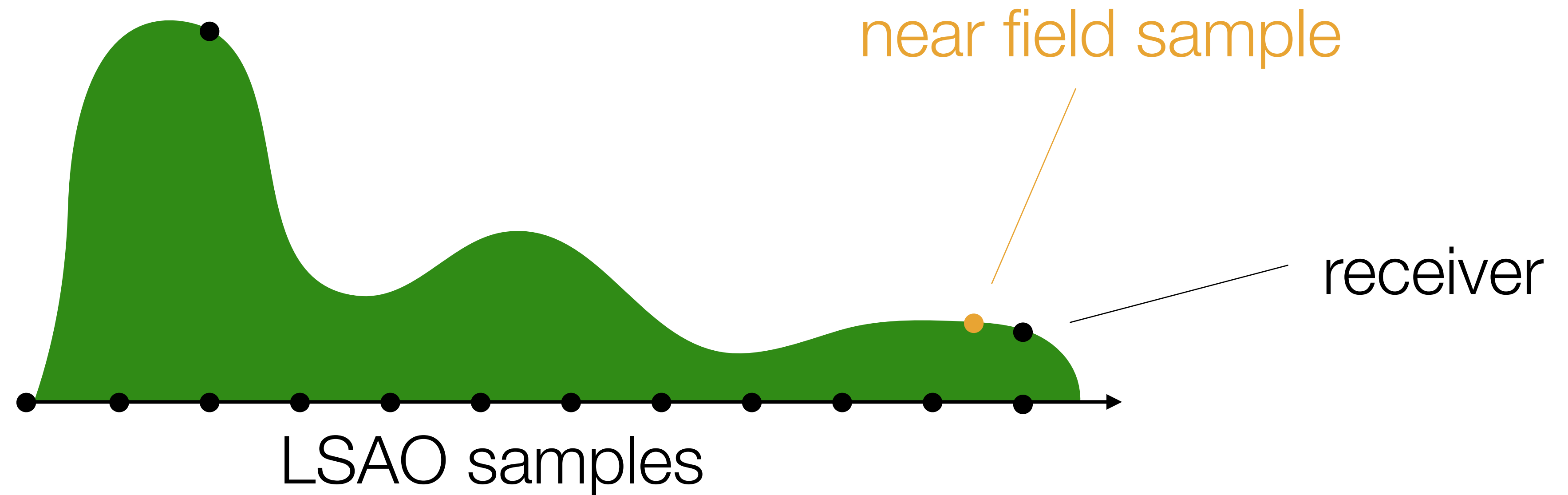
regular



jittered

Screen-Space Ambient Occlusion

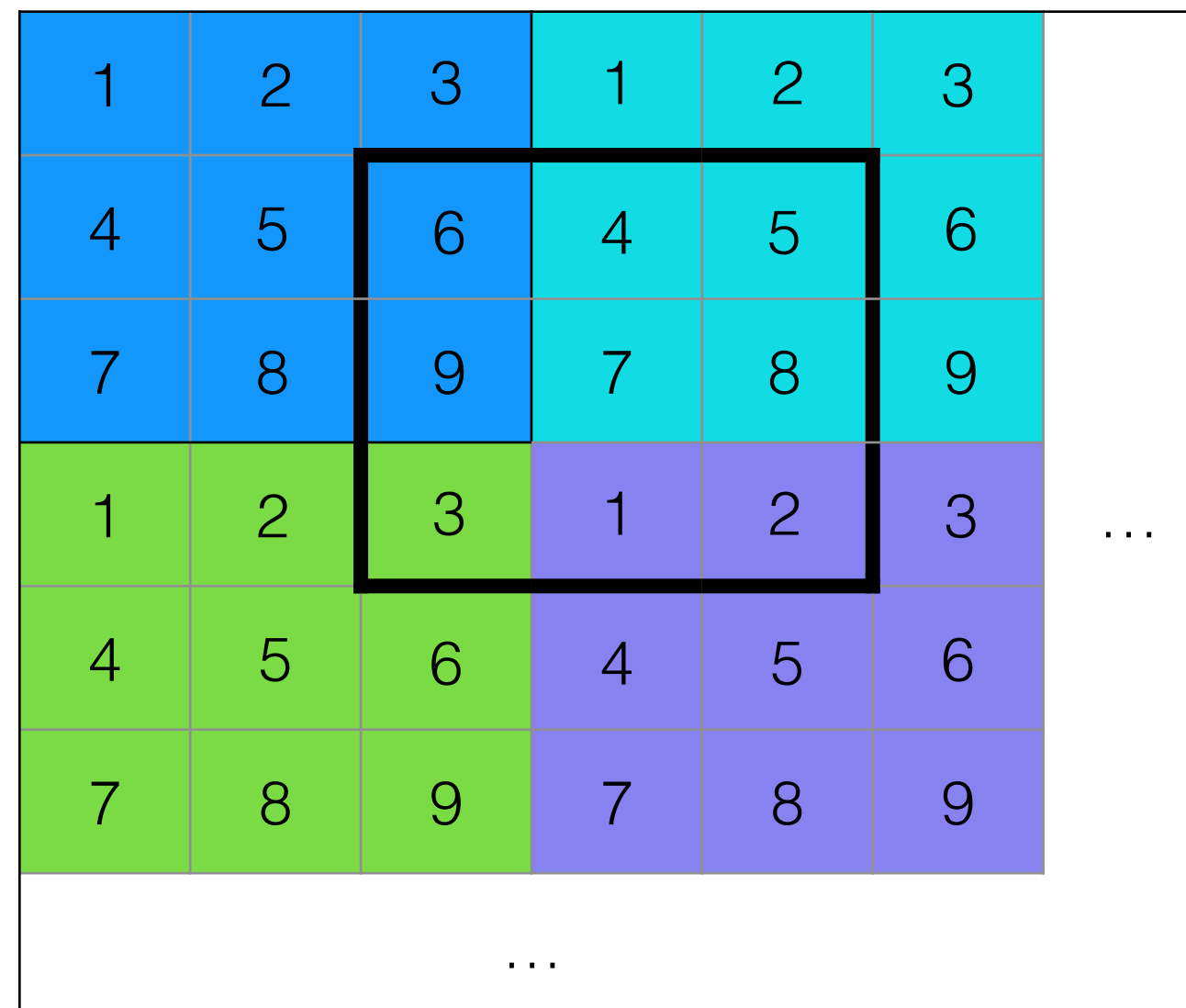
- An additional near field sample (at $\sim 2\text{px}$ distance)
- Sample normal to clamp occluders



Screen-Space Ambient Occlusion

36 directions too expensive to gather per pixel

- Interleave on a 3x3 neighborhood (4 dirs/pixel)
- Gather using a depth and normal aware 3x3 box filter

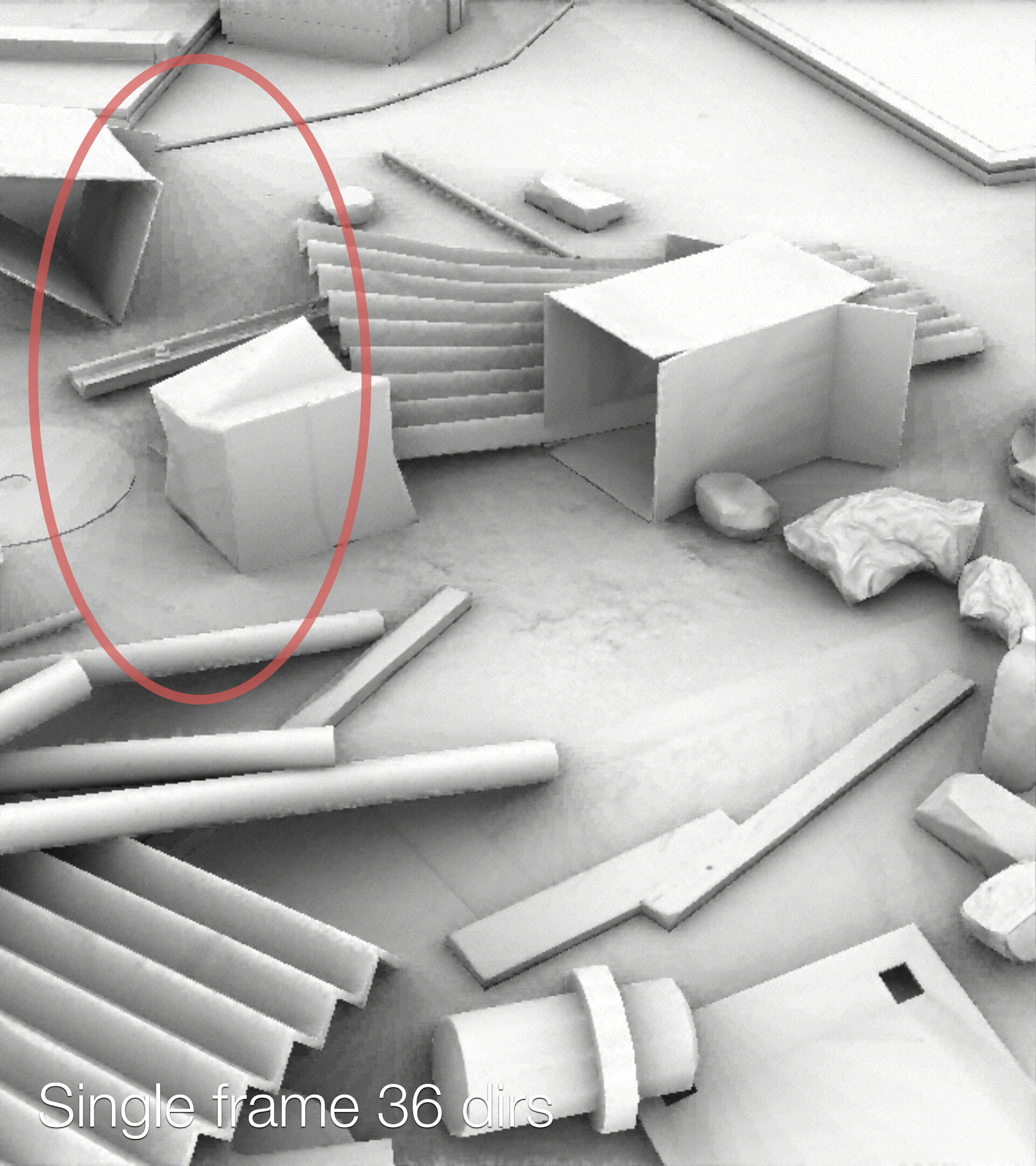




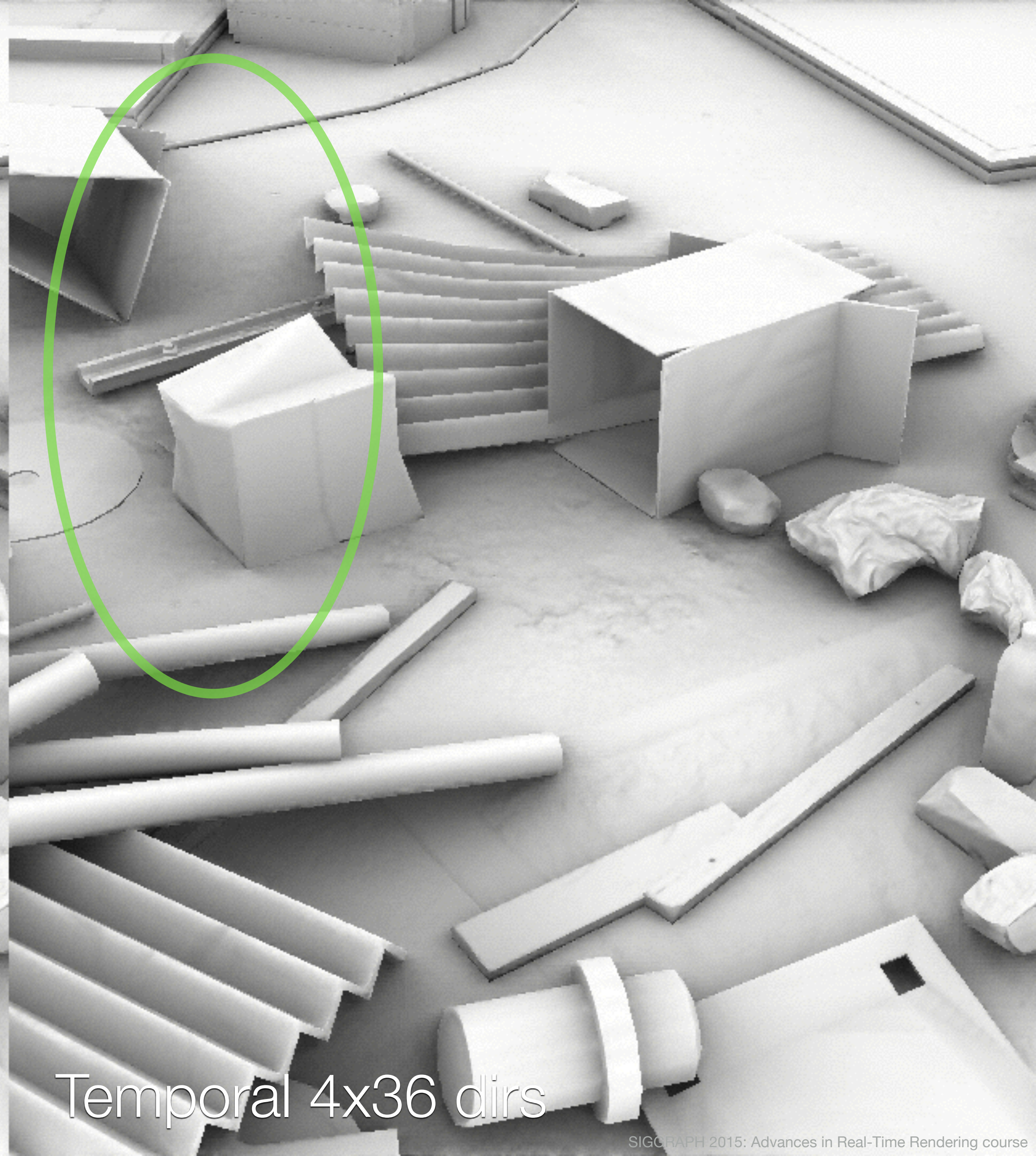
Screen-Space Ambient Occlusion — 1.4ms @ 720p on XB1



Screen-Space Ambient Occlusion — 1.4ms @ 720p on XB1



Single frame 36 dirs



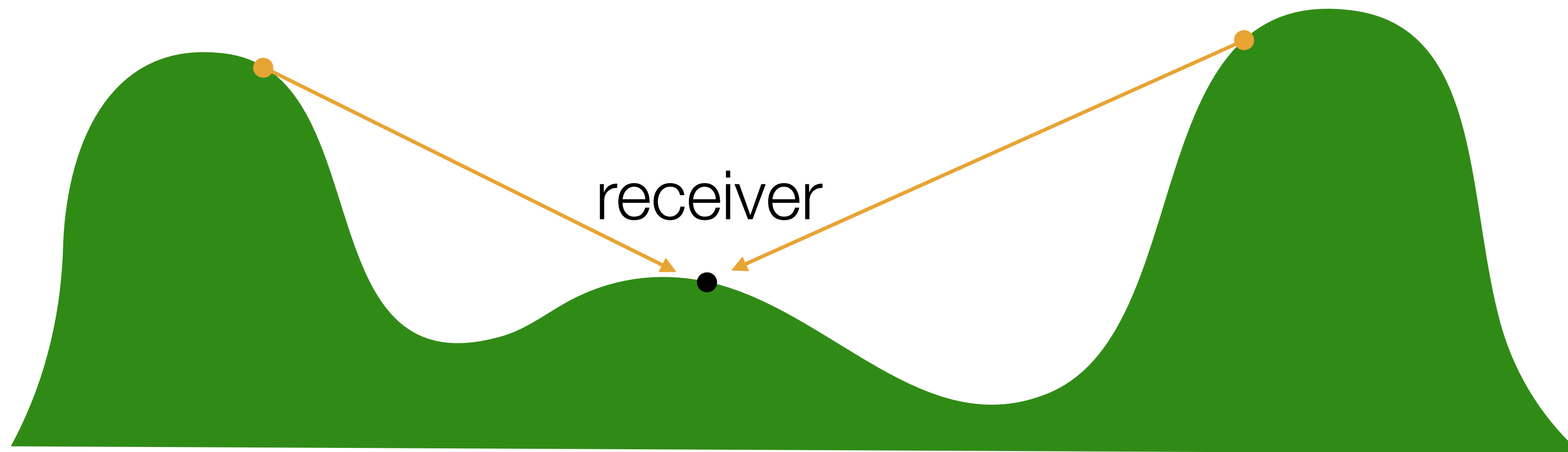
Temporal 4x36 dirs

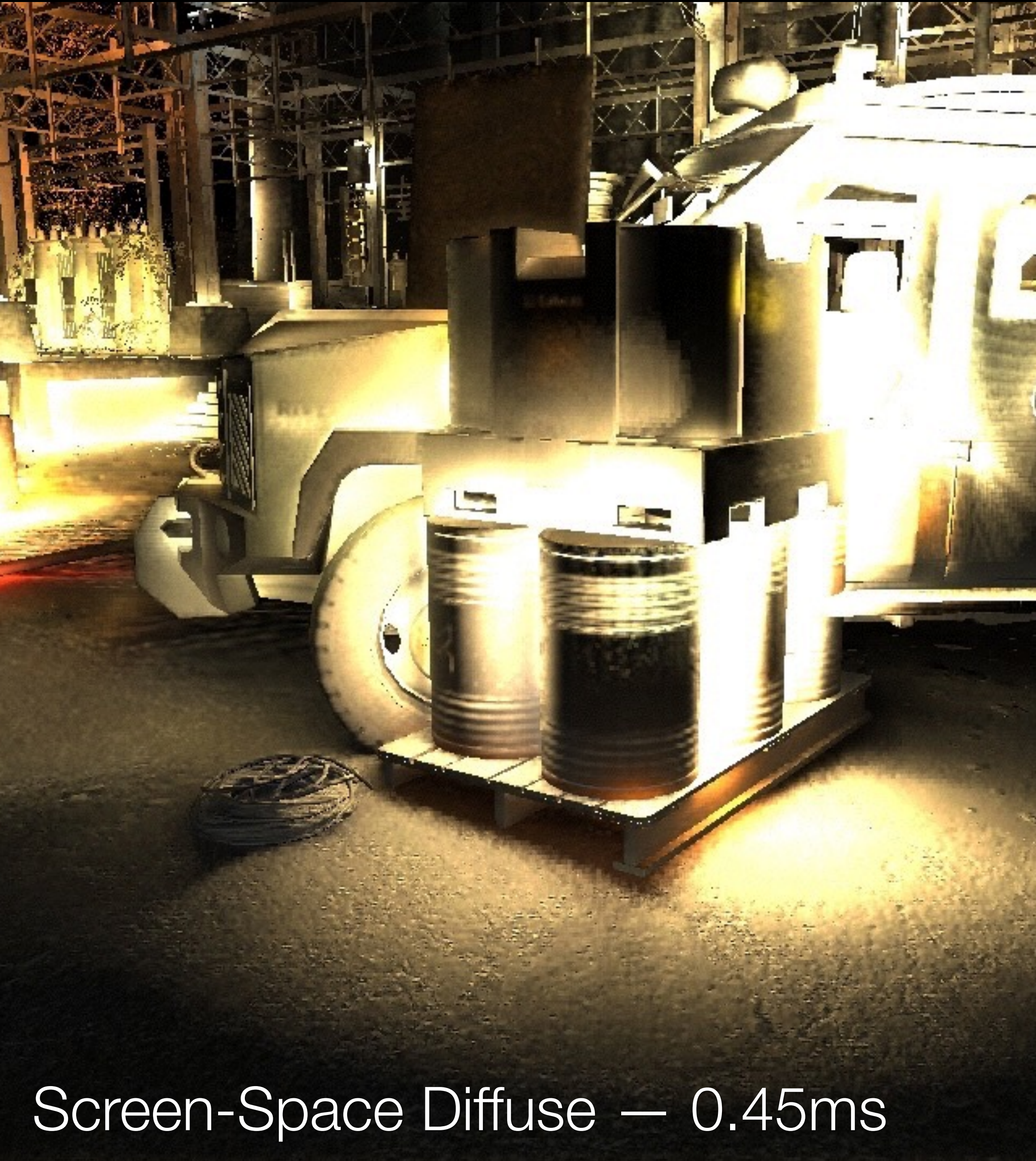
Screen-Space Diffuse Lighting

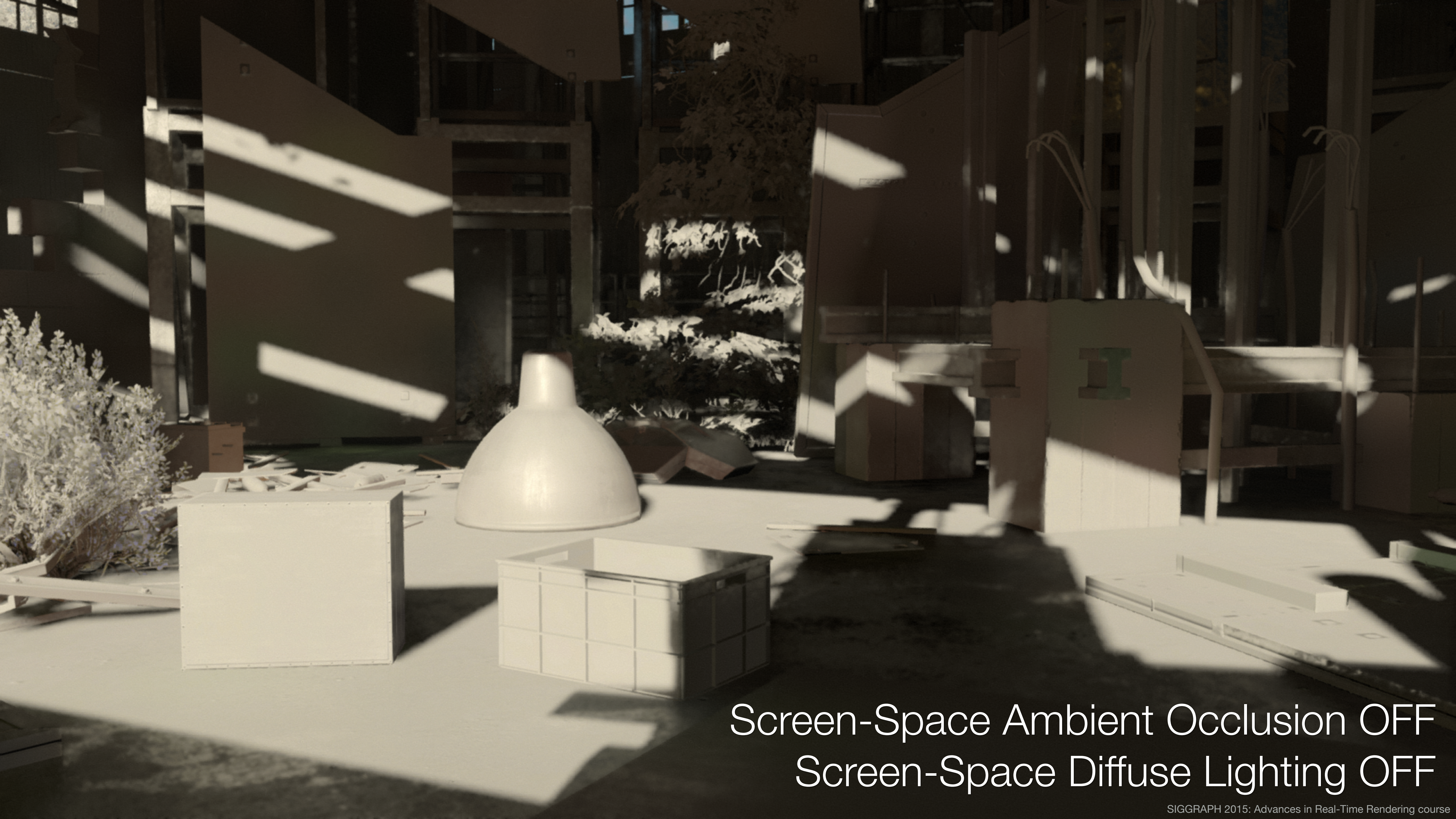
Screen-Space Diffuse Lighting

LSAO samples are “the most visible”

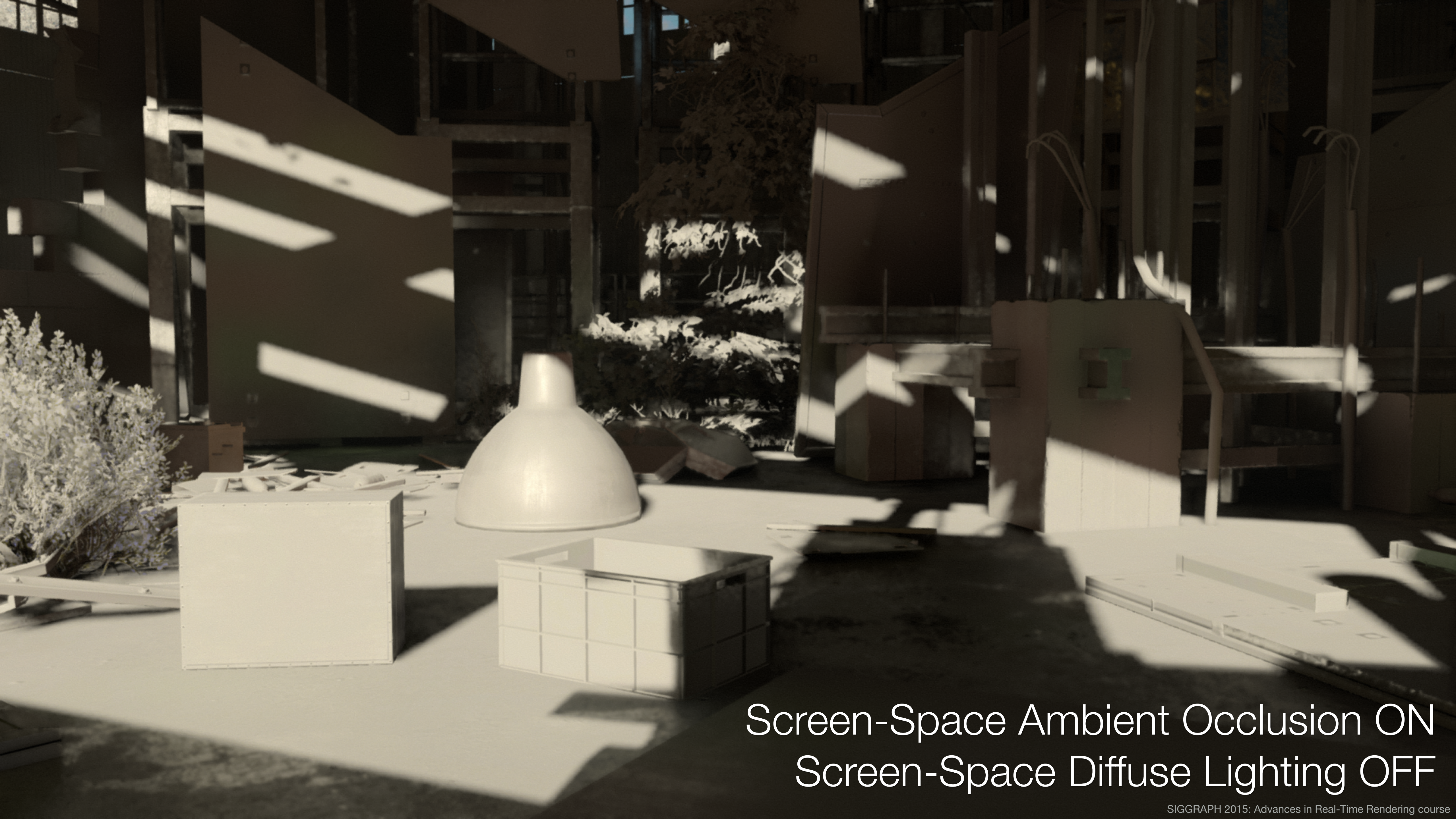
- Good candidates to sample incident light
- Can't be occluded by definition (providing self-occlusion)



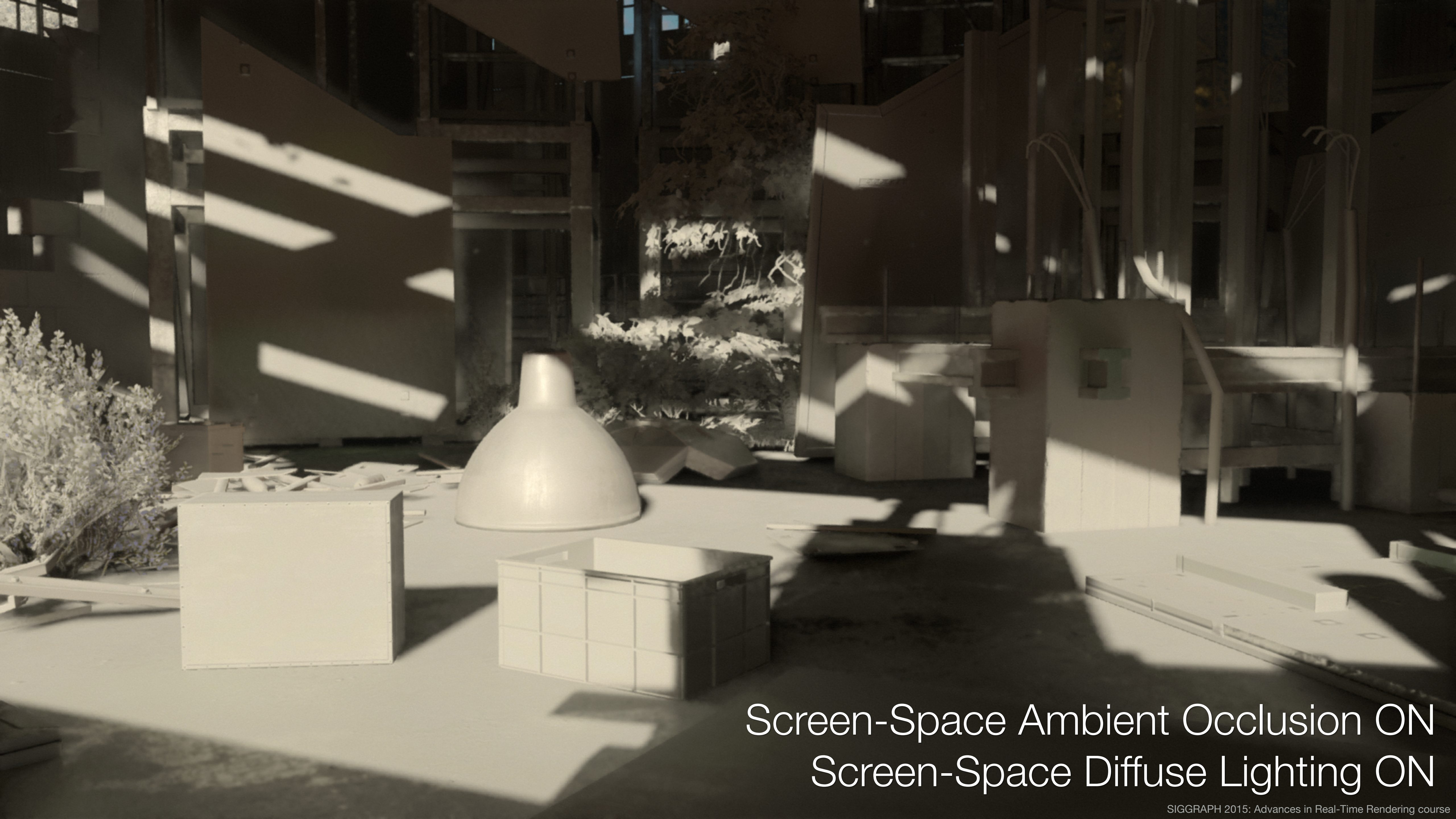




Screen-Space Ambient Occlusion OFF
Screen-Space Diffuse Lighting OFF



Screen-Space Ambient Occlusion ON
Screen-Space Diffuse Lighting OFF



Screen-Space Ambient Occlusion ON
Screen-Space Diffuse Lighting ON



Screen-Space Ambient Occlusion OFF
Screen-Space Diffuse Lighting OFF



Screen-Space Ambient Occlusion ON
Screen-Space Diffuse Lighting ON



Screen-Space Ambient Occlusion OFF
Screen-Space Diffuse Lighting OFF



Screen-Space Ambient Occlusion ON
Screen-Space Diffuse Lighting OFF



Screen-Space Ambient Occlusion ON
Screen-Space Diffuse Lighting ON

Screen-Space Reflections and Occlusion



GI specular occlusion

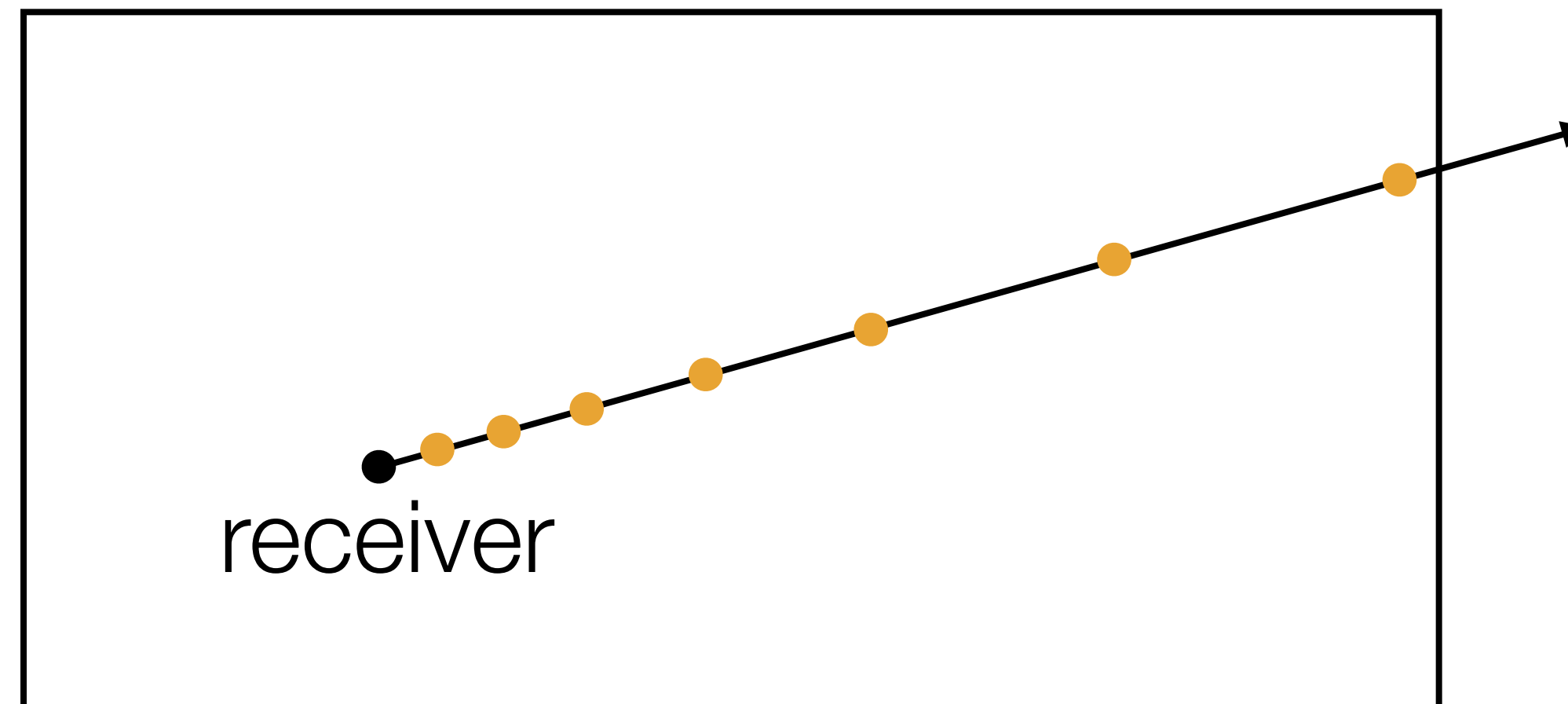


Screen-Space Specular

Screen-Space Reflections

1 ray per pixel from GGX distribution, evaluated for all surfaces

- Linear search (7 steps)
- Step distances form a geometric series



Screen-Space Reflections

Treating the depth buffer samples

Need to support varying roughness

- Calculate cone coverage

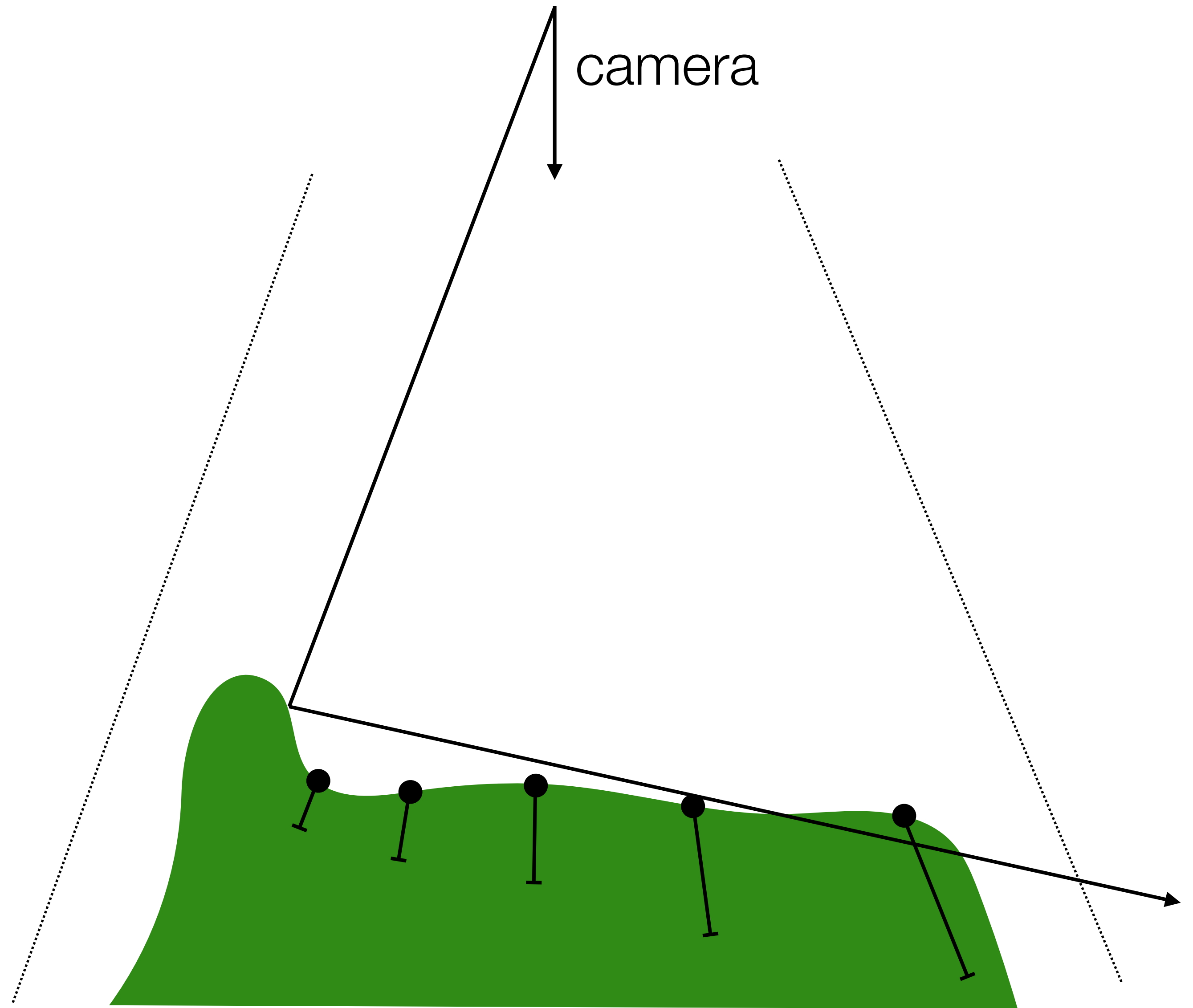
Need to suit both occlusion and color sampling

- Also find a single color sample location

Screen-Space Reflections

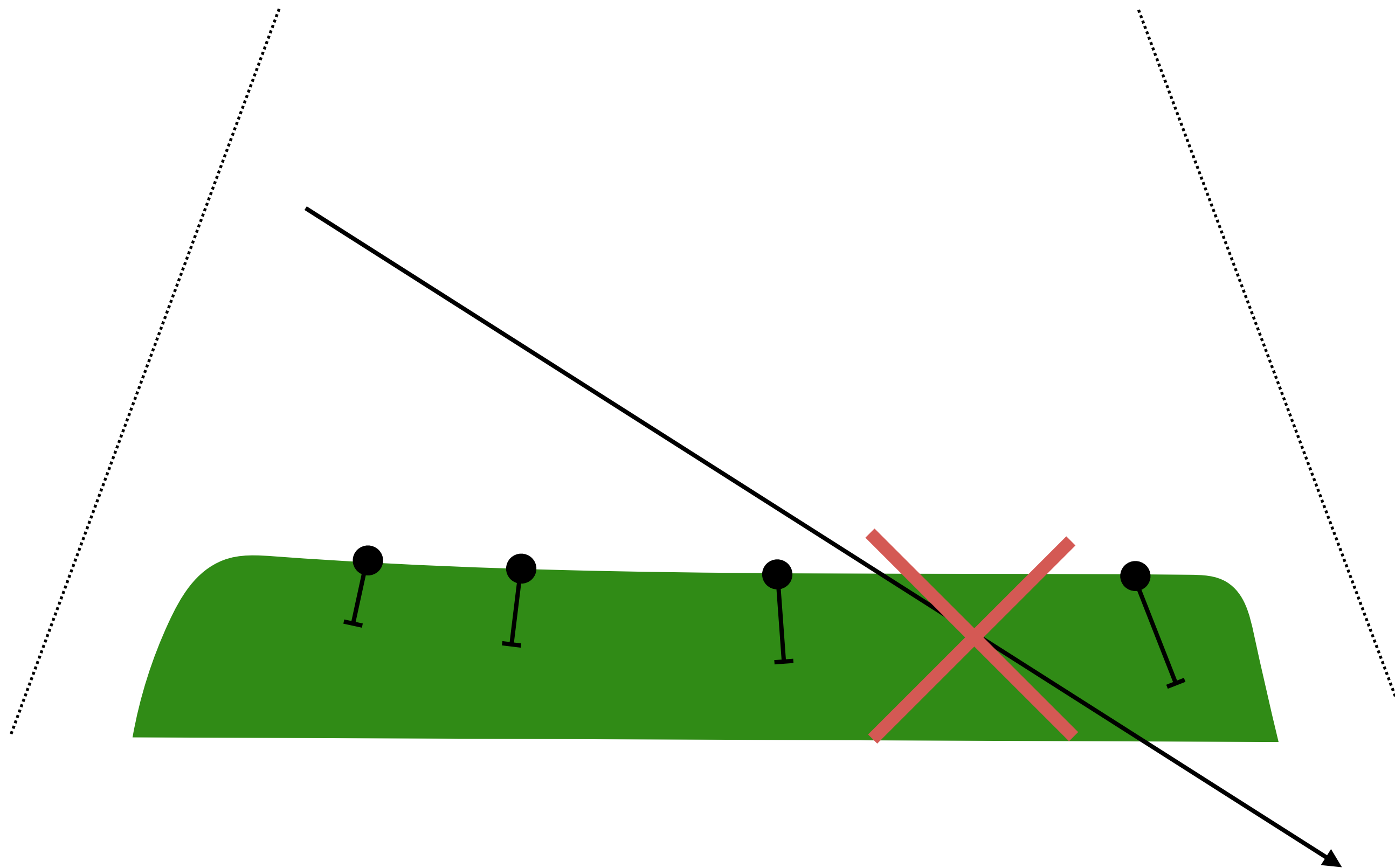
Depth thickness =
 $a + b^*$ (distance along the ray)

Depth field extends to/from
camera, not along view z!



Screen-Space Reflections

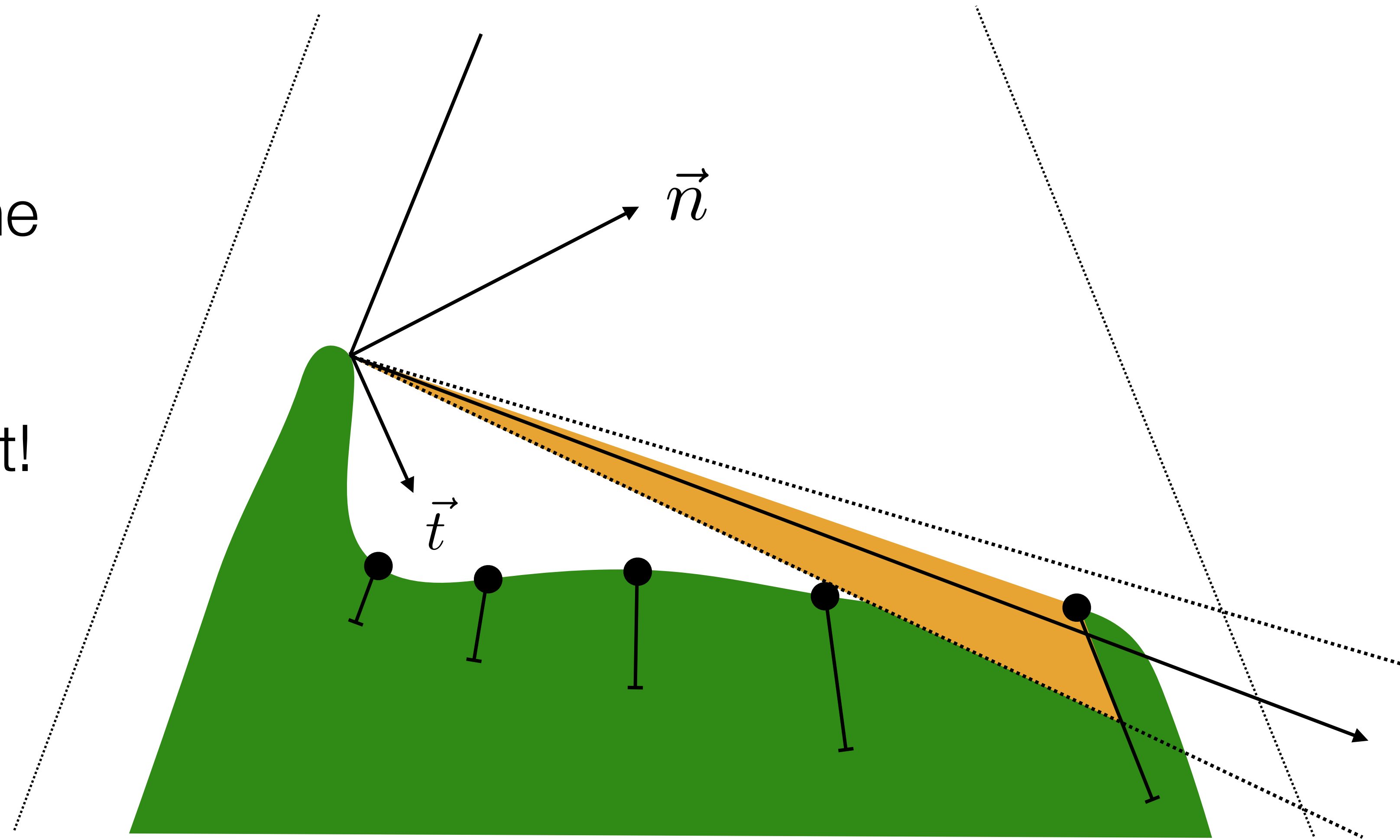
Match the linear term to step size in view space.
Otherwise holes on solid geometry:



Screen-Space Reflections

For occlusion, calculate
max coverage of the cone

Clamp the cone's lower
bound to surface tangent!



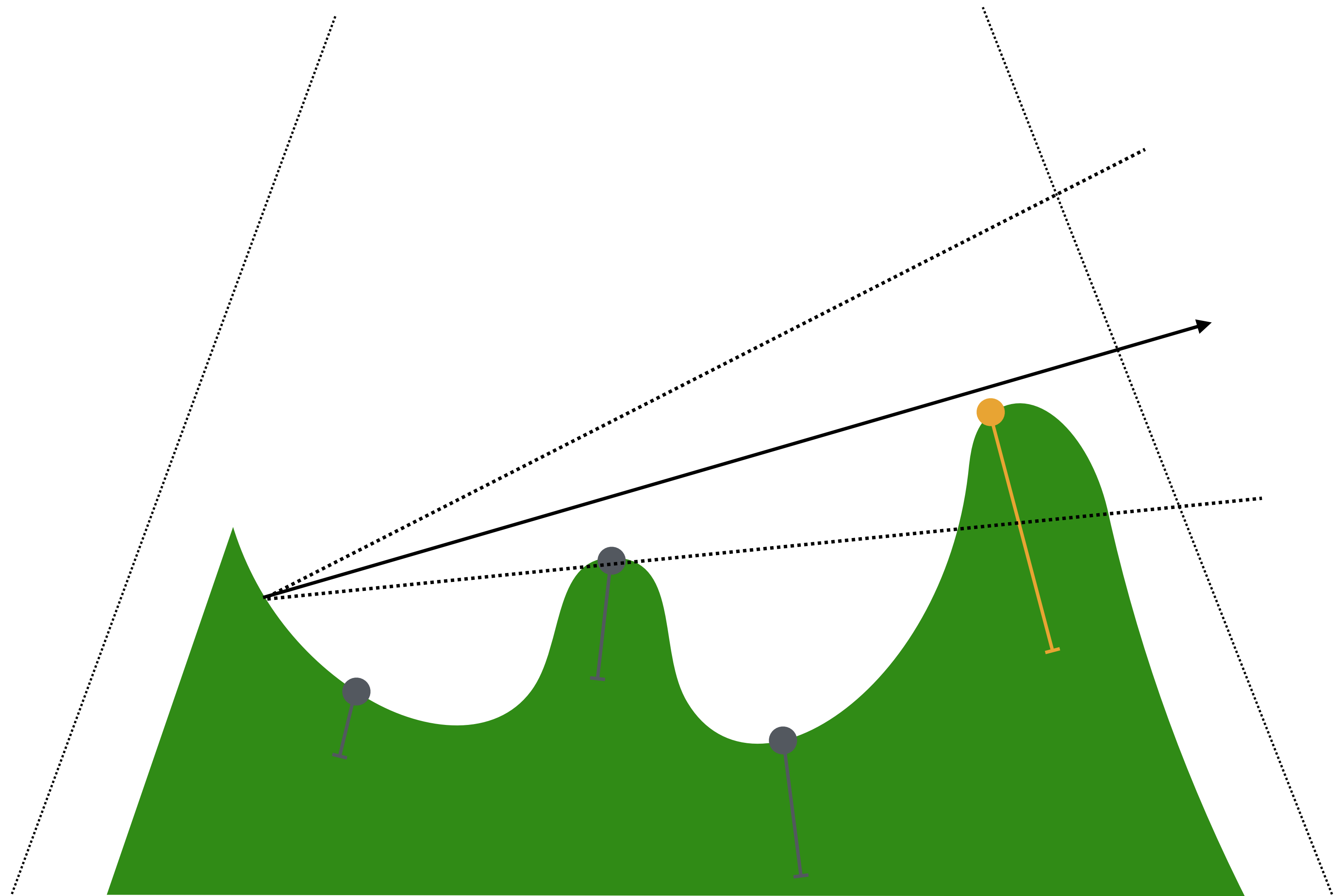


Screen-Space Reflection Occlusion — 0.8 ms @ 720p on XB1

Screen-Space Reflections

For **color**, we need a single sample location

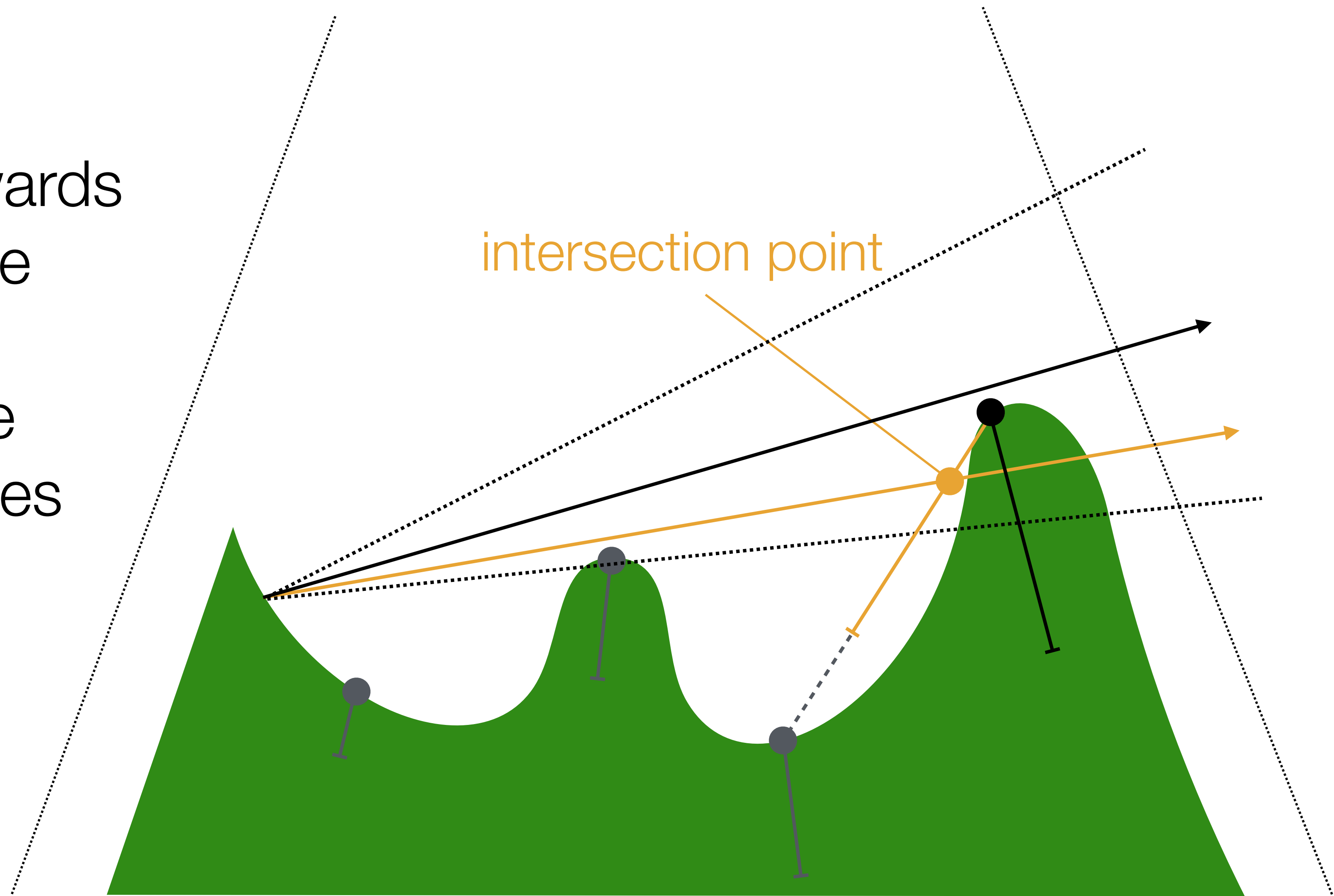
First, we pick the sample that covered most of the cone



Screen-Space Reflections

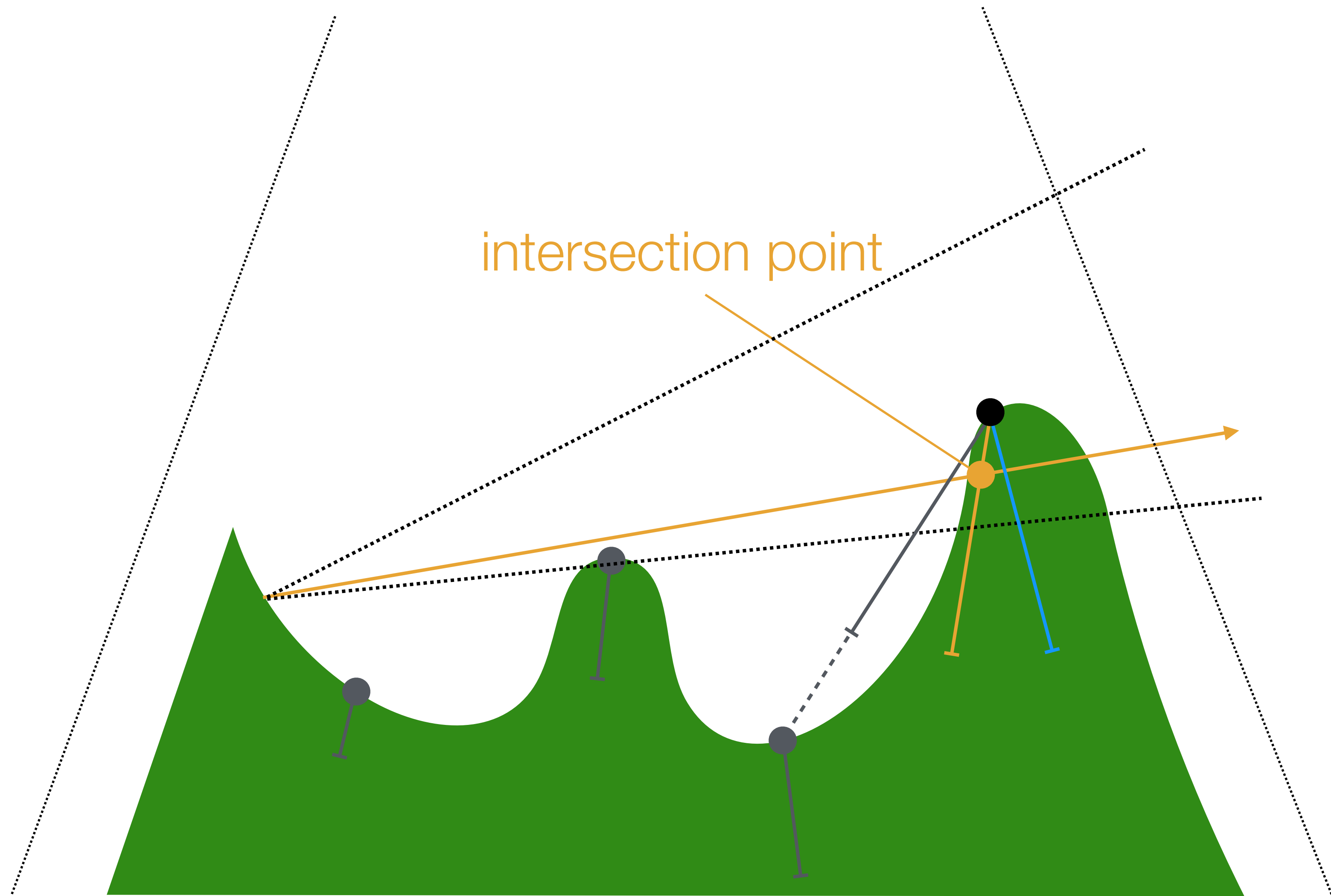
Aim the reflection ray towards the center of the coverage

And intersect with the line between the last 2 samples



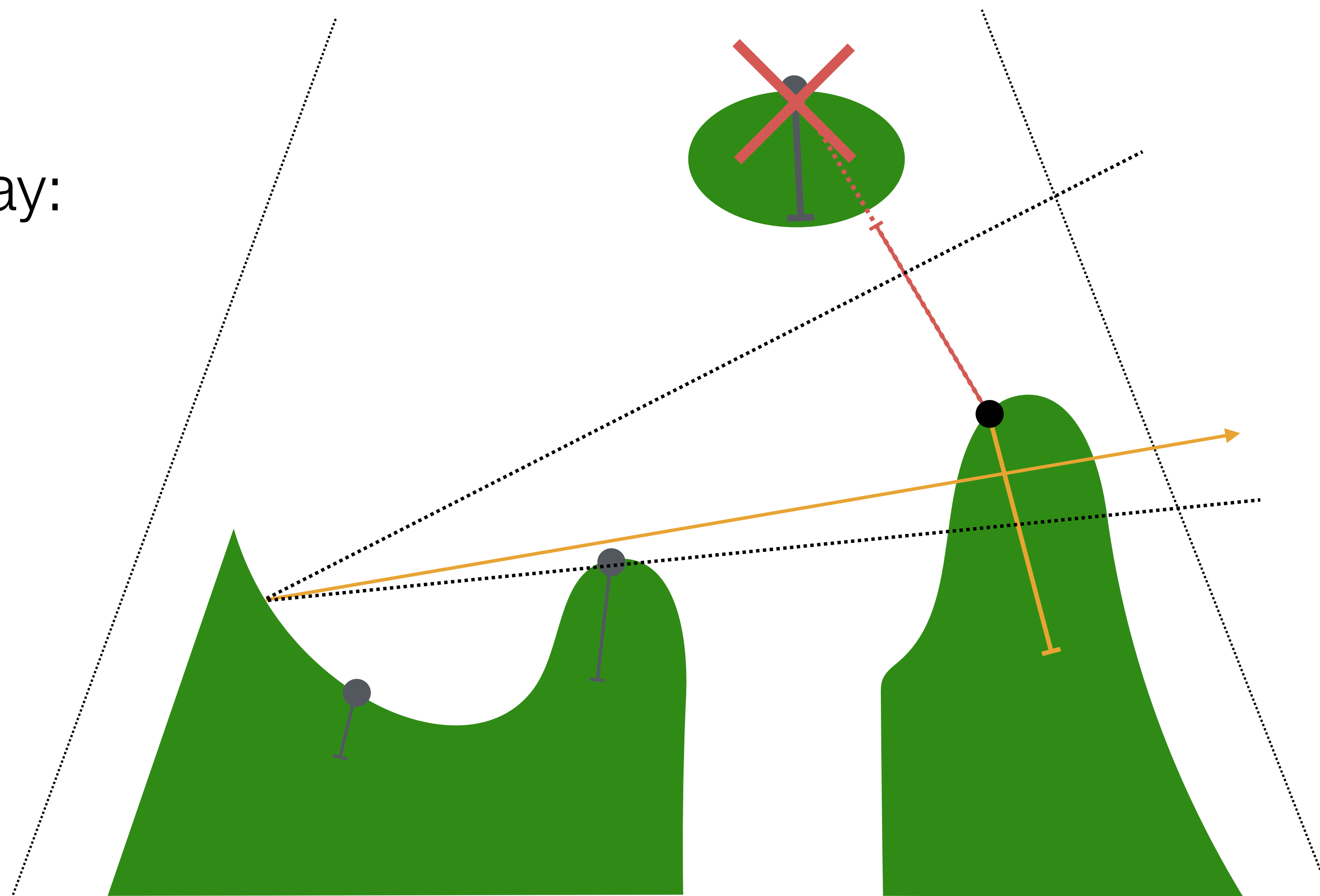
Screen-Space Reflections

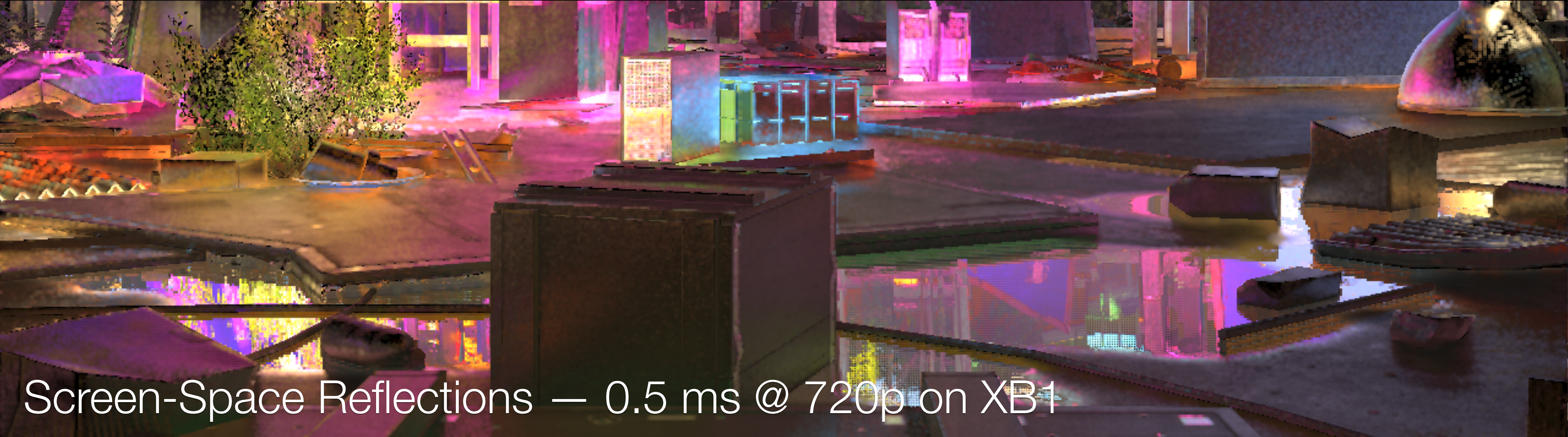
Low sample density:
interpolate towards
camera direction (in blue)



Screen-Space Reflections

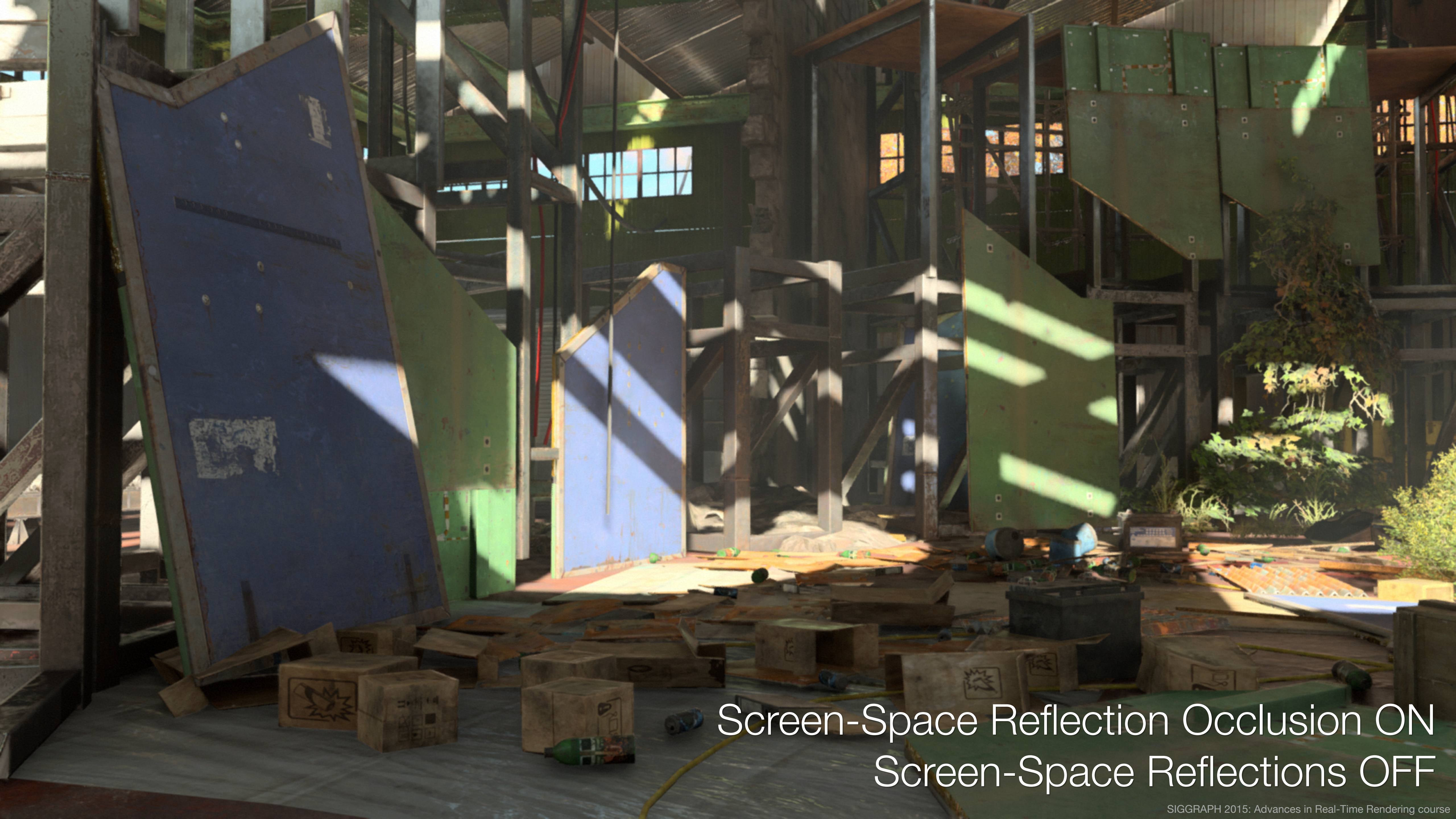
Previous sample above ray:
don't interpolate



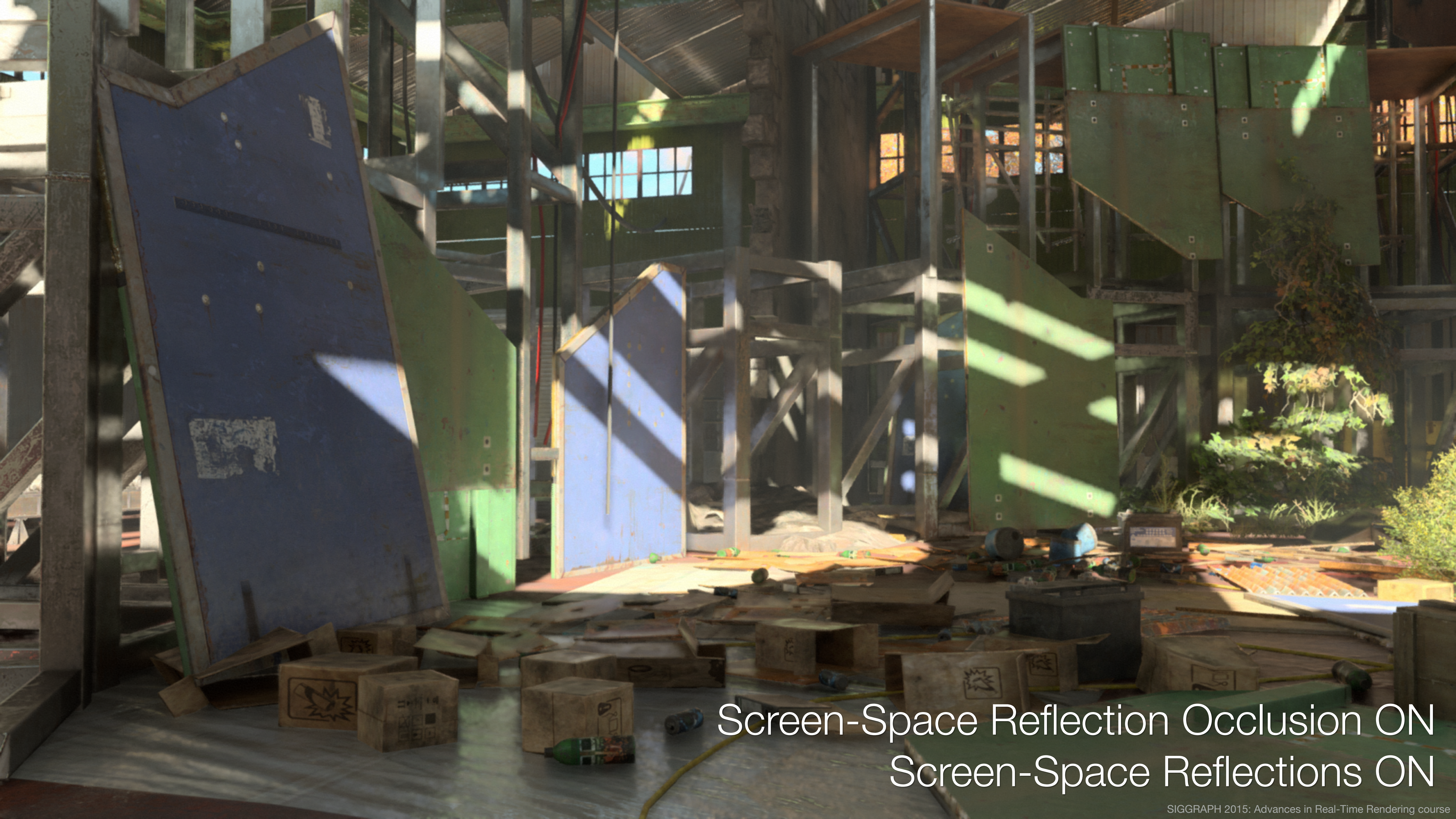




Screen-Space Reflection Occlusion OFF
Screen-Space Reflections OFF



Screen-Space Reflection Occlusion ON
Screen-Space Reflections OFF



Screen-Space Reflection Occlusion ON
Screen-Space Reflections ON



smooth

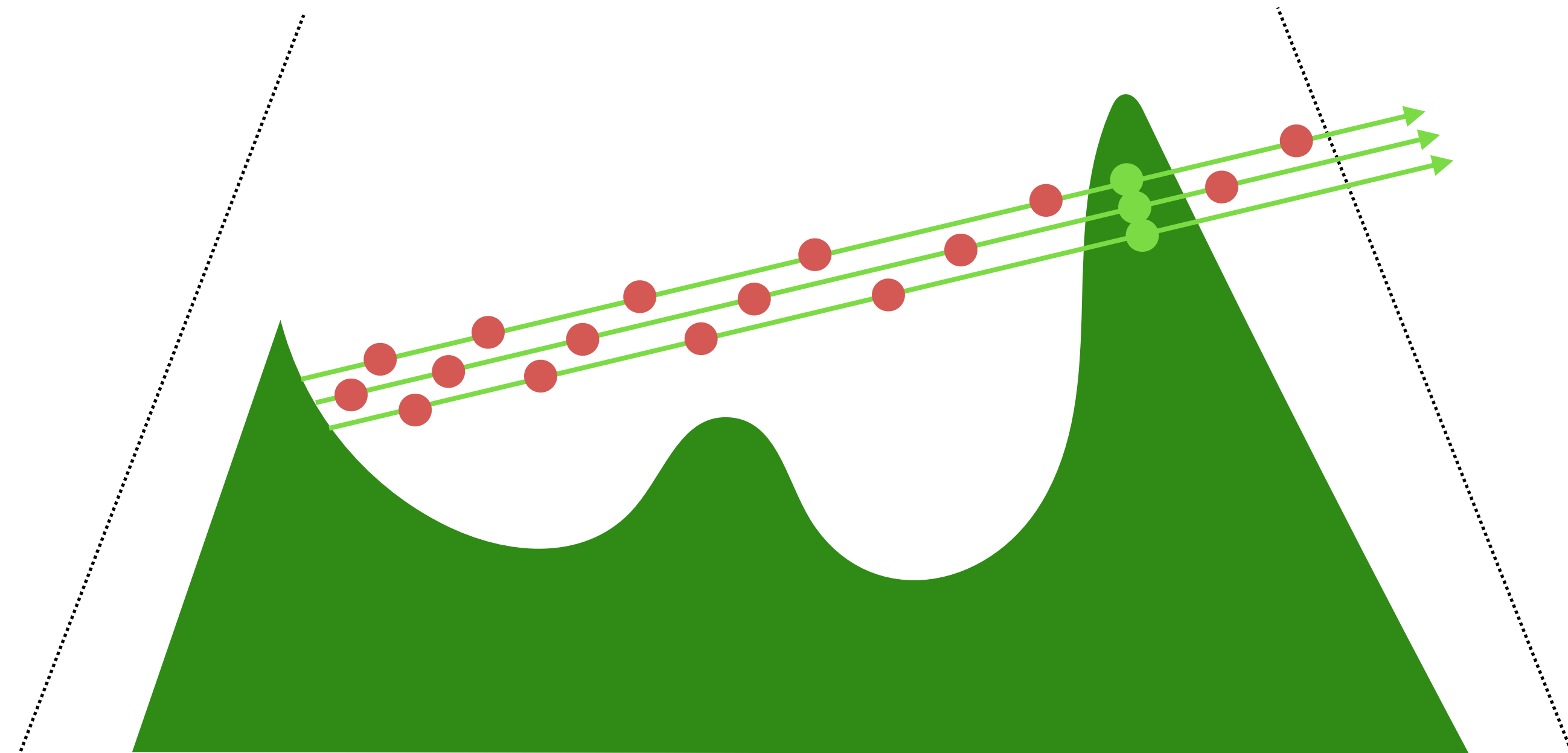
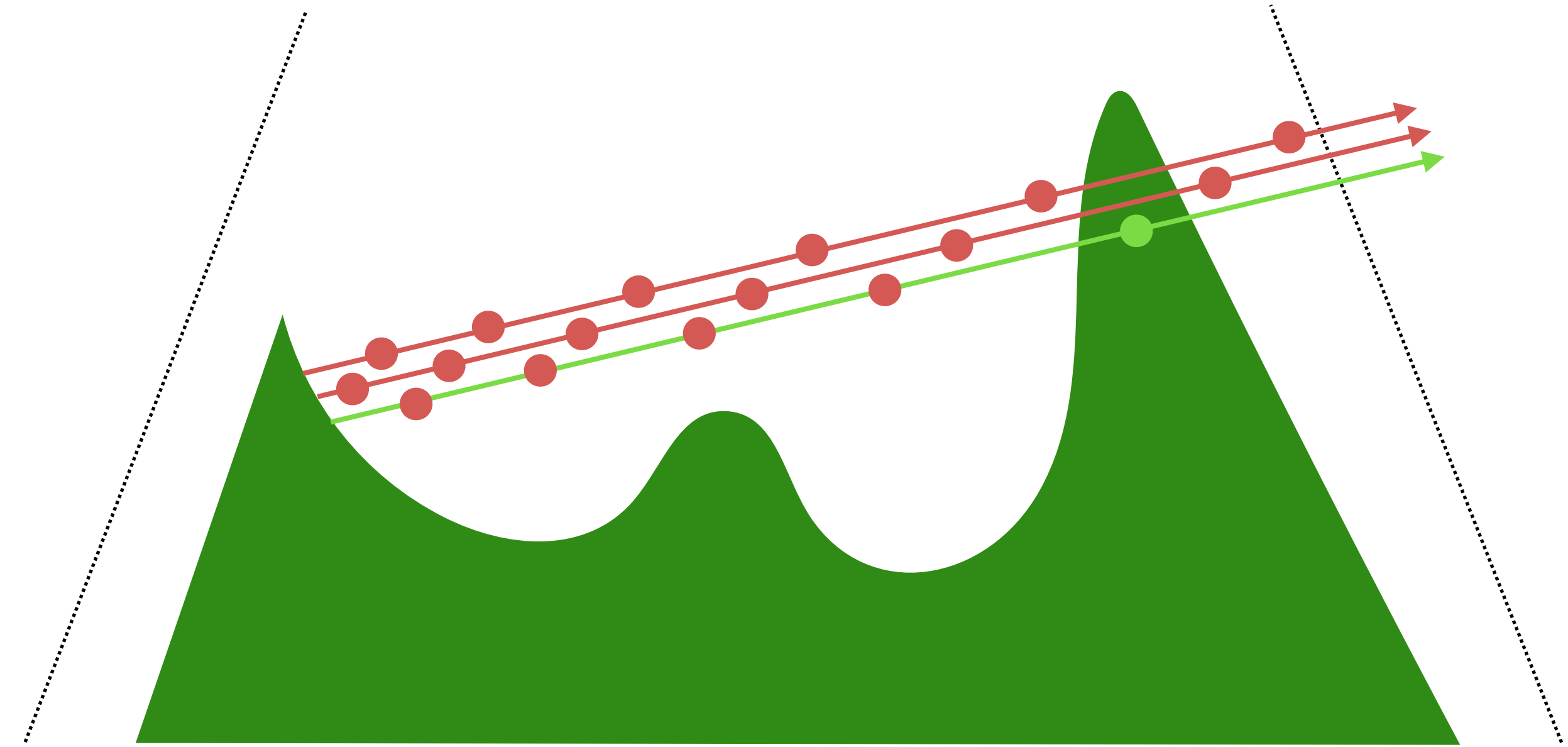


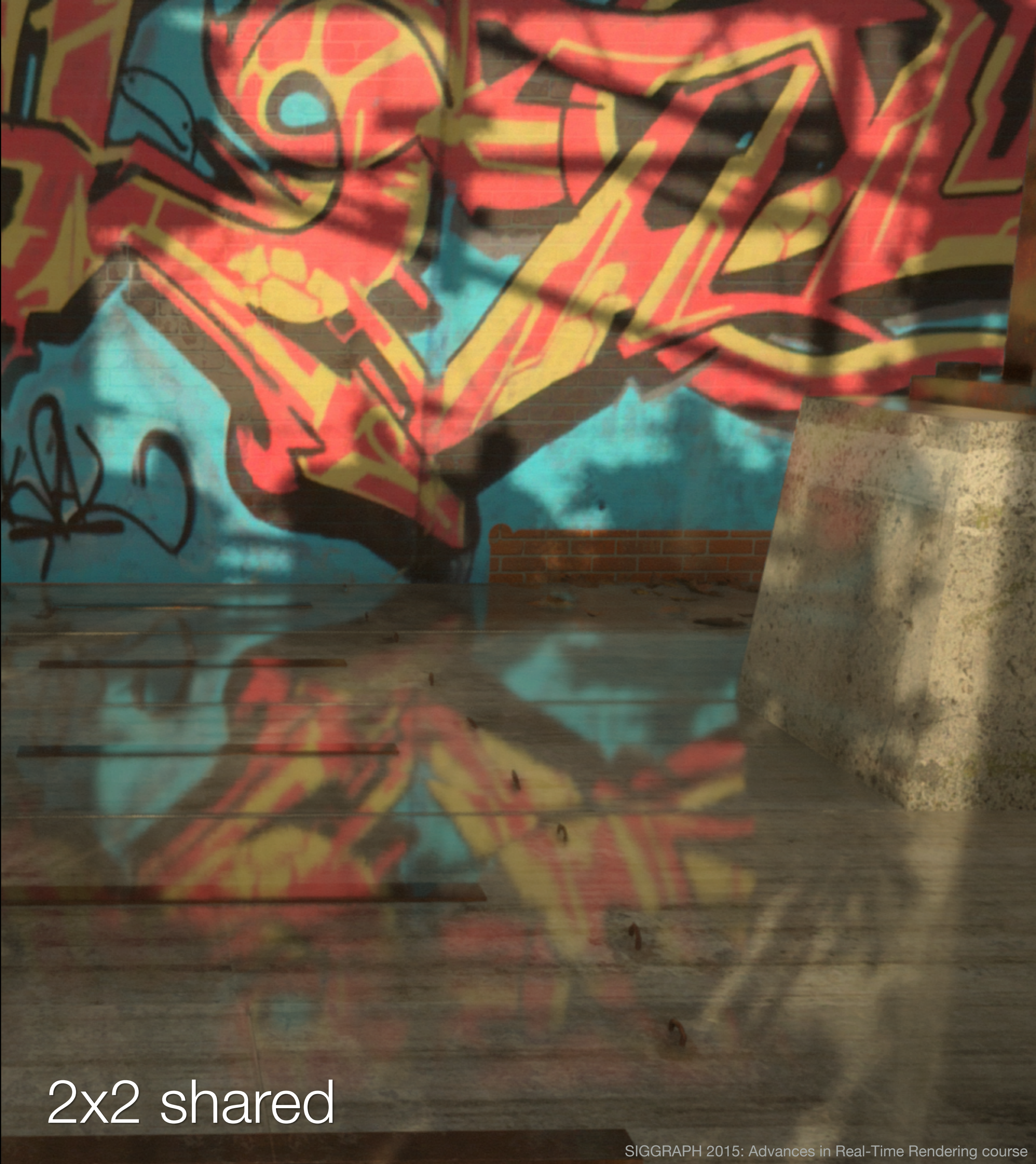
rough

Refining the intersections

If neighboring rays have the same direction

- Interleave search
- Take nearest hit distance







Thank You!

Acknowledgments

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Jaakko Lehtinen



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